

# Katalyst: Boosting Convex Katayusha for Non-Convex Problems with a Large Condition Number

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# Overview

- 1 Introduction
- 2 Katalyst Algorithm and Theoretical Guarantee
- 3 Experiments

# Problem Definition

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$$\min_{\mathbf{x} \in \mathbb{R}^d} \phi(\mathbf{x}) := \frac{1}{n} \sum_{i=1}^n f_i(\mathbf{x}) + \psi(\mathbf{x}) \quad (1)$$

- we can obtain a better gradient complexity w.r.t. sample size  $n$  and accuracy  $\epsilon$  via variance reduced method (Johnson & Zhang, 2013) (SVRG-type).
- We name the proposed algorithm **Katalyst** after Katyusha (Allen-Zhu, 2017) and Catalyst (Lin et al., 2015).

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# Assumptions

- $\{f_i\}$  are  $L$ -smooth.
- $\psi$  can be non-smooth but convex.
- $\phi$  is  $\mu$ -weakly convex.

## Definition 1

( $L$ -smoothness) A function  $f$  is Lipschitz smooth with constant  $L$  if its derivatives are Lipschitz continuous with constant  $L$ , that is

$$\|\nabla f(\mathbf{x}) - \nabla(\mathbf{y})\| \leq L\|\mathbf{x} - \mathbf{y}\|, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d$$

## Definition 2

(Weak convexity) A function  $\phi$  is  $\mu$ -weakly convex, if  $\phi(\mathbf{x}) + \frac{\mu}{2}\|\mathbf{x}\|^2$  is convex.

# Comparisons with Related Work

**Table 1:** Comparison of gradient complexities of variance reduction based algorithms for finding  $\epsilon$ -stationary point of (1). \* marks the result is only valid when  $L/\mu \leq \sqrt{n}$ .

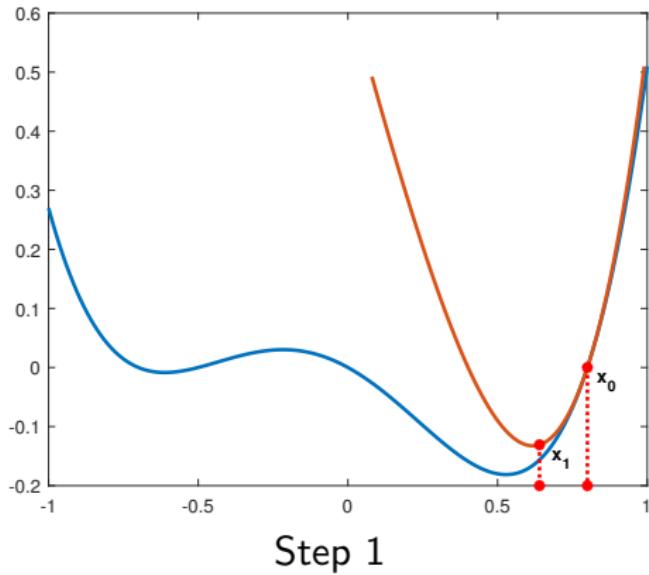
Algorithms	$L/\mu \geq \Omega(n)$	$L/\mu \leq O(n)$	Non-smooth $\psi$
SAGA (Reddi et al., 2016)	$O(n^{2/3}L/\epsilon^2)$	$O(n^{2/3}L/\epsilon^2)$	Yes
RapGrad (Lan & Yang, 2018)	$\tilde{O}(\sqrt{nL\mu}/\epsilon^2)$	$\tilde{O}((\mu n + \sqrt{nL\mu})/\epsilon^2)$	indicator function
SVRG (Reddi et al., 2016)	$O(n^{2/3}L/\epsilon^2)$	$O(n^{2/3}L/\epsilon^2)$	Yes
Natasha1 (Allen-Zhu, 2017)	NA	$O(n^{2/3}L^{2/3}\mu^{1/3}/\epsilon^2)^*$	Yes
RepeatSVRG (Allen-Zhu, 2017)	$\tilde{O}(n^{3/4}\sqrt{L\mu}/\epsilon^2)$	$\tilde{O}((\mu n + n^{3/4}\sqrt{L\mu})/\epsilon^2)$	Yes
4WD-Catalyst (Paquette et al., 2018)	$O(nL/\epsilon^2)$	$O(nL/\epsilon^2)$	Yes
SPIDER (Fang et al., 2018)	$O(\sqrt{nL}/\epsilon^2)$	$O(\sqrt{nL}/\epsilon^2)$	No
SNVRG (Zhou et al., 2018)	$O(\sqrt{nL}/\epsilon^2)$	$O(\sqrt{nL}/\epsilon^2)$	No
Katalyst (this work)	$\tilde{O}(\sqrt{nL\mu}/\epsilon^2)$	$\tilde{O}((\mu n + L)/\epsilon^2)$	Yes

Our bound is proved optimal up to a logarithmic factor by a recent work (Zhou & Gu, 2019).

