



Code



Paper



Learning to Learn from APIs: Black-Box Data-Free Meta-Learning

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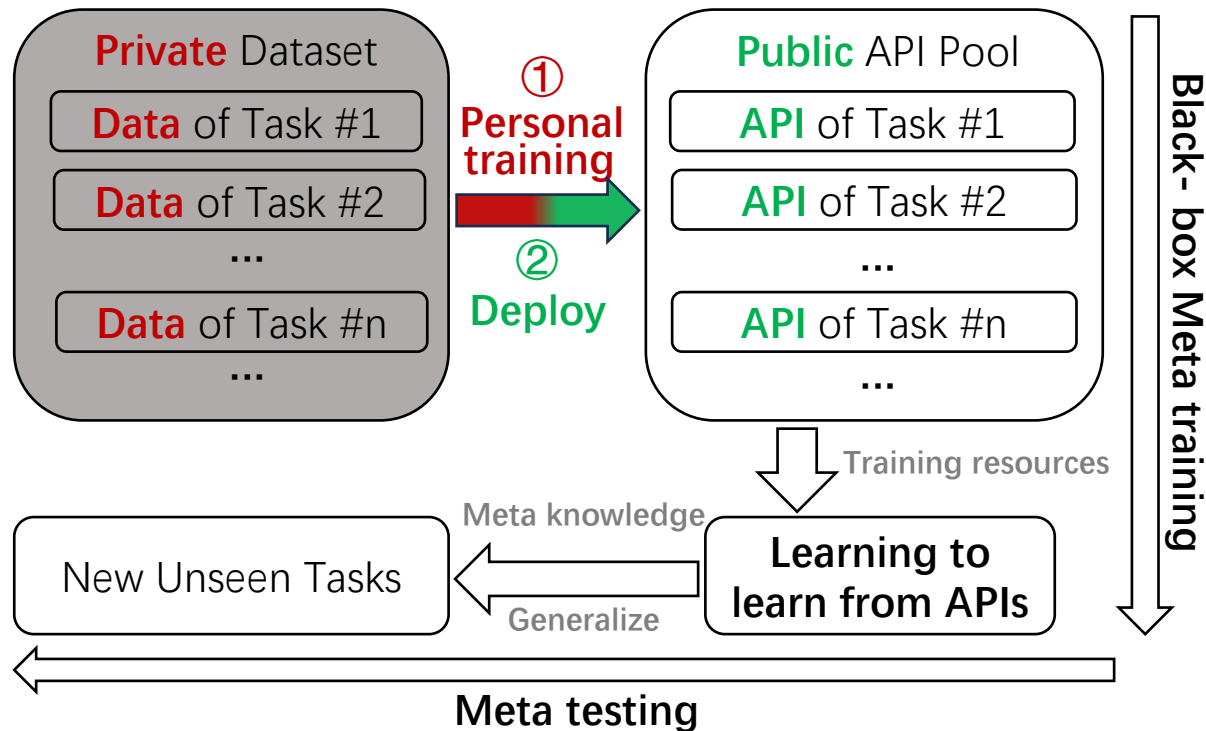


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Overview

Learning to Learn from APIs (Black-box Data-free Meta-learning):

Model as A Service
(e.g., Cloud Vision API, ChatGPT)



Goal:

Learning to learn from APIs or Black-box Data-free Meta-learning aims to enable efficient learning of new unseen tasks by meta-learning the meta-knowledge from a collection of black-box APIs without access to their private training data and with only query access.

Challenges:

- **Data-free:** no access to the original training data
- **Black-box:** with only query access to the APIs and with no prior knowledge of the underlying model architecture and parameters inside each API
- **Privacy-preserving:** no privacy leakage of original training data
- **Model-agnostic:** each API may correspond to arbitrary underlying model architectures and model scale.

