

# Probability Functional Descent:

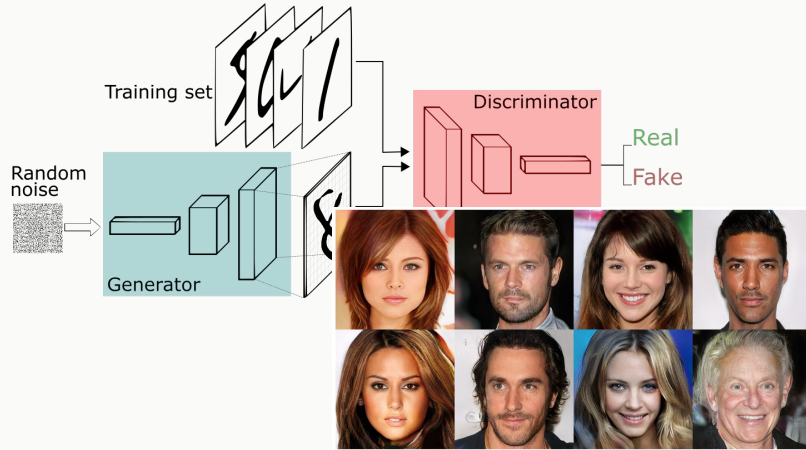
A Unifying Perspective on GANs, VI, and RL

Casey Chu <[caseychu@stanford.edu](mailto:caseychu@stanford.edu)> Jose Blanchet Peter Glynn