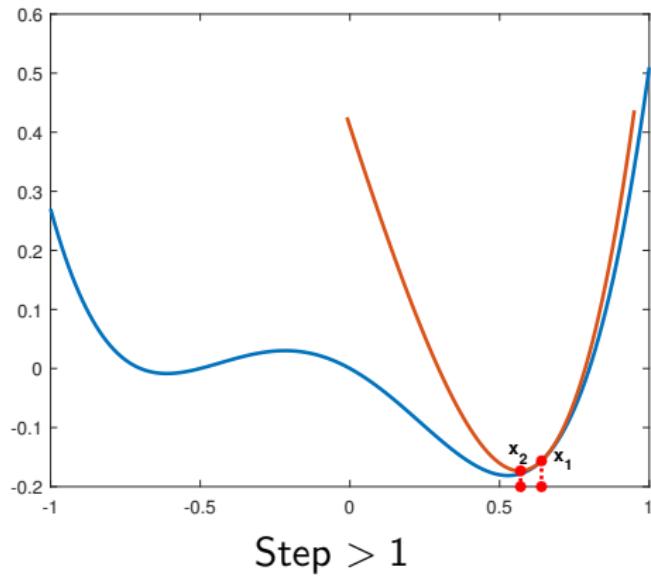
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# Interpretation - Our Basic Idea



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# A Unified Framework

## Meta Algorithm

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**Algorithm 1:** Stagewise-SA( $\mathbf{w}_0$ ,  $\{\eta_s\}$ ,  $\mu$ ,  $\{\mathbf{w}_s\}$ )

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**Input** : a non-increasing sequence  $\{\mathbf{w}_s\}$ ,  $\mathbf{x}_0 \in \text{dom}(\psi)$ ,  $\gamma = (2\mu)^{-1}$ ;

1 **for**  $s = 1, \dots, S$  **do**

2      $f_s(\cdot) = \phi(\cdot) + \frac{1}{2\gamma} \|\cdot - \mathbf{x}_{s-1}\|^2$ ;

3      $\mathbf{x}_s = \text{Katyusha}(f_s, \mathbf{x}_{s-1}, K_s, \mu, L + \mu)$  //  $\mathbf{x}_s$  is usually an averaged solution;

4 **end**

**Output:**  $\mathbf{x}_\tau$ ,  $\tau$  is randomly chosen from  $\{0, \dots, S\}$  according to the

probabilities  $p_\tau = \frac{w_{\tau+1}}{\sum_{k=0}^S w_{k+1}}$ ,  $\tau = 0, \dots, S$  ;

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$$f_s(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^n \underbrace{\left( f_i(\mathbf{x}) + \frac{\mu}{2} \|\mathbf{x} - \mathbf{x}_{s-1}\|^2 \right)}_{\hat{f}_i(\mathbf{x})} + \underbrace{\frac{\gamma^{-1} - \mu}{2} \|\mathbf{x} - \mathbf{x}_{s-1}\|^2 + \psi(\mathbf{x})}_{\hat{\psi}(\mathbf{x})}$$

# Algorithm

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**Algorithm 2:** Katyusha( $f, x_0, K, \sigma, \hat{L}$ )