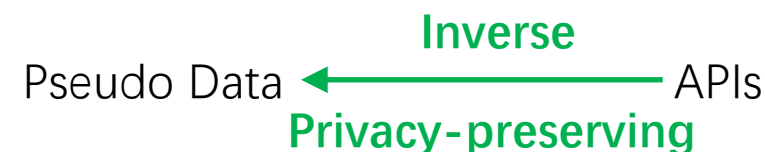
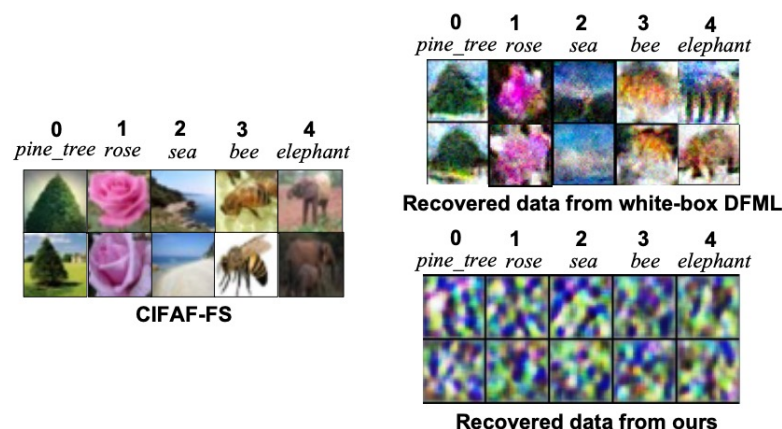
Motivation

What information can we obtain from numerous public APIs of different tasks?

- Model parameters \succ DRO[1](UAI, 2022)
- Model architectures \succ DRO[1](UAI, 2022)
- Underlying data knowledge --- PURER[2](CVPR, 2023)

Challenges	DRO[1]	PURER[2]	Ours
Data-free	✓	✓	✓
Black-box	✗	✗	✓
Privacy-preserving	✓	✗	✓
Model-agnostic	✗	✓	✓

Explore underlying data knowledge contained in APIs in a safe (privacy-preserving) way:

