

# Variational Laplace Autoencoders

Yookoon Park, Chris Dongjoo Kim and Gunhee Kim

Vision and Learning Lab

Seoul National University, South Korea

# Introduction

- Variational Autoencoders
- Two Challenges of Amortized Variational Inference
- Contributions

# Variational Autoencoders (VAEs)

- Generative network  $\theta$

$$p_{\theta}(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{g}_{\theta}(\mathbf{z}), \sigma^2\mathbf{I}), p(\mathbf{z}) = \mathcal{N}(\mathbf{0}, \mathbf{I})$$

- Inference network  $\phi$ : **amortized inference** of  $p_{\theta}(\mathbf{z}|\mathbf{x})$

$$q_{\phi}(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\boldsymbol{\mu}_{\phi}(\mathbf{x}), \text{diag}(\boldsymbol{\sigma}_{\phi}^2(\mathbf{x})))$$

- Networks jointly trained by maximizing the *Evidence Lower Bound (ELBO)*

$$\begin{aligned} \mathcal{L}(\mathbf{x}) &= \mathbb{E}_q[\log p_{\theta}(\mathbf{x}, \mathbf{z}) - \log q_{\phi}(\mathbf{z}|\mathbf{x})] = \log p_{\theta}(\mathbf{x}) - D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \parallel p_{\theta}(\mathbf{z}|\mathbf{x})) \\ &\leq \log p_{\theta}(\mathbf{x}) \end{aligned}$$

# Two Challenges of Amortized Variational Inference

1. Enhancing the **expressiveness** of  $q_\phi(\mathbf{z}|\mathbf{x})$ 
  - The full-factorized assumption is restrictive to capture complex posteriors
  - E.g. normalizing flows (Rezende & Mohamed, 2015; Kingma et al., 2016)
2. Reducing the **amortization error** of  $q_\phi(\mathbf{z}|\mathbf{x})$ 
  - The error due to the inaccuracy of the inference network
  - E.g. gradient-based refinements of  $q_\phi(\mathbf{z}|\mathbf{x})$  (Kim et al, 2018; Marino et al., 2018; Krishnan et al. 2018)

Rezende, D. J. and Mohamed, S. Variational inference with normalizing flows. In *ICML*, 2015.

Kingma, D. P., Salimans, T., Jozefowicz, R., Chen, X., Sutskever, I., and Welling, M. Improved variational inference with inverse autoregressive flow. In *NeurIPS*, 2016.

Kim, Y., Wiseman, S., Millter, A. C., Sontag, D., and Rush, A. M. Semi-amortized variational autoencoders. In *ICML*, 2018.

Marino, J., Yisong, Y., and Mandt, S. Iterative amortized inference. In *ICML*, 2018.

Krishnan, R. G., Liang, D., and Hoffman, M. D. On the challenges of learning with inference networks on sparse high-dimensional data. In *AISTAT*, 2018.

# Contributions

- The *Laplace approximation* of the posterior to improve the training of latent deep generative models with:
  1. Enhanced **expressiveness** of full-covariance Gaussian posterior
  2. Reduced **amortization error** due to direct covariance computation from the generative network behavior
- A novel posterior inference exploiting local linearity of ReLU networks

# Approach

- Posterior Inference using Local Linear Approximations
- Generalization: Variational Laplace Autoencoders

# Observation 1: Probabilistic PCA

- A linear Gaussian model  
(Tipping & Bishop, 1999)