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**Initialize:**  $\tau_2 = \frac{1}{2}$ ,  $\tau_1 = \min\{\sqrt{\frac{n\sigma}{3L}}, \frac{1}{2}\}$ ,  $\eta = \frac{1}{3\tau_1 L}$ ,  $\theta = 1 + \eta\sigma$ ,  $m = \lceil \frac{\log(2\tau_1+2/\theta-1)}{\log \theta} \rceil + 1$ ,  $\mathbf{y}_0 = \zeta_0 = \tilde{\mathbf{x}}^0 \leftarrow \mathbf{x}_0$ ;

```
1 for  $k = 0, \dots, K - 1$  do
2    $\mathbf{u}^k = \nabla \hat{f}(\tilde{\mathbf{x}}^k)$ ;
3   for  $t = 0, \dots, m - 1$  do
4      $j = km + t$ ;
5      $\mathbf{x}_j = \tau_1 \zeta_j + \tau_2 \tilde{\mathbf{x}}^k + (1 - \tau_1 - \tau_2) \mathbf{y}_j$ ;
6      $\tilde{\nabla}_{j+1} = \mathbf{u}^k + \nabla \hat{f}_i(\mathbf{x}_{j+1}) - \nabla \hat{f}_i(\tilde{\mathbf{x}}^k)$ ;
7      $\zeta_{j+1} = \arg \min_{\zeta} \frac{1}{2\eta} \|\zeta - \zeta_j\|^2 + \langle \tilde{\nabla}_{j+1}, \zeta \rangle + \hat{\psi}(\zeta)$ ;
8      $\mathbf{y}_{j+1} = \arg \min_{\mathbf{y}} \frac{3\hat{L}}{2} \|\mathbf{y} - \mathbf{x}_{j+1}\|^2 + \langle \tilde{\nabla}_{j+1}, \mathbf{y} \rangle + \hat{\psi}(\zeta)$ ;
9   end
10   $\tilde{\mathbf{x}}^{k+1} = \frac{\sum_{t=0}^{m-1} \theta^t \mathbf{y}_{sm+t+1}}{\sum_{j=0}^{m-1} \theta^t}$ ;
11 end
Output :  $\tilde{\mathbf{x}}^K$ ;
```

# Theory

## Theorem 3

Let  $w_s = s^\alpha$ ,  $\alpha > 0$ ,  $\gamma = \frac{1}{2\mu}$ ,  $\hat{L} = L + \mu$ ,  $\sigma = \mu$ , and in each call of Katyusha let

$\tau_1 = \min\{\sqrt{\frac{N\sigma}{3L}}, \frac{1}{2}\}$ , step size  $\eta = \frac{1}{3\tau_1 \hat{L}}$ ,  $\tau_2 = 1/2$ ,  $\theta = 1 + \eta\sigma$ , and  $K_s = \left\lceil \frac{\log(D_s)}{m \log(\theta)} \right\rceil$ ,  
 $m = \left\lfloor \frac{\log(2\tau_1 + 2/\theta - 1)}{\log \theta} \right\rfloor + 1$ , where  $D_s = \max\{4\hat{L}/\mu, \hat{L}^3/\mu^3, L^2s/\mu^2\}$ . Then we have that

$$\max\{\mathbb{E}[\|\nabla\phi_\gamma(\mathbf{x}_{\tau+1})\|^2], \mathbb{E}[L^2\|\mathbf{x}_{\tau+1} - \mathbf{z}_{\tau+1}\|^2]\} \leq \frac{34\mu\Delta_\phi(\alpha+1)}{S+1} + \frac{98\mu\Delta_\phi(\alpha+1)}{(S+1)\alpha^{\mathbb{I}_{\alpha<1}}},$$

where  $\mathbf{z} = \text{prox}_{\gamma\phi}(\mathbf{x})$ ,  $\tau$  is randomly chosen from  $\{0, \dots, S\}$  according to probabilities

$p_\tau = \frac{w_{\tau+1}}{\sum_{k=0}^S w_{k+1}}$ ,  $\tau = 0, \dots, S$ . Furthermore, the total gradient complexity for finding  $\mathbf{x}_{\tau+1}$  such that

$$\max(\mathbb{E}[\|\nabla\phi_\gamma(\mathbf{x}_{\tau+1})\|^2], L^2\mathbb{E}[\|\mathbf{x}_{\tau+1} - \mathbf{z}_{\tau+1}\|^2]) \leq \epsilon^2$$

is

$$N(\epsilon) = \begin{cases} O\left((\mu n + \sqrt{n\mu L}) \log\left(\frac{L}{\mu\epsilon}\right) \frac{1}{\epsilon^2}\right), & n \geq \frac{3L}{4\mu}, \\ O\left(\sqrt{nL\mu} \log\left(\frac{L}{\mu\epsilon}\right) \frac{1}{\epsilon^2}\right), & n \leq \frac{3L}{4\mu}. \end{cases}$$