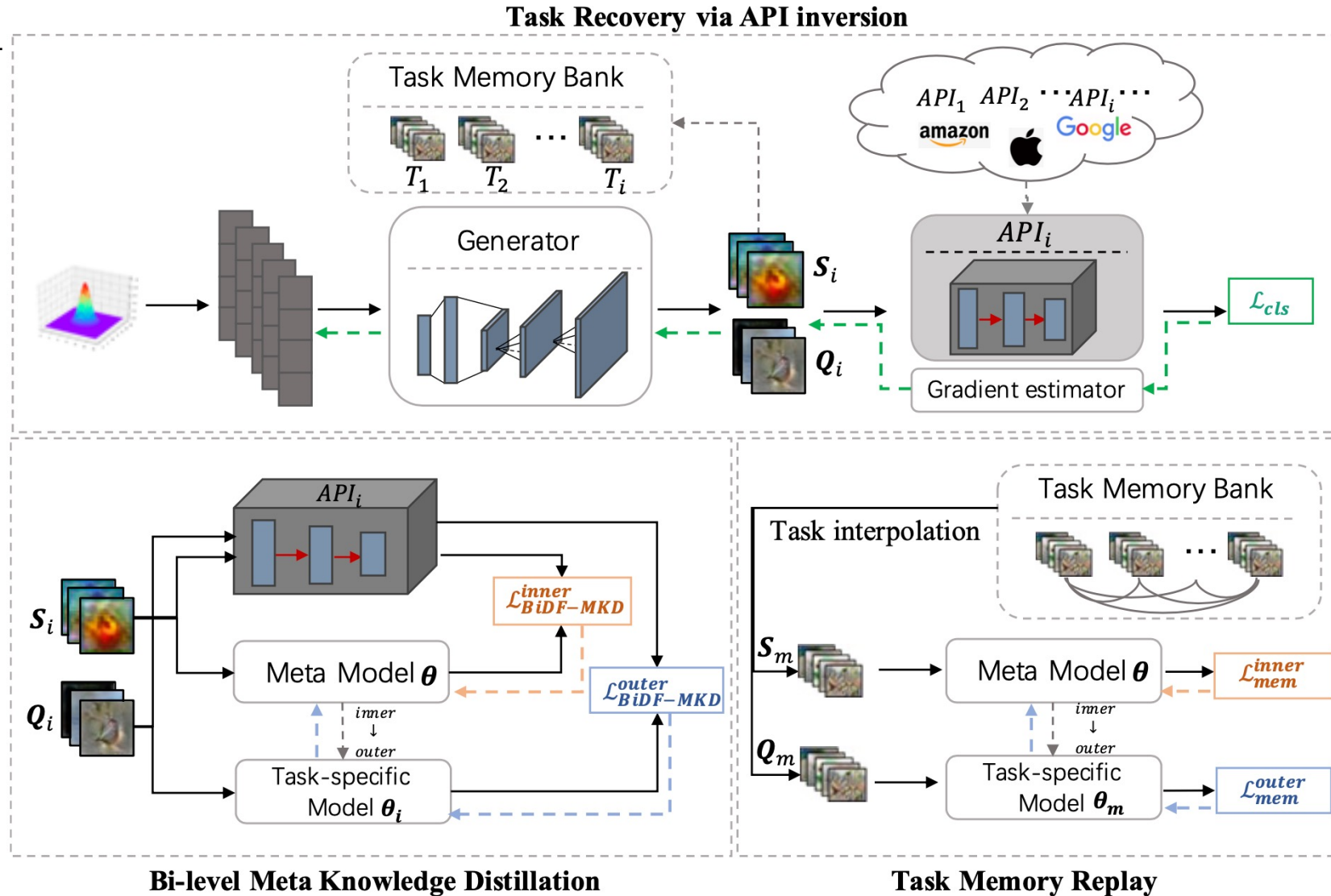


[1] Zhenyi Wang, et al. Meta-learning without data via Wasserstein distributionally-robust model fusion. UAI 2022.

[2] Zixuan Hu, et al. Architecture, Dataset and Model-Scale Agnostic Data-free Meta-Learning. CVPR 2023.

Methodology

Overall framework:



Methodology

Pseudo task recovery via API inversion:

1. Objective function

$$\min_{\mathbf{Z}, \boldsymbol{\theta}_G} \mathcal{L}_{cls}(\hat{\mathbf{X}}) = \frac{1}{|\hat{\mathbf{X}}|} \sum_{(\hat{\mathbf{x}}, y) \in (\hat{\mathbf{X}}, \mathbf{Y})} l_{cls}(\hat{\mathbf{x}}, y), \text{ s.t. } \hat{\mathbf{X}} = G(\mathbf{Z}; \boldsymbol{\theta}_G), l_{cls}(\hat{\mathbf{x}}, y) = CE(A_i(\hat{\mathbf{x}}), y)$$

2. Gradient backward propogation

$$\begin{aligned} \boldsymbol{\theta}_G^{t+1} &= \boldsymbol{\theta}_G^t - \eta \nabla_{\boldsymbol{\theta}_G} \mathcal{L}_{cls} \\ \mathbf{z}^{t+1} &= \mathbf{z}^t - \eta \nabla_{\mathbf{z}} \mathcal{L}_{cls}. \end{aligned}$$

$$\nabla_{\boldsymbol{\theta}_G} \mathcal{L}_{cls} = \frac{\partial \mathcal{L}_{cls}}{\partial \boldsymbol{\theta}_G} = \frac{1}{|\hat{\mathbf{X}}|} \sum_{\hat{\mathbf{x}} \in \hat{\mathbf{X}}} \left[\frac{\partial l_{cls}}{\partial \hat{\mathbf{x}}} \times \frac{\partial \hat{\mathbf{x}}}{\partial \boldsymbol{\theta}_G} \right]$$

$$\nabla_{\mathbf{z}} \mathcal{L}_{cls} = \frac{\partial \mathcal{L}_{cls}}{\partial \mathbf{z}} = \frac{\partial l_{cls}}{\partial \hat{\mathbf{x}}} \times \frac{\partial \hat{\mathbf{x}}}{\partial \mathbf{z}}$$

intractable

3. Zero-order optimization by querying APIs

$$\hat{\nabla}_{\hat{\mathbf{x}}} l_{cls} = \frac{1}{q} \sum_{i=1}^q \left[\frac{d\hat{\mathbf{x}}}{\mu} (l_{cls}(\hat{\mathbf{x}} + \mu \mathbf{u}_i, y) - l_{cls}(\hat{\mathbf{x}}, y)) \mathbf{u}_i \right]$$

Zero-order gradient estimation

Methodology

Bi-level meta knowledge distillation for meta-learning:

$$\begin{aligned} \min_{\theta} \mathcal{L}_{\text{BiDf-MKD}}^{\text{outer}}(\theta) &= \sum_{\hat{x} \in \mathcal{Q}_i} \ell_{KL}(F(\hat{x}; \theta_i), A_i(\hat{x})), \\ \text{s.t. } \theta_i &= \min_{\theta} \mathcal{L}_{\text{BiDf-MKD}}^{\text{inner}} \triangleq \min_{\theta} \sum_{\hat{x} \in \mathcal{S}_i} \ell_{KL}(F(\hat{x}; \theta), A_i(\hat{x})) \end{aligned}$$