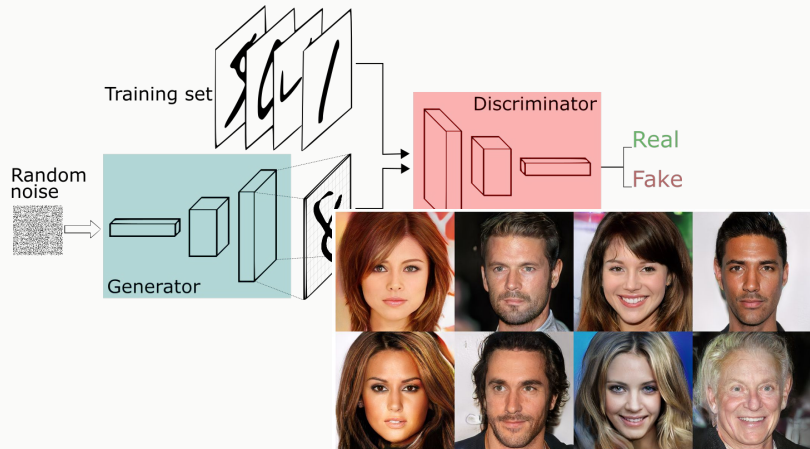




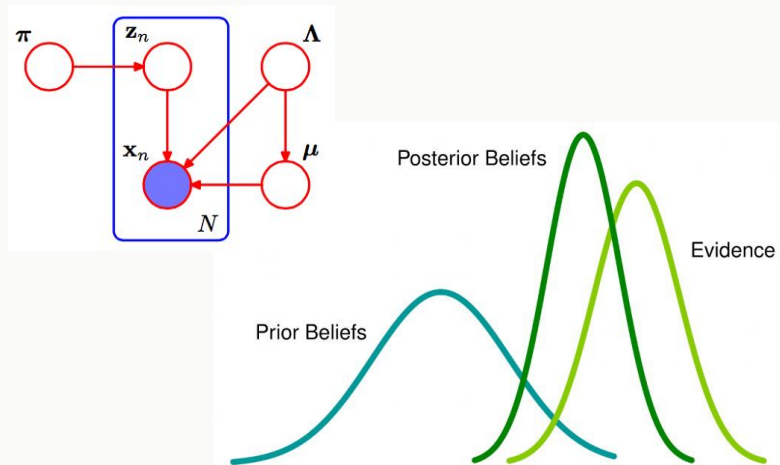
# Deep generative models



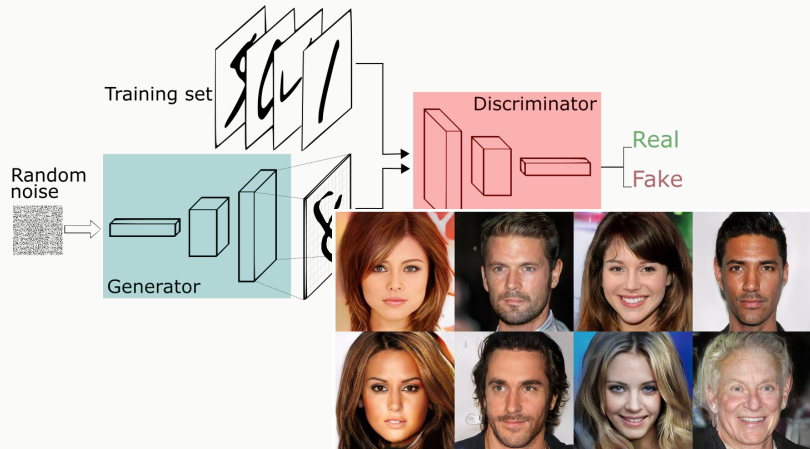
# Deep generative models



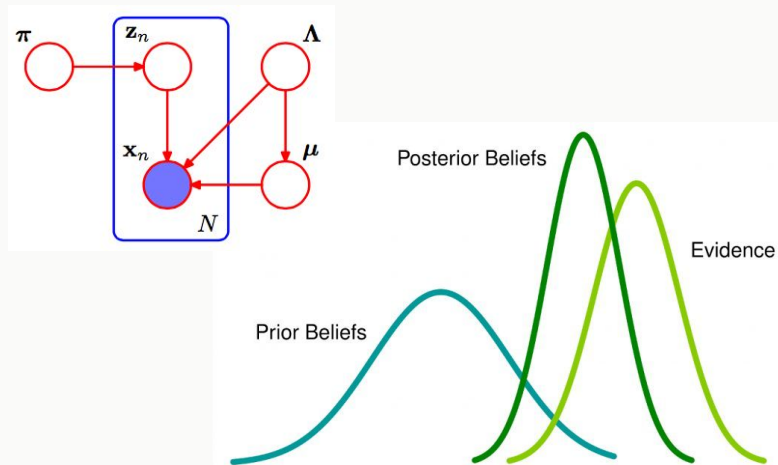
# Variational inference



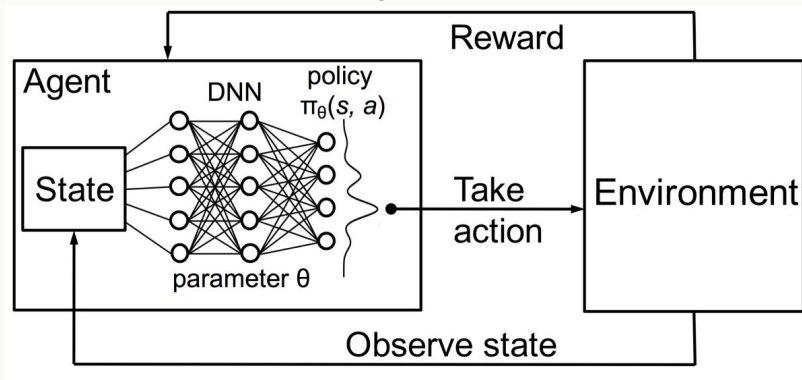
# Deep generative models



# Variational inference



# Deep reinforcement learning



Probability functional

$$J : \mathbf{P}(X) \rightarrow \mathbb{R}$$

Probability functional

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"gradient"  $\nabla J$

Probability functional

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"gradient"  $\nabla J$

von Mises influence function

$$\Psi : X \rightarrow \mathbb{R}$$



## Gradient descent on $f: \mathbb{R}^n \rightarrow \mathbb{R}$

0. Initialize  $x \in \mathbb{R}^n$  arbitrarily
1. Compute the gradient  $g = \nabla f(x)$
2. Choose  $x'$  such that  $x' \cdot g < x \cdot g$  (usually, we set  $x' = x - \alpha g$ )

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## Probability functional descent on $J: \mathbf{P}(X) \rightarrow \mathbb{R}$

0. Initialize a distribution  $\mu \in \mathbf{P}(X)$  arbitrarily
1. Compute the **influence function**  $\Psi$  of  $J$  at  $\mu$
2. Choose  $\mu'$  such that  $\mathbb{E}_{x \sim \mu'}[\Psi(x)] < \mathbb{E}_{x \sim \mu}[\Psi(x)]$

# Generative modeling

$$J_G(\mu) = D(\mu \parallel \nu_0)$$

where  $D$  is e.g. Jensen–Shannon, Wasserstein

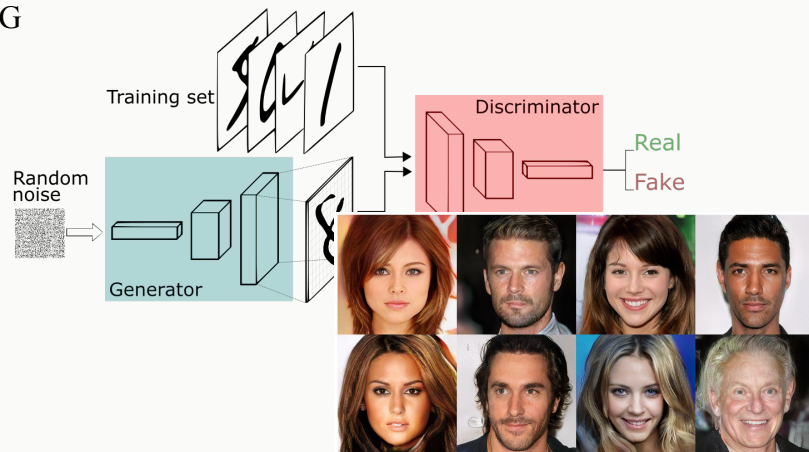
1. Optimize the **discriminator**, which approximates the influence function of  $J_G$
2. Update the **generator**  $\mu$