# Theory

## Theorem 4

Suppose  $\psi = 0$ . With the same parameter values as in Theorem 3 except that  $K = \left\lceil \frac{\log(D)}{m \log(\theta)} \right\rceil$ , where  $D = \max(48\hat{L}/\mu, 2\hat{L}^3/\mu^3)$ . The total gradient complexity for finding  $\mathbf{x}_{\tau+1}$  such that  $\mathbb{E}[\|\nabla \phi(\mathbf{x}_{\tau+1})\|^2] \leq \epsilon^2$  is

$$N(\epsilon) = \begin{cases} O\left((\mu n + \sqrt{n\mu L}) \log\left(\frac{L}{\mu}\right) \frac{1}{\epsilon^2}\right), & n \geq \frac{3L}{4\mu}, \\ O\left(\sqrt{nL\mu} \log\left(\frac{L}{\mu}\right) \frac{1}{\epsilon^2}\right), & n \leq \frac{3L}{4\mu}. \end{cases}$$

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# Experiments I

Squared hinge loss + (log-sum penalty (LSP) / transformed  $\ell_1$  penalty (TL1)).

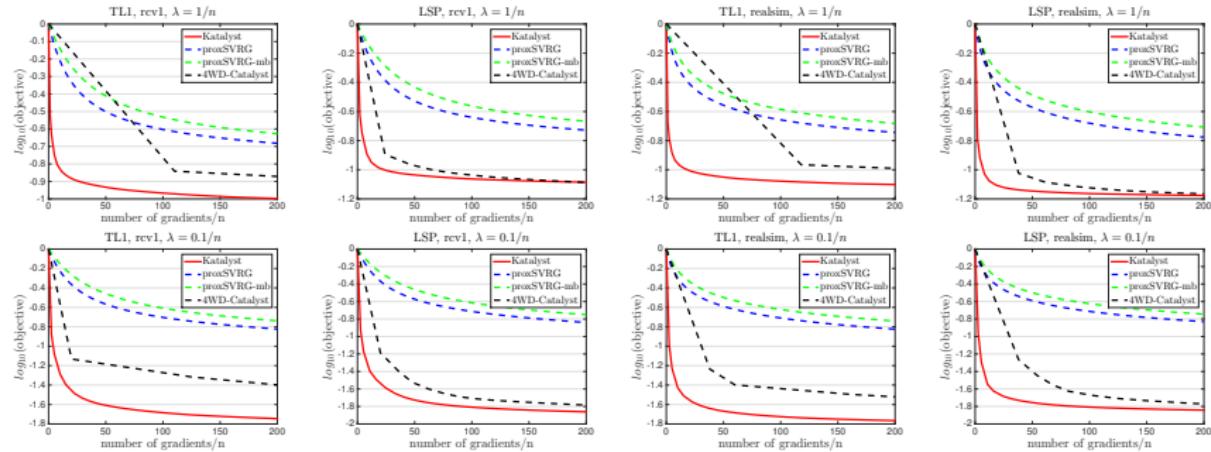


Figure 1: Comparison of different algorithms for two tasks on different datasets

## Experiments II

We use Smoothed SCAD given in (Lan & Yang, 2018),

$$R_{\lambda, \gamma, \epsilon}(x) = \begin{cases} \lambda(x^2 + \epsilon)^{\frac{1}{2}}, & \text{if } (x^2 + \epsilon)^{\frac{1}{2}} \leq \lambda, \\ \frac{2\gamma\lambda(x^2 + \epsilon)^{\frac{1}{2}} - (x^2 + \epsilon) - \lambda^2}{2(\gamma - 1)}, & \text{if } \lambda < (x^2 + \epsilon)^{\frac{1}{2}} < \gamma\lambda, \\ \frac{\lambda^2(\gamma + 1)}{2}, & \text{otherwise,} \end{cases}$$

where  $\gamma > 2$ ,  $\lambda > 0$ , and  $\epsilon > 0$ . Then the problem is

$$\min_{\mathbf{x} \in \mathbb{R}^d} \phi(\mathbf{x}) := \frac{1}{2n} \sum_{i=1}^n (\mathbf{a}_i^\top \mathbf{x} - b_i)^2 + \frac{\rho}{2} \sum_{i=1}^d R_{\lambda, \gamma, \epsilon}(x_i)$$