Task-memory replay:

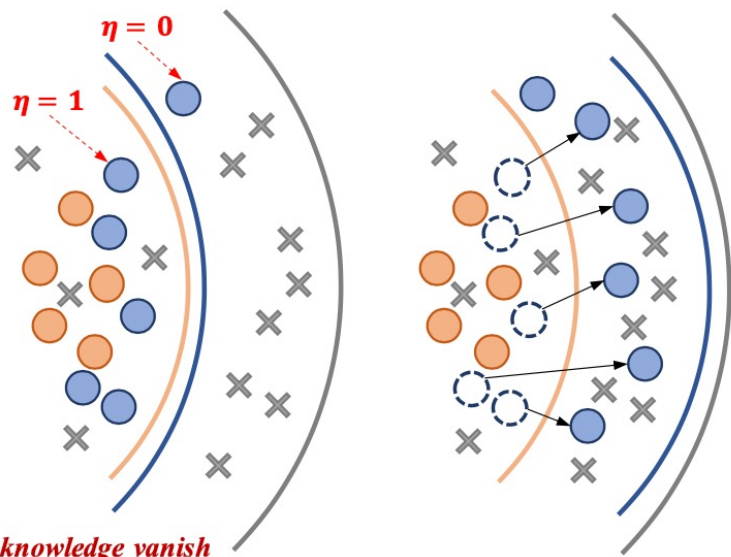
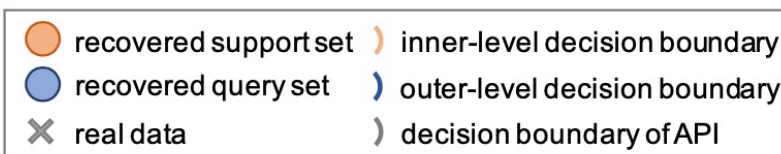
$$\begin{aligned} \min_{\theta} \mathcal{L}_{\text{mem}}^{\text{outer}} &= \mathcal{L}_{\text{cls}}(F(\mathcal{Q}_m; \theta_m), \mathbf{Y}_{\mathcal{Q}_m}), \\ \text{s.t. } \theta_m &= \min_{\theta} \mathcal{L}_{\text{mem}}^{\text{inner}} \triangleq \min_{\theta} \mathcal{L}_{\text{cls}}(F(\mathcal{S}_m; \theta), \mathbf{Y}_{\mathcal{S}_m}) \end{aligned}$$

Methodology

Knowledge vanish issue of data-free meta-learning:

Boundary query set recovery:

Definition 4.1. The *complete knowledge vanish* of meta-learning occurs when the outer-level optimization can be ignored, namely the mutual information $I(\theta; \mathbf{Q}_i | \theta_i, \mathbf{S}_i) = 0$ (or $H(\theta | \theta_i, \mathbf{S}_i) = H(\theta | \theta_i, \mathbf{S}_i, \mathbf{Q}_i)$).



