



CURIOUS: Intrinsically Motivated Modular Multi-Goal RL

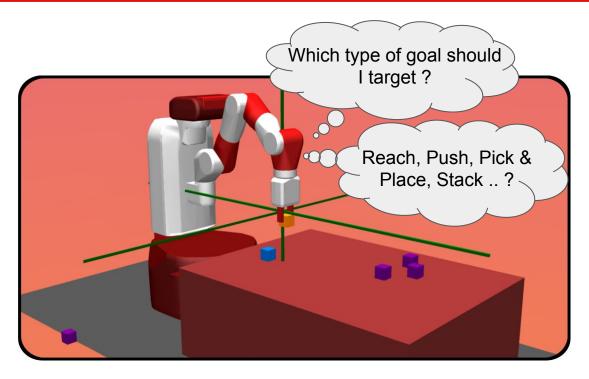
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Co-authors:

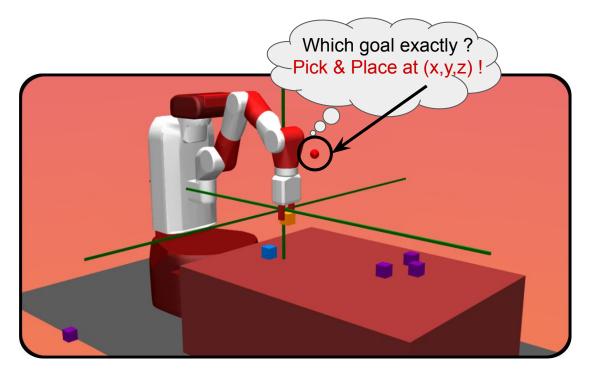
Pierre Fournier, Olivier Sigaud, Mohamed Chetouani, Pierre-Yves Oudeyer

Problem: Intrinsically Motivated Modular Multi-Goal RL

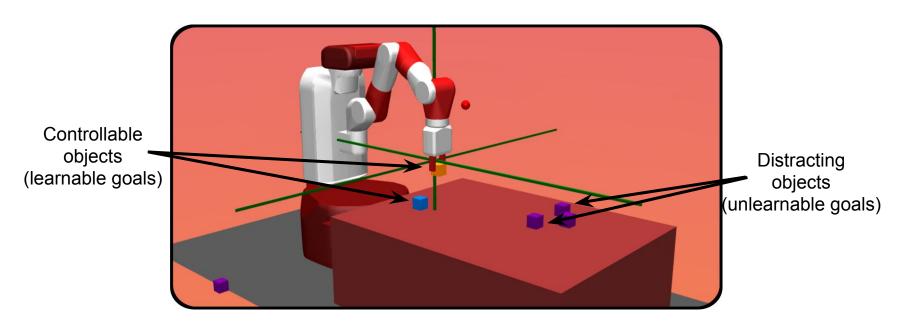


Modular Multi-Goal Fetch Arm environment

Problem: Intrinsically Motivated Modular Multi-Goal RL

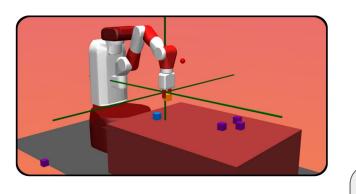


Modular Multi-Goal Fetch Arm environment



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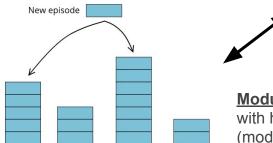
The Curious Algorithm



External world



Sampling of modules and goals using absolute learning progress² (using Bandit algorithm)



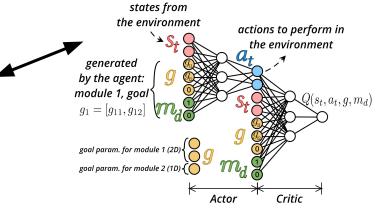
Modular replay buffer:

with hindsight learning^{3, 4} (module and goal substitutions)

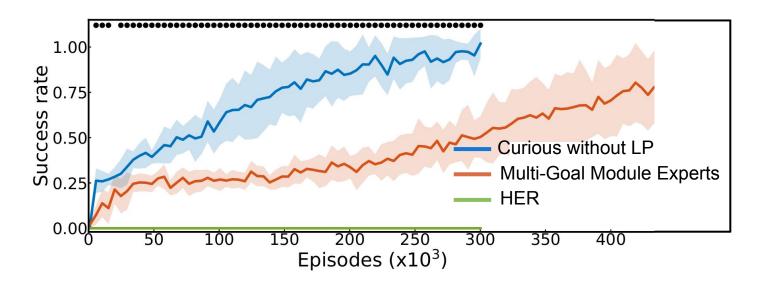
Modular goal encoding for UVFA:1

e.g. of modular goals:

