

Transfer of Samples in Policy Search via Multiple Importance Sampling

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Policy Search (PS): very effective RL technique for continuous control tasks







[OpenAI, 2018]



[Vinyals et al., 2017]

High sample complexity remains a major limitation

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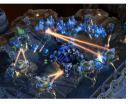
[Vinyals et al., 2017]

- High sample complexity remains a major limitation
- Samples available from several sources are discarded
 - Different policies
 - Different environments

Policy Search (PS): very effective RL technique for continuous control tasks







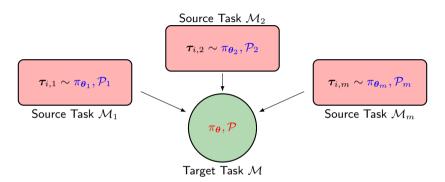
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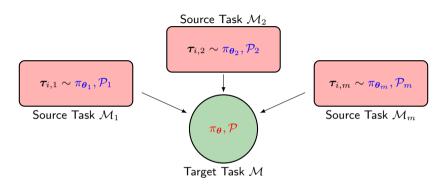
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Transfer of Samples





- Existing works: **batch value-based** settings [Lazaric et al., 2008, Taylor et al., 2008, Lazaric and Restelli, 2011, Laroche and Barlier, 2017, Tirinzoni et al., 2018]
- Extension to online PS algorithms not trivial

$$\nabla^{\mathsf{MIS}}_{\theta}J(\boldsymbol{\theta}) := \frac{1}{n} \sum_{j=1}^{m} \sum_{i=1}^{n_{j}} \underbrace{w(\boldsymbol{\tau}_{i,j})}_{\text{weights gradient}} \underbrace{g_{\boldsymbol{\theta}}(\boldsymbol{\tau}_{i,j})}_{\text{gradient}} \quad w(\boldsymbol{\tau}) := \frac{p(\boldsymbol{\tau}|\boldsymbol{\theta}, \mathcal{P})}{\sum_{j=1}^{m} \alpha_{j} p(\boldsymbol{\tau}|\boldsymbol{\theta}_{j}, \mathcal{P}_{j})}$$

Multiple Importance Sampling (MIS) Gradient Estimator

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Unbiased and bounded weights

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- Unbiased and bounded weights
- Easily combined with other variance reduction techniques

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- Provably robust to negative transfer

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 $\textbf{Problem} \colon \mathcal{P} \text{ unknown} \to \textbf{Importance weights cannot be computed}$

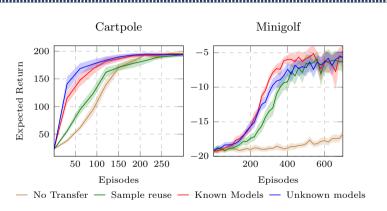
Solution: Online minimization of an upper-bound to the expected MSE of $\nabla_{\theta}^{\mathsf{MIS}}J(\pmb{\theta})$

Problem: $\mathcal P$ unknown \to Importance weights cannot be computed **Solution**: Online minimization of an upper-bound to the expected MSE of $\nabla_{\theta}^{\mathsf{MIS}}J(\boldsymbol{\theta})$

Obtain principled estimates even without target samples

- Obtain principled estimates even without target samples
- Can be efficiently optimized for
 - Discrete set of models
 - lacktriangledown Reproducing Kernel Hilbert Spaces (RKHS) ightarrow Closed-form solution

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- Good performance with both known and unknown models
- Very effective **sample reuse** from different policies but *same* environment





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