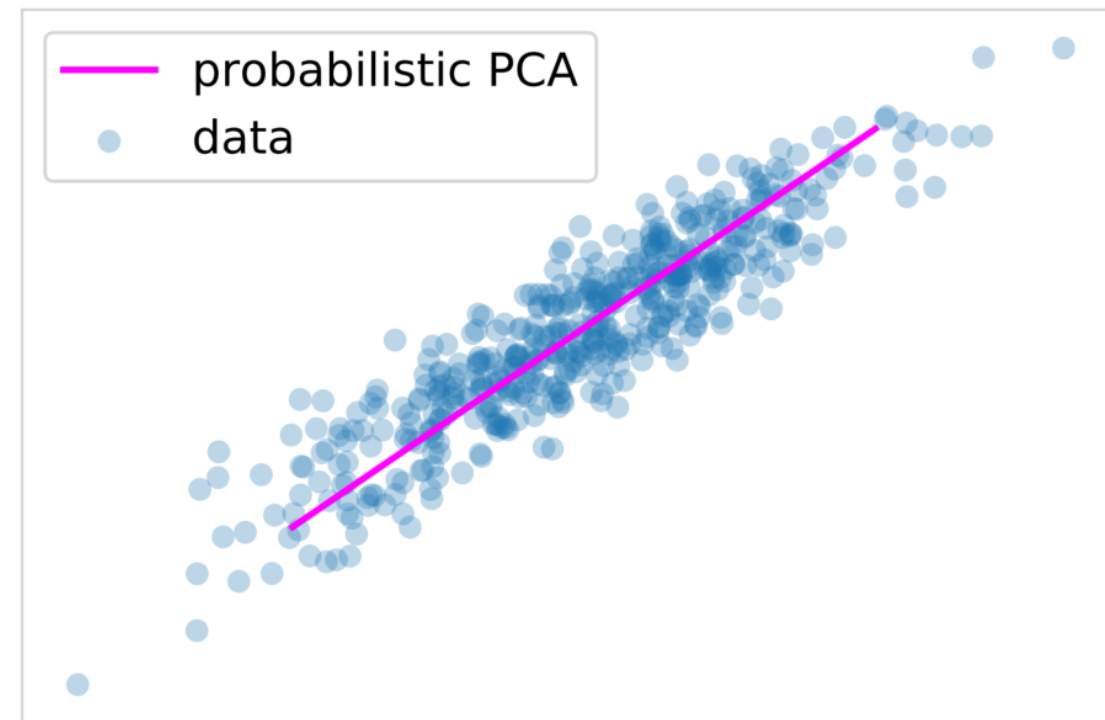
$$p(\mathbf{z}) = \mathcal{N}(\mathbf{0}, \mathbf{I})$$

$$p_{\theta}(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{W}\mathbf{z} + \mathbf{b}, \sigma^2\mathbf{I})$$

- The posterior distribution is **exactly**

$$p_{\theta}(\mathbf{z}|\mathbf{x}) = \mathcal{N}\left(\frac{1}{\sigma^2}\boldsymbol{\Sigma}\mathbf{W}^{\mathbf{T}}(\mathbf{x} - \mathbf{b}), \boldsymbol{\Sigma}\right)$$

$$\text{where } \boldsymbol{\Sigma} = \left(\frac{1}{\sigma^2}\mathbf{W}^{\mathbf{T}}\mathbf{W} + \mathbf{I}\right)^{-1}$$



Toy example. 1-dim pPCA on 2-dim data

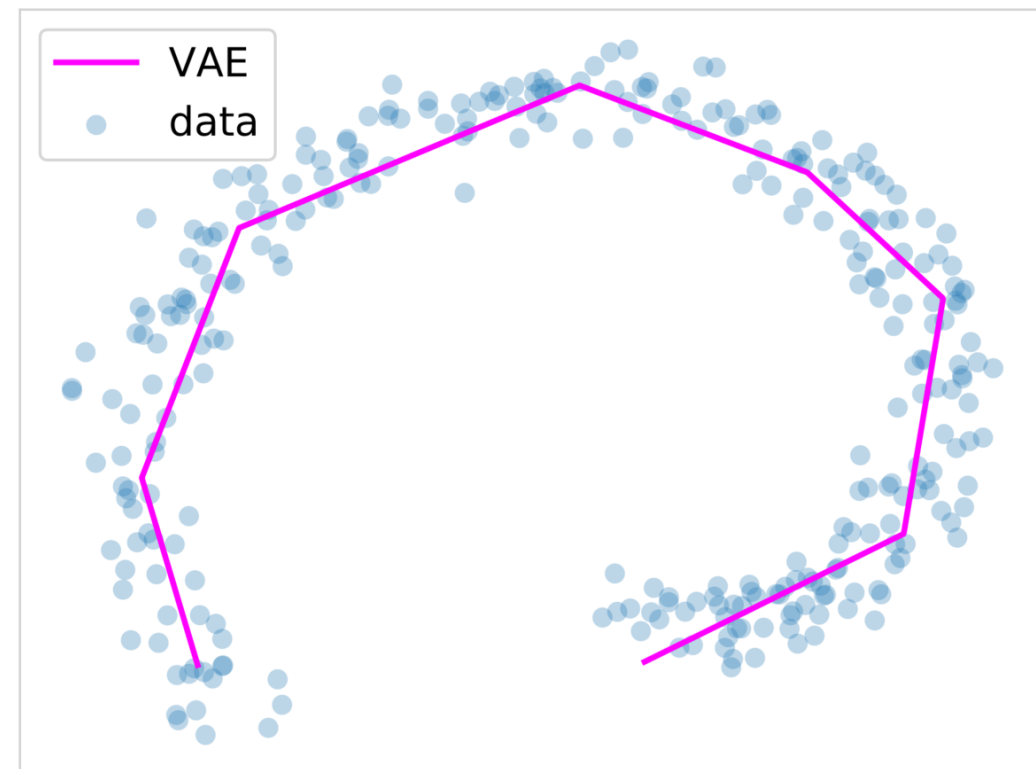
# Observation 2: Piece-wise Linear ReLU Networks

