

Iterative Approximate Cross-Validation

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Much progress has been made to speed up Leave-one-out CV under the ERM framework [Beirami et al., 2017, Giordano et al., 2019, Wang et al., 2018, Wilson et al., 2020, Rad and Maleki, 2020, Stephenson and Broderick, 2020].

Prediction Error Estimation in ERM via CV

- Empirical Risk Minimization:

$$\hat{\theta} = \arg \min_{\theta \in \mathbb{R}^p} F(\mathcal{Z}; \theta) := \sum_{j=1}^n \ell(Z_j; \theta) + \lambda \pi(\theta),$$

$\mathcal{Z} = \{Z_j\}_{j=1}^n$ is the data, $\ell(Z_j, \theta)$ is the loss on data Z_j with parameter θ .

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- Leave-one-out CV estimation for the prediction error of $\hat{\theta}$:

$$\text{CV}(\{\hat{\theta}_{-i}\}_{i=1}^n) = \sum_{i=1}^n \ell(Z_i; \hat{\theta}_{-i}),$$

where

$$\hat{\theta}_{-i} = \arg \min_{\theta \in \mathbb{R}^p} F(\mathcal{Z}_{-i}; \theta) := \sum_{j=1, j \neq i}^n \ell(Z_j; \theta) + \lambda \pi(\theta)$$

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- These two methods rely on the assumption $\hat{\theta}$ can be exactly obtained.

Guarantees for Existing Methods and Limitations

This assumption can be restrictive in a couple of scenarios:

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What if $\hat{\theta}$ is unknown?

New solution: Iterative Approximate Cross-Validation (IACV).

General Setup

$$F(\mathcal{Z}; \theta) = g(\mathcal{Z}; \theta) + h(\theta),$$

where $g(\mathcal{Z}; \theta)$ is twice-differentiable in θ while $h(\theta)$ may be nondifferentiable.

- Iterative solver:

$$\hat{\theta}^{(t)} = \operatorname{argmin}_{\theta} \left\{ \frac{1}{2\alpha_t} \|\theta - \theta'\|_2^2 + h(\theta) \right\},$$

where $\theta' = \hat{\theta}^{(t-1)} - \alpha_t \nabla_{\theta} g(\mathcal{Z}_{S_t}; \hat{\theta}^{(t-1)})$.

- $S_t \subseteq [n]$: subset of indices, $\mathcal{Z}_{S_t} := \{Z_i : i \in S_t\}$, and $\alpha_t > 0$: learning rate
- Examples: GD, proxGD and SGD ...

Iterative Approximate CV (IACV)

Recall, for $i = 1, \dots, n$:

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where $\theta' = \hat{\theta}_{-i}^{(t-1)} - \alpha_t (\nabla_{\theta} g(\mathcal{Z}_{S_t \setminus i}; \hat{\theta}^{(t-1)}) + \nabla_{\theta}^2 g(\mathcal{Z}_{S_t \setminus i}; \hat{\theta}^{(t-1)}) [\hat{\theta}_{-i}^{(t-1)} - \hat{\theta}^{(t-1)}])$.

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- Smaller computation complexity
- Guaranteed per-iteration error control
- Recover the existing one-step Newton method in the limit
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Exhibit Hall 1 <https://arxiv.org/abs/2303.02732>

Thank you!

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