

# Approximating Orthogonal Matrices with Effective Givens Factorization

---

**Thomas Frerix**

Technical University of Munich

*joint work with*

**Joan Bruna**

(NYU)

*Poster #164*

## Givens Factorization of Orthogonal Matrices

$$G^T(i, j, \alpha) = \begin{bmatrix} 1 & \cdots & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & & \vdots & & \vdots \\ 0 & \cdots & \cos(\alpha) & \cdots & -\sin(\alpha) & \cdots & 0 \\ \vdots & & \vdots & \ddots & \vdots & & \vdots \\ 0 & \cdots & \sin(\alpha) & \cdots & \cos(\alpha) & \cdots & 0 \\ \vdots & & \vdots & & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \cdots & 0 & \cdots & 1 \end{bmatrix}$$

# Givens Factorization of Orthogonal Matrices

$$G^T(i, j, \alpha) = \begin{bmatrix} 1 & \cdots & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & & \vdots & & \vdots \\ 0 & \cdots & \cos(\alpha) & \cdots & -\sin(\alpha) & \cdots & 0 \\ \vdots & & \vdots & \ddots & \vdots & & \vdots \\ 0 & \cdots & \sin(\alpha) & \cdots & \cos(\alpha) & \cdots & 0 \\ \vdots & & \vdots & & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \cdots & 0 & \cdots & 1 \end{bmatrix}$$

## Exact Givens Factorization

$$U = G_1 \cdots G_N \quad N = \frac{d(d-1)}{2}$$

# Approximate Givens Factorization

## Approximate Givens Factorization

$$U \approx G_1 \dots G_N \quad N \ll \frac{d(d-1)}{2}$$

computationally hard problem

# Approximate Givens Factorization

## Approximate Givens Factorization

$$U \approx G_1 \dots G_N \quad N \ll \frac{d(d-1)}{2}$$

computationally hard problem

## Our Questions in this Context

1. Which orthogonal matrices can be effectively approximated?  
(not all of them)

# Approximate Givens Factorization

## Approximate Givens Factorization

$$U \approx G_1 \dots G_N \quad N \ll \frac{d(d-1)}{2}$$

computationally hard problem

## Our Questions in this Context

1. Which orthogonal matrices can be effectively approximated?  
(not all of them)
2. Which principles are behind effective approximation algorithms?  
(sparsity-inducing algorithms)

# Motivation: Unitary Basis Transform / FFT

## Advantageous Setting

Once computed, applied many times

# Motivation: Unitary Basis Transform / FFT

## Advantageous Setting

Once computed, applied many times

## Unitary Basis Transform

FFT:  $\mathcal{O}(d^2) \rightarrow \mathcal{O}(d \log(d))$



# Motivation: Unitary Basis Transform / FFT

## Advantageous Setting

Once computed, applied many times

## Unitary Basis Transform

FFT:  $\mathcal{O}(d^2) \rightarrow \mathcal{O}(d \log(d))$

Application: Graph Fourier Transform

# Which Matrices can be Effectively Approximated?

## Theorem

Let  $\epsilon > 0$ . If  $N = o(d^2 / \log(d))$ , then as  $d \rightarrow \infty$ ,

$$\mu \left( \left\{ U \in U(d) \mid \inf_{G_1 \dots G_N} \left\| U - \prod_n G_n \right\|_2 \leq \epsilon \right\} \right) \rightarrow 0 ,$$

where  $\mu$  is the Haar measure over  $U(d)$ .

# Which Matrices can be Effectively Approximated?

## Theorem

Let  $\epsilon > 0$ . If  $N = o(d^2 / \log(d))$ , then as  $d \rightarrow \infty$ ,

$$\mu \left( \left\{ U \in U(d) \mid \inf_{G_1 \dots G_N} \left\| U - \prod_n G_n \right\|_2 \leq \epsilon \right\} \right) \rightarrow 0 ,$$

where  $\mu$  is the Haar measure over  $U(d)$ .

- proof is based on an  $\epsilon$ -covering argument
- suggests **computational-to-statistical gap** together with experimental results (details at poster)

## $K$ -planted Distribution over $SO(d)$

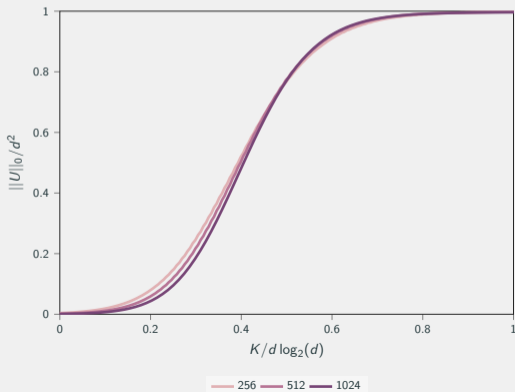
Sample  $U = G_1 \dots G_K$

- choose subspace  $(i_k, j_k)$  uniformly with replacement
- choose rotation angle  $\alpha_k \in [0, 2\pi)$  uniformly

# $K$ -planted Distribution over $SO(d)$

Sample  $U = G_1 \dots G_K$

- choose subspace  $(i_k, j_k)$  uniformly with replacement
- choose rotation angle  $\alpha_k \in [0, 2\pi)$  uniformly



$K$ -planted matrices  
quickly become dense

## Minimizing Sparsity-Inducing Norms over $O(d)$

$$G_N^T \dots G_1^T U \approx I \quad \hat{U} = G_1 \dots G_N$$

## Minimizing Sparsity-Inducing Norms over $O(d)$

$$G_N^T \dots G_1^T U \approx I \quad \hat{U} = G_1 \dots G_N$$

### Approximation criterion

$$\|U - \hat{U}\|_{F, \text{sym}} := \min_{P \in \mathcal{P}_d} \|U - \hat{U}P\|_F$$

## Minimizing Sparsity-Inducing Norms over $O(d)$

$$G_N^T \dots G_1^T U \approx I \quad \hat{U} = G_1 \dots G_N$$

### Approximation criterion

$$\|U - \hat{U}\|_{F, \text{sym}} := \min_{P \in \mathcal{P}_d} \|U - \hat{U}P\|_F$$

### Better functions to be minimized greedily?

$$f(U) := d^{-1} \|U\|_1 = d^{-1} \sum_{i,j=1}^d |U_{ij}|$$



## Minimizing Sparsity-Inducing Norms over $O(d)$

$$G_N^T \dots G_1^T U \approx I \quad \hat{U} = G_1 \dots G_N$$

### Approximation criterion

$$\|U - \hat{U}\|_{F, \text{sym}} := \min_{P \in \mathcal{P}_d} \|U - \hat{U}P\|_F$$

### Better functions to be minimized greedily?

$$f(U) := d^{-1} \|U\|_1 = d^{-1} \sum_{i,j=1}^d |U_{ij}|$$

- *Non-convex* greedy step
- global optimum in  $\mathcal{O}(d^2)$  amortized time complexity

Thank you

*Poster #164*

<https://github.com/tfrerix/givens-factorization>