PFD recovers:

- Minimax GAN
- Non-saturating GAN
- Wasserstein GAN

## Probability functional descent

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2. Choose  $\mu'$  such that  $\mathbb{E}_{x \sim \mu'}[\Psi(x)] < \mathbb{E}_{x \sim \mu}[\Psi(x)]$



# Variational inference

$$J_{\text{VI}}(q) = \text{KL}(q(\theta) \parallel p(\theta|x))$$

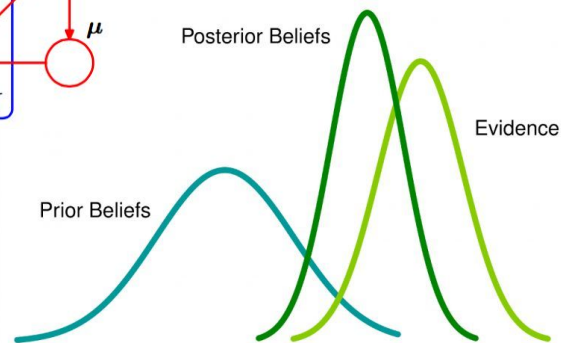
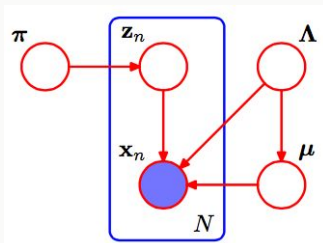
1. Compute the **ELBO**,  $\log(q(\theta)/p(x,\theta))$ , the influence function for  $J_{\text{VI}}$
2. Update the **approximate posterior**  $q$

PFD recovers:

- Black-box variational inference
- Adversarial variational Bayes
- Approximate posterior distillation

## Probability functional descent

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2. Choose  $\mu'$  such that  $\mathbb{E}_{x \sim \mu'}[\Psi(x)] < \mathbb{E}_{x \sim \mu}[\Psi(x)]$



# Reinforcement learning

$$J_{\text{RL}}(\pi) = \mathbb{E}_{\pi}[\sum_t \gamma^t R_t]$$

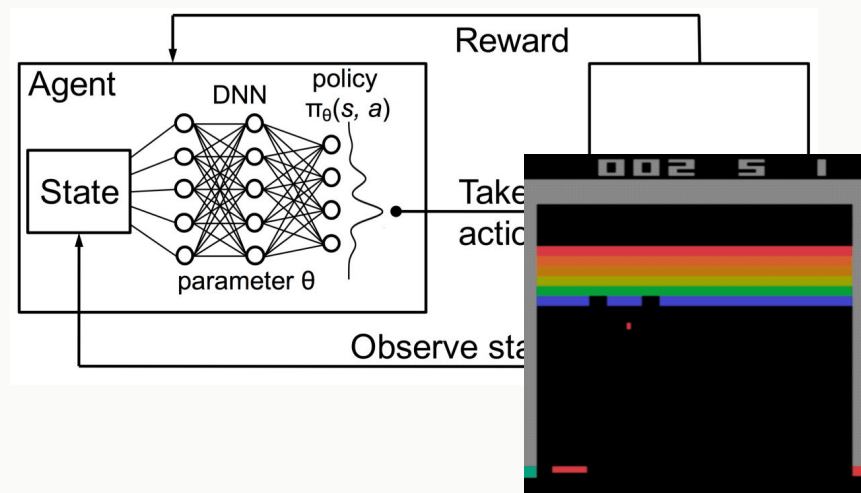
1. Approximate the **advantage**  $Q^{\pi}(s,a) - V^{\pi}(s)$ , the influence function for  $J_{\text{RL}}$
2. Update the **policy**  $\pi$

PFD recovers:

- Policy gradient
- Actor-critic
- Dual actor critic

## Probability functional descent

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2. Choose  $\mu'$  such that  $\mathbb{E}_{x \sim \mu'}[\Psi(x)] < \mathbb{E}_{x \sim \mu}[\Psi(x)]$



**Probability functional descent** is a unifying perspective that enables the easy development of new algorithms.

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<https://www.freecodecamp.org/news/an-intuitive-introduction-to-generative-adversarial-networks-gans-7a2264a81394/>

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