Lipschitz Generative Adversarial Nets

Zhiming Zhou¹ Jiadong Liang² Lantao Yu³ Yong Yu¹ Zhihua Zhang²

¹Shanghai Jiao Tong University

²Peking University

²Stanford University

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Generalized Formulation for GANs

$$\min_{f \in \mathcal{F}} \mathbb{E}_{z \sim \mathbb{P}_z}[\phi(f(g(z)))] + \mathbb{E}_{x \sim \mathbb{P}_r}[\psi(f(x))], \\ \min_{g \in \mathcal{G}} \mathbb{E}_{z \sim \mathbb{P}_z}[\varphi(f(g(z)))],$$

where

- \mathbb{P}_z : the source distribution in \mathbb{R}^{n_z} ;
- \mathbb{P}_r : the target (real) distribution in \mathbb{R}^{n_r} ;
- g: the generative function $\mathbb{R}^{n_z} \to \mathbb{R}^{n_r}$;
- f: the discriminative function $\mathbb{R}^{n_r} \to \mathbb{R}$;
- \mathcal{G} : the generative function space;
- \mathcal{F} : the discriminative function space;

We denote the generation distribution by \mathbb{P}_{g} .

ϕ , ψ , φ : $\mathbb{R} \to \mathbb{R}$ are loss metrics.

 $\mathsf{GAN} \quad : \quad \phi(x) = \psi(-x) = -\log(\sigma(-x))$

WGAN :
$$\phi(x) = \psi(-x) = x$$

LSGAN : $\phi(x) = \psi(-x) = (x + \alpha)^2$



(1)

The problem that the gradient from the discriminator does not contain any informative about the real distribution.

A new perspective for the training instability / convergence issue of GANs.

For GANs with unrestricted \mathcal{F} :

$$f^*(x) = \underset{f(x) \in \mathbb{R}}{\arg\min} \ \mathbb{P}_g(x)\phi(f(x)) + \mathbb{P}_r(x)\psi(f(x)), \ \forall x.$$
(2)

- $f^*(x)$ is independently defined and only reflects the local densities $\mathbb{P}_r(x)$ and $\mathbb{P}_g(x)$;
- ∇_xf^{*}(x) does not reflect any information about the other distribution, if the supports of two distributions are disjoint.



The Gradient Uninformativeness

Unrestricted GANsMUST suffer from this problemRestricted GANsMay suffer from this problemGANs with W-DistanceMay suffer from this problemLipschitz GANsDO NOT suffer from this problem



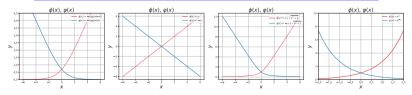
Lipschitz Generative Adversarial Nets (LGANs)

$$\min_{f \in \mathcal{F}} \mathbb{E}_{z \sim \mathbb{P}_{z}}[\phi(f(g(z)))] + \mathbb{E}_{x \sim \mathbb{P}_{r}}[\psi(f(x))] + \lambda \cdot k(f)^{2}],$$

$$\min_{g \in \mathcal{G}} \mathbb{E}_{z \sim \mathbb{P}_{z}}[\varphi(f(g(z)))]. \qquad \qquad k(f): \text{ Lipschitz constant of } f$$

We require ϕ and ψ to satisfy:

Any increasing function with non-decreasing derivative.





(3)

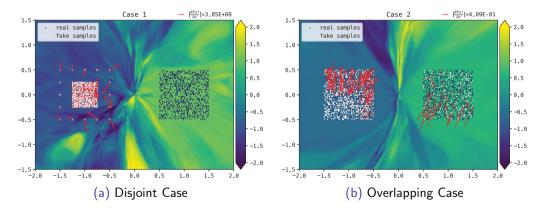
Theoretically guaranteed properties:

- The optimal discriminative function f^* exists;
- If ϕ is strictly convex, then f^* is unique;
- There exists a unique Nash equilibrium where $\mathbb{P}_r = \mathbb{P}_g$ and $k(f^*) = 0$;
- Do not suffer from gradient uninformativeness;
- For each generated sample, the gradient directly points towards a real sample.



Experiments: Gradient Uninformativeness

Gradient uninformativeness practically behaviors as noisy gradient.

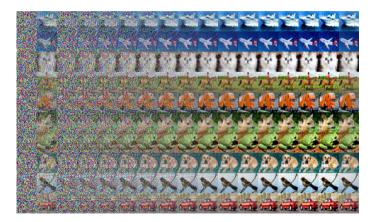




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Experiments: $\nabla_x f^*(x)$ in LGANs

 $\nabla_{x} f^{*}(x)$ directly point towards real samples.

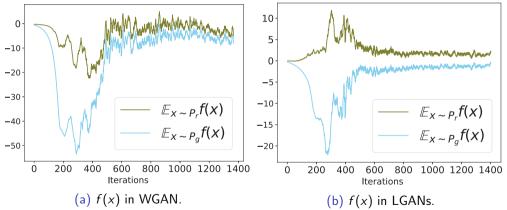




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Experiments: f^* is Unique

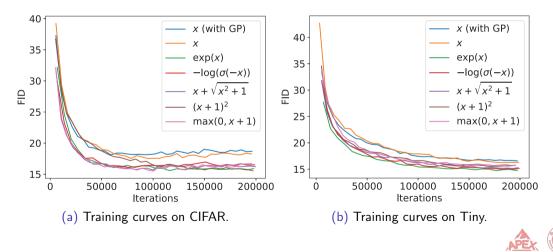
Uniqueness of f^* leads to stabilized discriminative functions.





Experiments: Unsupervised Image Generation

LGANs, with different choices of $\phi(x)$, consistently outperform WGAN.





• Gradient uninformativeness

Unrestricted GANs	MUST suffer from this problem
Restricted GANs	May suffer from this problem
GANs with W-Distance	May suffer from this problem
Lipschitz GANs	DO NOT suffer from this problem

- Lipschitz GANs:
 - Penalize the Lipschitz constant of *f*;
 - Set $\phi(x)$ to be any increasing function with non-decreasing derivative;
 - If ϕ is strictly convex, then f^* is unique;
 - The gradients directly point towards real samples.



(5)