- ReLU networks are *piece-wise linear*  
(Pascanu et al., 2014; Montufar et al., 2014)

$$g_{\theta}(\mathbf{z}) \approx \mathbf{W}_z \mathbf{z} + \mathbf{b}_z$$

- Locally equivalent to *probabilistic PCA*

$$p_{\theta}(\mathbf{x}|\mathbf{z}) \approx \mathcal{N}(\mathbf{W}_z \mathbf{z} + \mathbf{b}_z, \sigma^2 \mathbf{I})$$



Toy example. 1-dim ReLU VAE on 2-dim data



# Posterior Inference using Local Linear Approximations

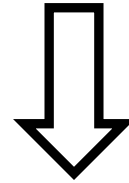
***Linear models give exact  
posterior distribution***

*Observation 1*

+

***ReLU networks are  
locally linear***

*Observation 2*



***Posterior approximation  
based on the local linearity***

# Posterior Inference using Local Linear Approximations

1. Iteratively find the **posterior mode**  $\boldsymbol{\mu}$  where the density is concentrated

- Solve under the linear assumption  $\mathbf{g}_\theta(\boldsymbol{\mu}_t) \approx \mathbf{W}_t \boldsymbol{\mu}_t + \mathbf{b}_t$

$$\boldsymbol{\mu}_{t+1} = \frac{1}{\sigma^2} \left( \frac{1}{\sigma^2} \mathbf{W}_t^T \mathbf{W}_t + \mathbf{I} \right)^{-1} \mathbf{W}_t^T (\mathbf{x} - \mathbf{b})$$

- Repeat for T steps

2. Posterior approximation using  $p_\theta(\mathbf{x}|\mathbf{z}) \approx \mathcal{N}(\mathbf{W}_\mu \mathbf{z} + \mathbf{b}_\mu, \sigma^2 \mathbf{I})$

$$q(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma}), \text{ where } \boldsymbol{\Sigma} = \left( \frac{1}{\sigma^2} \mathbf{W}_\mu^T \mathbf{W}_\mu + \mathbf{I} \right)^{-1}$$

# Generalization: Variational Laplace Autoencoders

1. Find the posterior mode s.t.  $\nabla_{\mathbf{z}} \log p(\mathbf{x}, \mathbf{z})|_{\mathbf{z}=\boldsymbol{\mu}} = 0$

- Initialize  $\boldsymbol{\mu}_0$  using the inference network
- Iteratively refine  $\boldsymbol{\mu}_t$  (e.g. use gradient-descent)

2. The **Laplace approximation** defines the posterior as:

$$q(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma}), \text{ where } \boldsymbol{\Sigma}^{-1} = \boldsymbol{\Lambda} = -\nabla_{\mathbf{z}}^2 \log p(\mathbf{x}, \mathbf{z})|_{\mathbf{z}=\boldsymbol{\mu}}$$