w/o boundary query set recovery

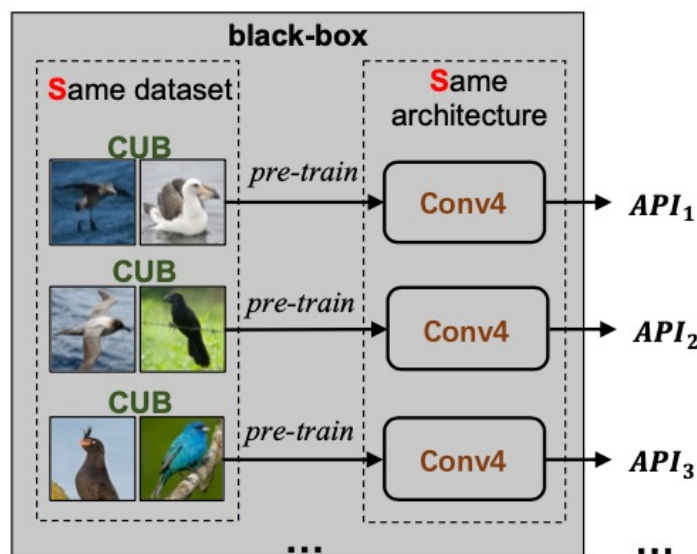
w/ boundary query set recovery

$$\begin{aligned} \min_{\mathbf{z}, \theta_G} \quad & \ell_Q(\hat{\mathbf{x}}, y) \\ & = CE(A_i(\hat{\mathbf{x}}), y) - \lambda_Q \cdot \eta \cdot \ell_{KL}(F(\hat{\mathbf{x}}; \theta_i), A_i(\hat{\mathbf{x}})), \\ \text{s.t.} \quad & \hat{\mathbf{x}} = G(\mathbf{z}; \theta_G), \\ & \eta = \mathbb{I}\{\arg \max F(\hat{\mathbf{x}}; \theta_i) = \arg \max A_i(\hat{\mathbf{x}})\}. \end{aligned}$$

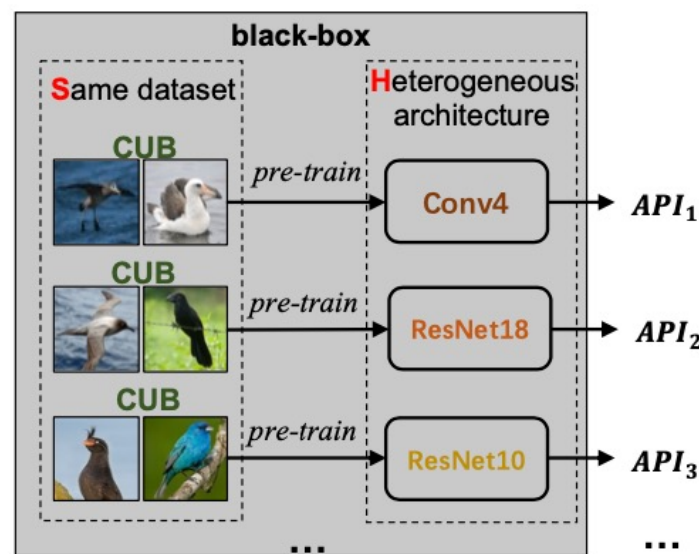
Experiments

Three real-world scenarios:

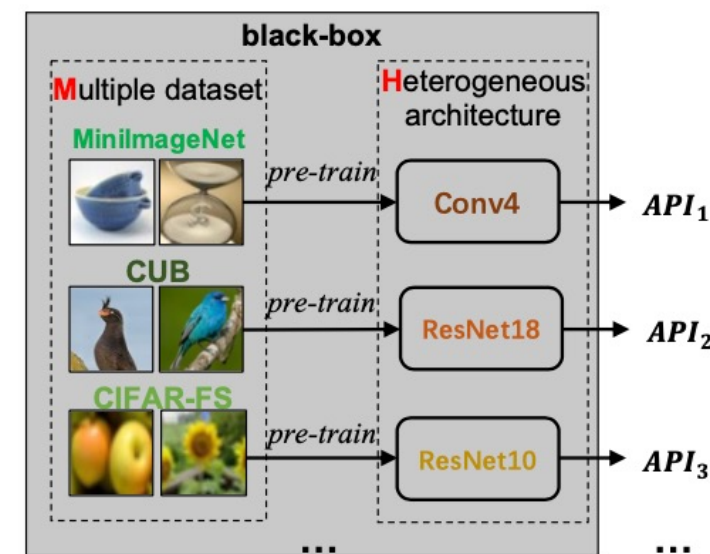
- API-SS:** All APIs are designed for solving tasks from the **S**ame meta training subset with the **S**ame architecture inside
- API-SH:** All APIs are designed for solving tasks from the **S**ame meta training subset but with **H**eterogeneous architectures inside
- API-MH:** All APIs are designed for solving tasks from **M**ultiple meta training subsets with **H**eterogeneous architectures inside



API-SS scenario



API-SH scenario



API-MH scenario

Experiments

Main results:

Table 1. Compare to baselines in API-SS scenario.

