

Paper: Optimal Kronecker-Sum Approximation of Real Time Recurrent Learning

Poster: Online & Untruncated Gradients for RNNs

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Recurrent Neural Nets (RNNs)

- Model temporal and sequential data (RL, audio synthesis, language modelling,...)
- One of the key research challenges: Learn Long-Term dependencies

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Training RNNs

Truncated Backprop Trough Time (TBPTT)

(Williams & Peng, 1990)



- Introduces arbitrary **Truncation Horizon** → no longer term dependencies
- **Parameter Update Lock** during forward & backward pass

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Forward Computing Gradients Real Time Recurrent Learning (RTRL)

(Williams & Zipser, 1989)

Forward compute $G_t =$

$$\frac{dh_t}{d\Theta}$$
 with recurrence

$$G_{t+1} = H_t G_t + F_t$$

It looks like you want to do RTRL. $\mathbf{G_t} = \frac{\mathbf{dh_t}}{\mathbf{d\Theta}} \in \mathbb{R}^{\mathbf{n} \times \mathbf{n}^2}$ $G_{t+1} = H_t G_t + F_t$

- Untruncated Gradients
- Memory is independent of sequence length
- Online parameter updates (no update lock)

BUT: Need n^4 Runtime and n^3 Memory (for *n* hidden units) \rightarrow infeasible

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Approximate RTRL to save time & space

Online Recurrent Optimization (UORO) (Tallec & Ollivier, 2017)

• Idea: Don't store G_t precisely, but approximately $G_t \approx u_t \otimes w_t$

and unbiasedly approximate recurrence equation.

- Memory: n^2
- > Runtime: n^3



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Does it work? Part I

UORO (Tallec & Ollivier, 2017) and KF-RTRL (Mujika et al., 2018)



Character-level PTB

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Does it work? Part II

Provably optimal approximation – Optimal Kronecker-Sum (OK)

(our contribution)



What to remember

- Truncated BPTT has problems (truncation, update lock)
- RTRL as online & untruncated alternative, but too costly
- Our OK approx of RTRL reduces costs by factor n
 - No performance loss
 - Break update lock \rightarrow faster convergence
 - Theoretically optimal (for certain class of approx)
- Still need to reduce computational costs

	Memory	Runtime	Unbiased&Online
RTRL	n ³	n ⁴	\checkmark
<i>r</i> -0K	rn ²	rn ³	\checkmark
TBPTT- <i>T</i>	Tn	Tn ²	×

It looks like you got interested in RTRL. Have a look at **Poster #166.**