3. Evaluate the ELBO using  $q(\mathbf{z}|\mathbf{x})$  and train the model

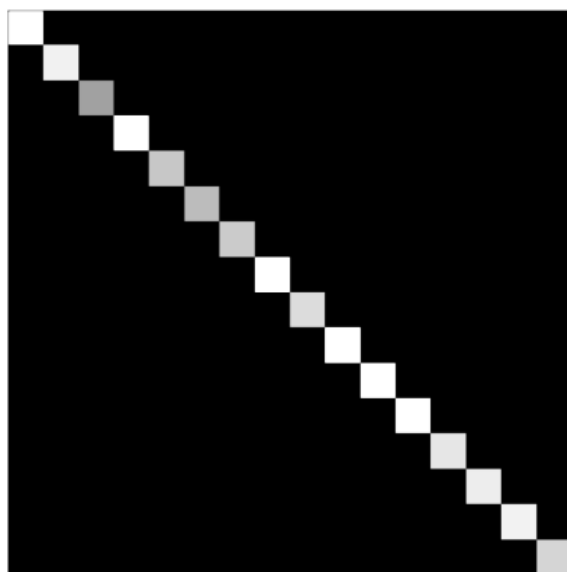
# Results

- Posterior Covariance
- Log-likelihood Results

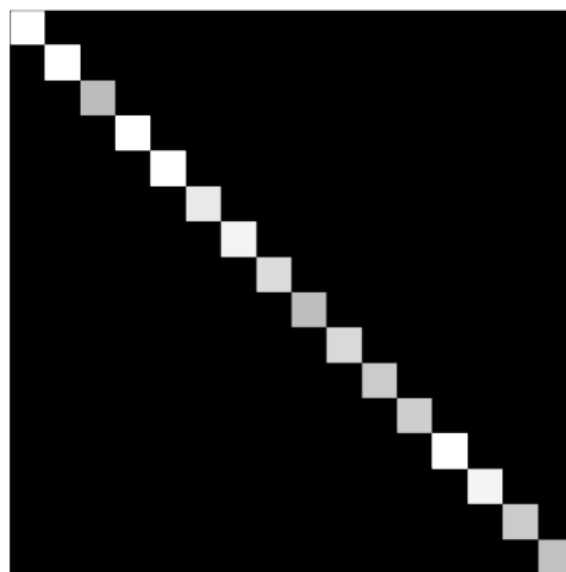
# Experiments

- Image datasets: MNIST, OMNIGLOT, Fashion MNIST, SVHN, CIFAR10
- Baselines
  - VAE
  - Semi-Amortized (SA) VAE (Kim et al, 2018)
  - VAE + Householder Flows (HF) (Tomczak & Welling, 2016)
  - Variational Laplace Autoencoder (VLAE)
- $T=1, 2, 4, 8$  (number of iterative updates or flows)