API-SS	Method	1-shot	5-shot
CIFAR-FS 5-way	Random	20.35 ± 0.42	20.59 ± 0.45
	Best-API	19.04 ± 0.68	19.04 ± 0.67
	Single-DFKD	20.04 ± 0.63	20.14 ± 0.64
	Distill-Avg	24.24 ± 0.46	27.56 ± 0.51
	Ours	35.48 ± 0.67	47.58 ± 0.74
MiniImageNet 5-way	Random	21.20 ± 0.38	21.13 ± 0.37
	Best-API	20.51 ± 0.63	20.39 ± 0.62
	Single-DFKD	20.03 ± 0.60	20.14 ± 0.66
	Distill-Avg	20.53 ± 0.20	21.24 ± 0.24
	Ours	29.35 ± 0.60	39.47 ± 0.64
CUB 5-way	Random	21.09 ± 0.38	21.11 ± 0.37
	Best-API	19.99 ± 0.69	19.95 ± 0.70
	Single-DFKD	19.56 ± 0.64	20.06 ± 0.64
	Distill-Avg	21.07 ± 0.25	21.97 ± 0.30
	Ours	29.10 ± 0.64	43.43 ± 0.66

Table 3. Compare to baselines in API-MH scenario.

API-MH	Method	1-shot	5-shot
5-way	Random	20.88 ± 0.39	21.00 ± 0.40
	Best-API	19.44 ± 0.65	19.64 ± 0.66
	Single-DFKD	19.04 ± 0.66	19.68 ± 0.64
	Distill-Avg	21.57 ± 0.25	23.11 ± 0.29
	Ours	32.78 ± 0.60	40.24 ± 0.65

Table 2. Compare to baselines in API-SH scenario.

API-SH	Method	1-shot	5-shot
CIFAR-FS 5-way	Random	20.35 ± 0.42	20.59 ± 0.45
	Best-API	19.04 ± 0.68	19.04 ± 0.67
	Single-DFKD	19.56 ± 0.67	20.06 ± 0.60
	Distill-Avg	22.82 ± 0.38	25.91 ± 0.45
	Ours	35.58 ± 0.79	46.92 ± 0.77
MiniImageNet 5-way	Random	21.20 ± 0.38	21.13 ± 0.37
	Best-API	20.51 ± 0.63	20.39 ± 0.62
	Single-DFKD	20.11 ± 0.64	20.23 ± 0.66
	Distill-Avg	20.32 ± 0.22	20.67 ± 0.24
	Ours	30.55 ± 0.62	39.74 ± 0.65
CUB 5-way	Random	21.09 ± 0.38	21.11 ± 0.37
	Best-API	19.99 ± 0.69	19.95 ± 0.70
	Single-DFKD	20.13 ± 0.66	20.24 ± 0.64
	Distill-Avg	20.46 ± 0.24	21.02 ± 0.26
	Ours	30.11 ± 0.58	43.98 ± 0.64

Results

Data privacy:

Zero-order VS. First-order (black-box VS. white-box):

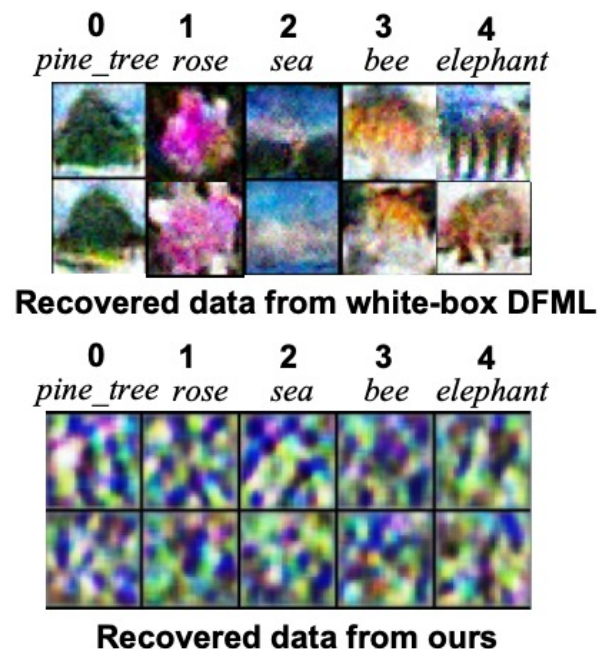
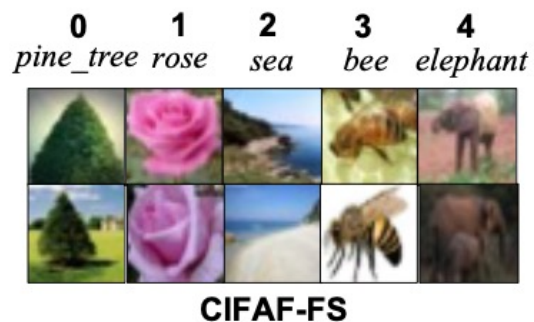


Table 5. Effectiveness of zero-order gradient estimator. Grey: unfair comparison with white-box DFML.

