

On efficient optimal transport: an analysis of greedy and accelerated mirror descent algorithms

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Optimal transport (OT)

OT formulation:

$$\min \langle C, X \rangle \quad X\mathbf{1} = r, \quad X^T\mathbf{1} = l, \quad X \geq 0.$$

- $X \in \mathbb{R}_+^{n \times n}$: *transportation plan*
- $C \in \mathbb{R}_+^{n \times n}$: cost matrix comprised of nonnegative elements
- r and l : fixed vectors in the probability simplex Δ^n .

Entropic regularized OT

Entropic regularized OT:

$$\min_{X \in \mathbb{R}^{n \times n}} \langle C, X \rangle - \eta H(X) \quad X\mathbf{1} = r, X^T\mathbf{1} = l.$$

- $\eta > 0$: regularization parameter
- $H(X)$: entropic regularization, given by

$$H(X) := - \sum_{i,j=1}^n X_{ij} \log(X_{ij}).$$

Main goal

Goal

Find ε -approximation transportation plan $\hat{X} \in \mathbb{R}_+^{n \times n}$ such that:

- $\hat{X}\mathbf{1} = r$ and $\hat{X}^\top \mathbf{1} = l$
- $\langle C, \hat{X} \rangle \leq \langle C, X^* \rangle + \varepsilon$ where X^* : optimal transportation plan.

Dual entropic regularized OT

Simple form:

$$\max_{u, v \in \mathbb{R}^n} - \sum_{i, j=1}^n e^{-\frac{c_{ij}}{\eta} + u_i + v_j} + \langle u, r \rangle + \langle v, l \rangle.$$

Matrix form:

$$\min_{u, v \in \mathbb{R}^n} f(u, v) := \mathbf{1}^\top B(u, v) \mathbf{1} - \langle u, r \rangle - \langle v, l \rangle.$$

where $B(u, v) := (e^u) e^{-\frac{c}{\eta}} (e^v)$.

- Popular algorithm for solving regularized OT is Sinkhorn algorithm

Greenhorn algorithm

- $\rho(a, b) := b - a + a \log\left(\frac{a}{b}\right)$.

Algorithm 1 GREENKHORN($C, \eta, r, l, \varepsilon'$)

Input: $k = 0$ and $u^0 = v^0 = 0$.

while $E^k > \varepsilon'$ **do**

$$r(u^k, v^k) = B(u^k, v^k)\mathbf{1}.$$

$$l(u^k, v^k) = B(u^k, v^k)^\top \mathbf{1}.$$

$$I = \operatorname{argmax}_{1 \leq i \leq n} \rho(r_i, r_i(u^k, v^k)).$$

$$J = \operatorname{argmax}_{1 \leq j \leq n} \rho(l_j, l_j(u^k, v^k)).$$

if $\rho(r_i, r_i(u^k, v^k)) > \rho(l_j, l_j(u^k, v^k))$ **then**

$$u_I^{k+1} = u_I^k + \log(r_I) - \log(r_I(u^k, v^k)).$$

else

$$v_J^{k+1} = v_J^k + \log(l_J) - \log(l_J(u^k, v^k)).$$

end if

$$k = k + 1.$$

end while

Output: $B(u^k, v^k)$.

Greenhorn algorithm (Cont.)

Algorithm 2 Approximating OT by GREENKHORN

Input: $\eta = \frac{\varepsilon}{4 \log(n)}$ and $\varepsilon' = \frac{\varepsilon}{8 \|C\|_\infty}$.

Step 1: Let $\tilde{r} \in \Delta_n$ and $\tilde{l} \in \Delta_n$ be defined as

$$(\tilde{r}, \tilde{l}) = \left(1 - \frac{\varepsilon'}{8}\right) (r, l) + \frac{\varepsilon'}{8n} (\mathbf{1}, \mathbf{1}).$$

Step 2: Compute

$$\tilde{X} = \text{GREENKHORN} \left(C, \eta, \tilde{r}, \tilde{l}, \varepsilon'/2 \right).$$

Step 3: Round \tilde{X} to \hat{X} by Algorithm 2 (Altschuler et al. 2017) such that $\hat{X} \mathbf{1} = r$ and $\hat{X}^\top \mathbf{1} = l$.

Output: \hat{X} .

Numerical experiments

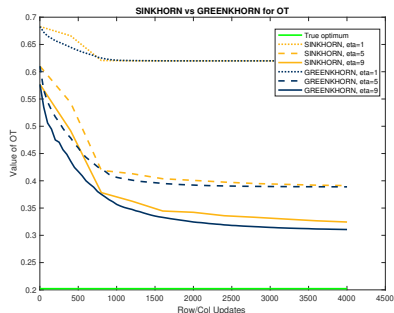
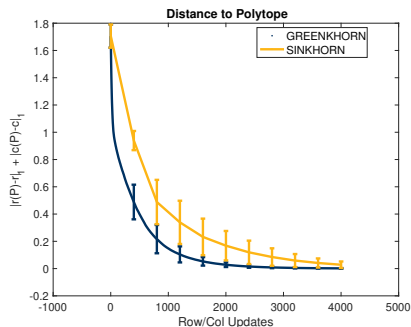


Figure: Comparison of Greenkhorn and Sinkhorn. Left panel: Distance to transportation polytope; Right panel: Different regularization parameter $\eta \in \{1, 5, 9\}$.

- Best known complexity of Sinkhorn is $\mathcal{O}(n^2/\varepsilon^2)$
- Best known complexity of Greenkhorn is $\mathcal{O}(n^2/\varepsilon^3)$ (Altschuler et. al. [2017])

Complexity analysis

- $E^k := \|B(u^k, v^k)\mathbf{1} - r\|_1 + \|B(u^k, v^k)^\top \mathbf{1} - l\|_1.$

Theorem 1

The Greenhorn algorithm returns $B(u^k, v^k)$ satisfying $E_k \leq \varepsilon'$ as long as $k \leq 2 + \frac{112nR}{\varepsilon'}$ where $R := \frac{\|C\|_\infty}{\eta} + \log(n) - 2 \log(\min_{1 \leq i, j \leq n} \{r_i, l_j\})$.

Theorem 2

The Greenhorn algorithm for approximating OT returns ε -approximation transportation plan $\hat{X} \in \mathbb{R}^{n \times n}$ in




$$\mathcal{O}\left(\frac{n^2 \|C\|_\infty^2 \log(n)}{\varepsilon^2}\right)$$

arithmetic operations.

Future directions

- Is the complexity bound $\mathcal{O}(n^2/\varepsilon^2)$ of Greenhorn algorithm tight?
- How to accelerate Sinkhorn and Greenhorn algorithms for OT?

References

-  T. Lin*, N. Ho*, M. I. Jordan. On efficient optimal transport: an analysis of greedy and accelerated mirror descent algorithms. *ICML, 2019*.
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-  J. Altschuler, J. Weed, P. Rigollet. Near-linear time approximation algorithms for optimal transport via Sinkhorn iteration. *NIPS, 2017*.