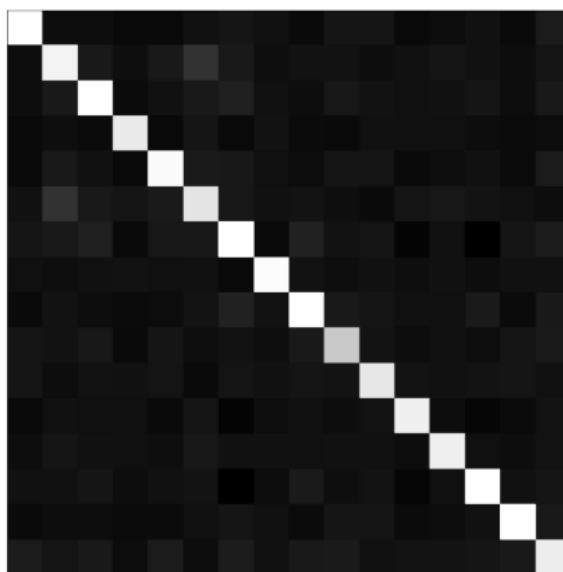
# Posterior Covariance Matrices



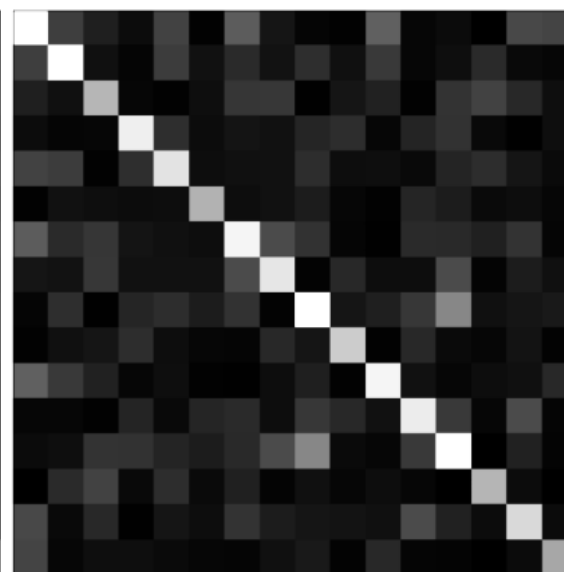
(a) VAE



(b) SA-VAE

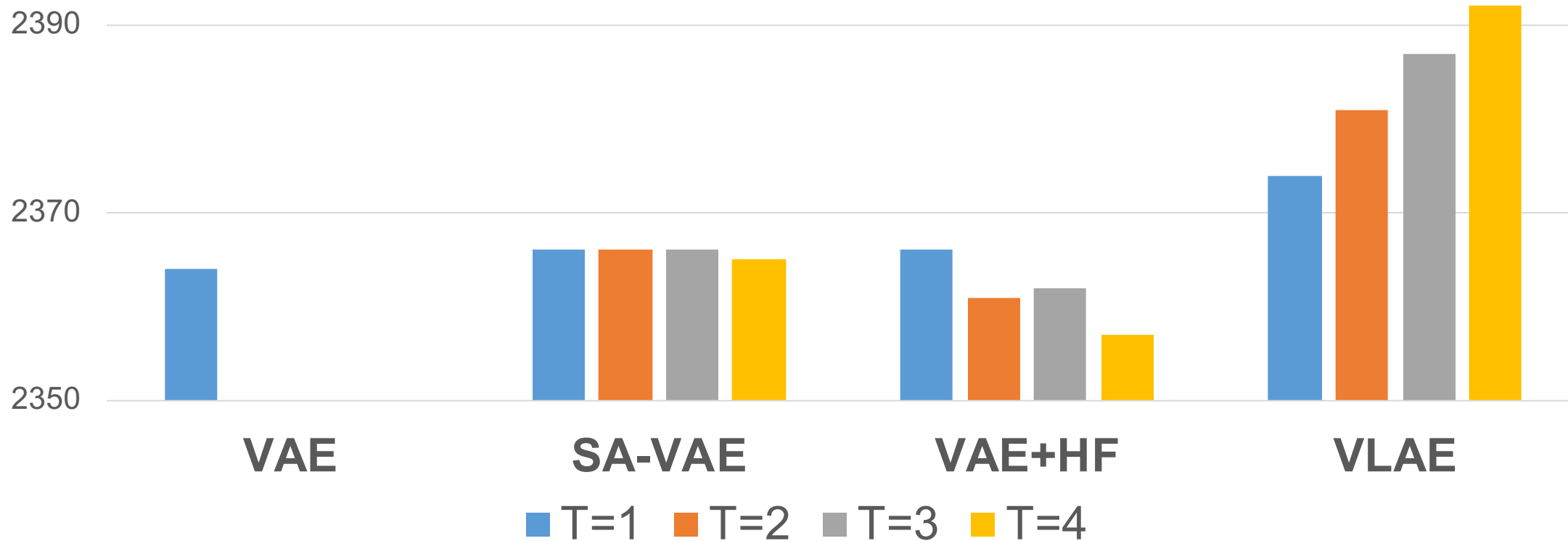


(c) VAE + HF



(d) VLAE

# Log-likelihood Results on CIFAR10



# Thank you

Visit our poster session at **Pacific Ballroom #2**

Code available at : <https://github.com/yookoon/VLAE>