# Experiments II.1

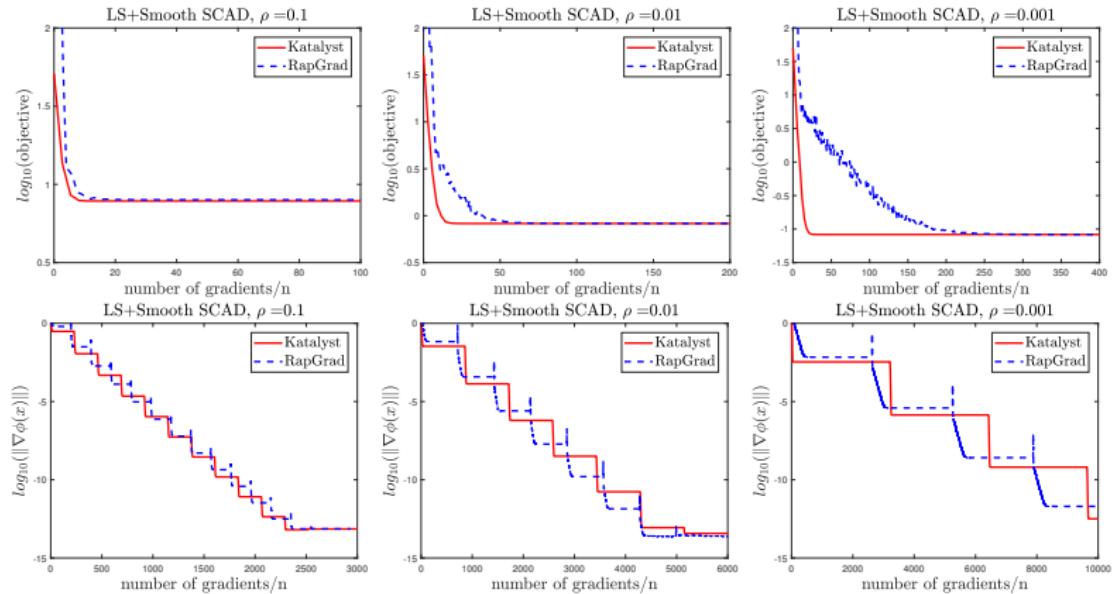


Figure 2: Theoretical performances of RapGrad and Katalyst.

# Experiments II.2

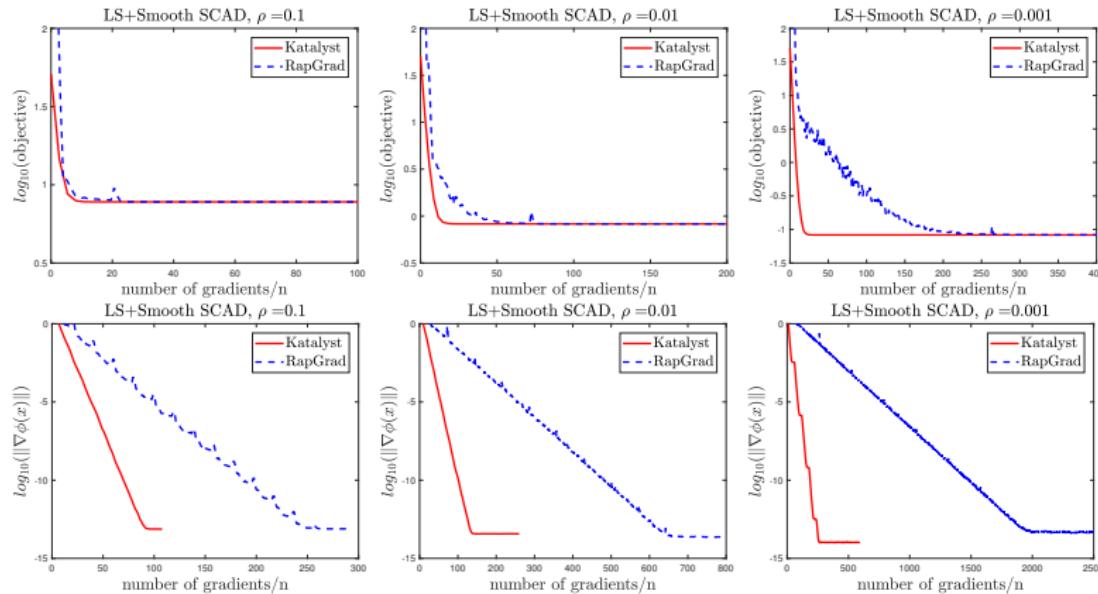


Figure 3: Empirical performances of RapGrad and Katalyst with early termination.

# The End

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