Move gripper to (x,y,z)
Pick & Place cube2 at (x,y,z)
Push cube1 at (x,y)

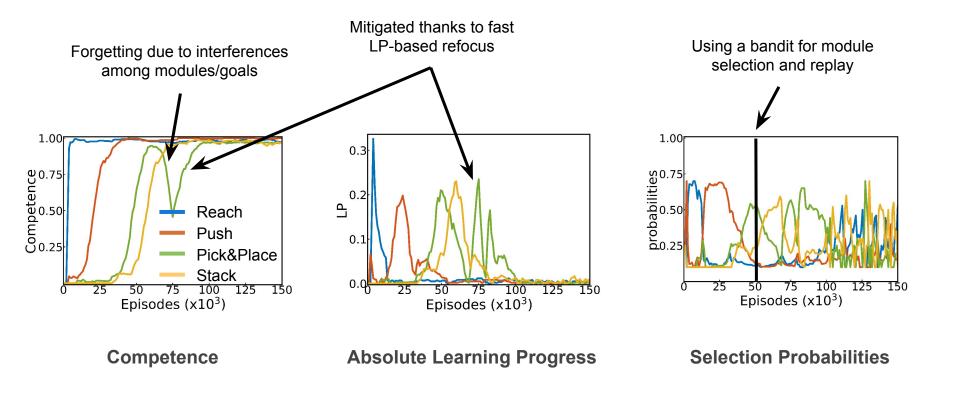


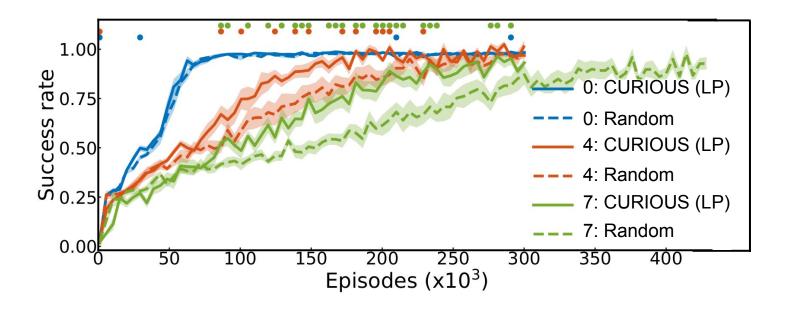
- 1: UVFA, Schaul et al., 2015
- 2: IMGEP, Forestier, 2017
- 3: HER, Andrychowicz et al., 2017
- 4: Unicorn, Mankowitz et al., 2018



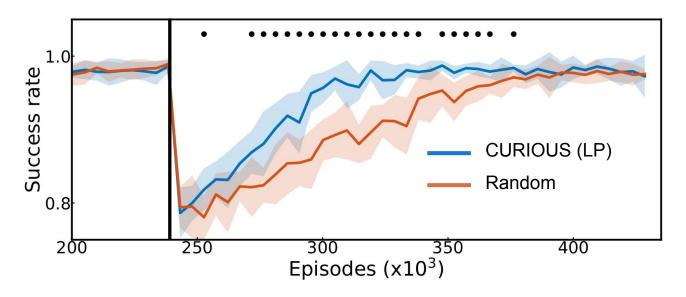
Impact of the policy and value function architecture. Average success rates over the set of tasks (mean +/- std, 10 seeds).

Automatic Curriculum with Absolute Learning Progress



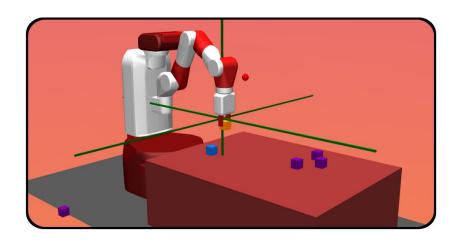


Resilience to distracting goals: 0, 4 or 7 distracting modules. CURIOUS (intrinsically motivated) and Random (random module). Mean +/- sem, 10 seeds.



Resilience to sensory failure: Recovery following a sensory failure. Mean +/- std, 10 seeds.

CURIOUS recovers 95 % of its original performance twice as fast as Random.



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Poster: Pacific Ballroom #42