API-SS	Method	1-shot	5-shot
CIFAR-FS 5-way	FO	37.66 ± 0.75	51.16 ± 0.79
	ZO	35.48 ± 0.67	47.58 ± 0.74
MiniImageNet 5-way	FO	30.66 ± 0.59	42.30 ± 0.64
	ZO	29.35 ± 0.60	39.47 ± 0.64
CUB 5-way	FO	31.62 ± 0.60	44.32 ± 0.69
	ZO	29.10 ± 0.64	43.43 ± 0.66

Results

Effect of the number of APIs:

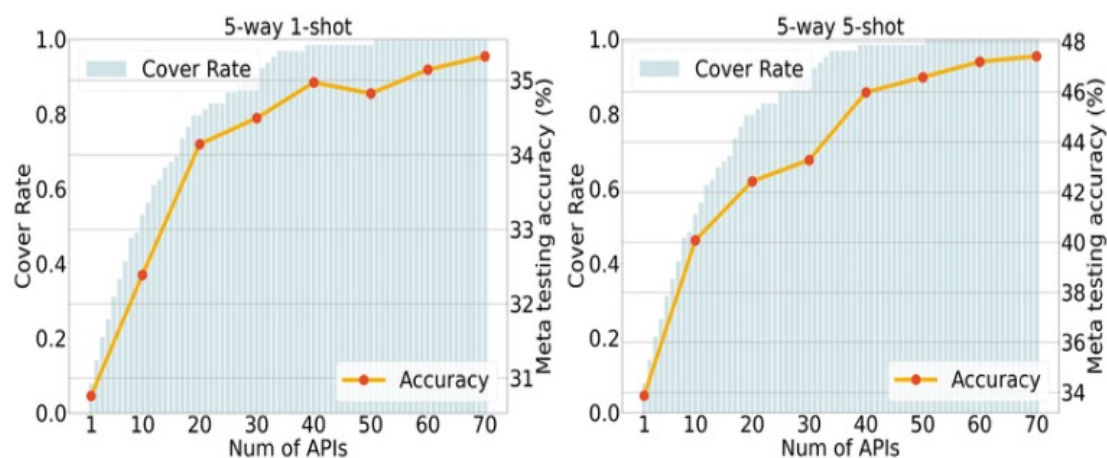


Figure 5. Effect of the number of APIs in API-SS scenario.

Effect of the number of query times:

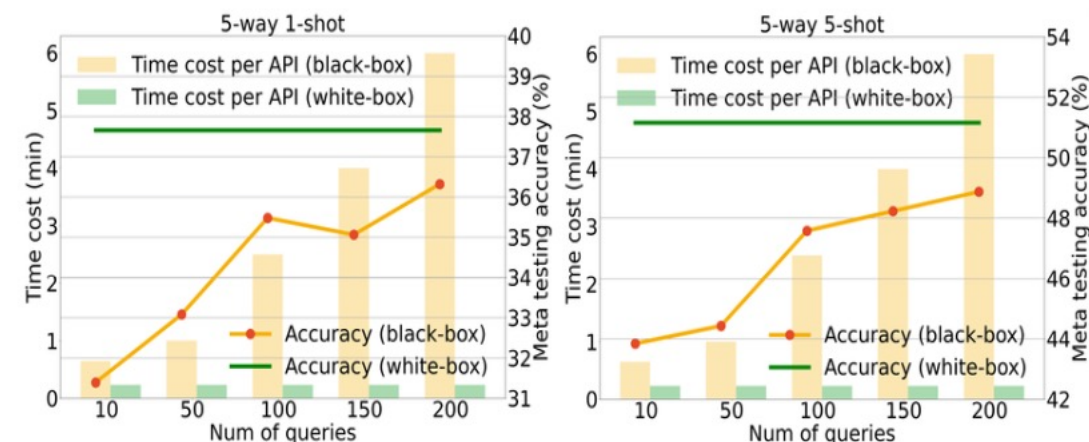


Figure 6. Effect of the number of query times on the accuracy and time cost. Here, white-box DFML provides unfair bounds of accuracy and time cost.



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