



LIDL: Local Intrinsic Dimension estimation using approximate Likelihood

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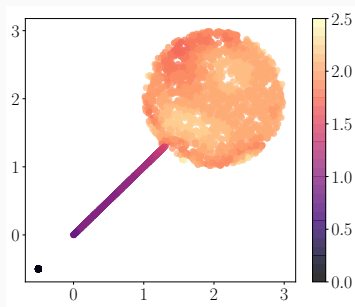


Figure 1: Lollipop dataset with composed of three manifolds of different dimensionality.

In our setting X is a subset of some d -dimensional data manifold M equipped with probability measure μ , and there exist an embedding $j: M \rightarrow \mathbb{R}^D$ into an Euclidean space, through which we can view X .



- The estimation of the intrinsic dimension (ID) of a data set is a classical problem of pattern recognition and machine learning.
- LID estimation is a powerful analytical tool to study the process of training and representation learning in deep neural networks ^{1 2}.
- Intrinsic dimension is connected with model performance ³. Our experiments show, that it can affect point-wise autoencoder performance for image datasets, and the accuracy of the classifier.

¹Li et al. "Measuring the intrinsic dimension of objective landscapes. ICLR 2018."

²Ansuini et al. "Intrinsic dimension of data representations in deep neural networks." NeurIPS 2019.

³Pope et al. "The intrinsic dimension of images and its impact on learning", ICLR 2020

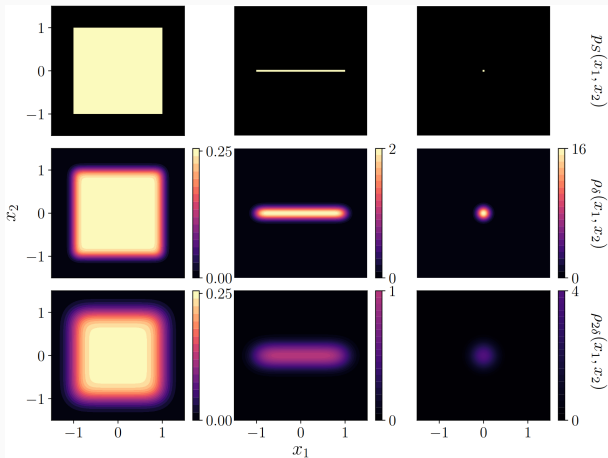


Figure 2: How density changes when perturbed with Gaussian noise.



For small values of δ and smooth on-manifold densities we have

$$\log \rho_\delta(x) \approx (d - D) \log \delta + \text{const.} \quad (1)$$

where:

$\rho_\delta(x)$ – the probability density of the perturbed data at point x with noise $\mathcal{N}(0, \delta^2 I_D)$,

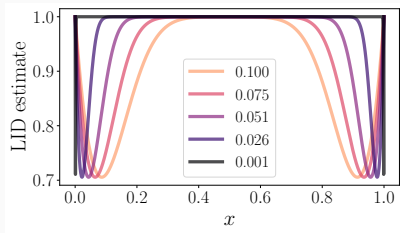
δ – the noise amplitude,

d – manifold dimensionality at x ,

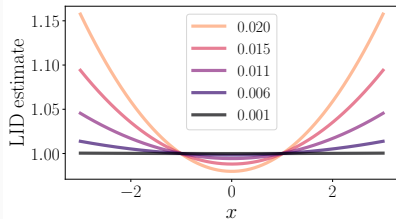
D – ambient space dimensionality.



Require: $X \subset \mathbb{R}^D$; $x_1, \dots, x_m \in \mathbb{R}^D$; $\delta_1, \dots, \delta_n \in \mathbb{R}^+$;
for $j = 1$ **to** n **do**
 $X_j \leftarrow X$ perturbed with $\mathcal{N}(0, \delta_j^2 I_D)$
 Fit the density model $\hat{\rho}_j$ to X_j
end for
for $i = 1$ **to** m **do**
 for $j = 1$ **to** n **do**
 $\xi_j \leftarrow \log \delta_j$
 $\eta_j \leftarrow \log \hat{\rho}_j(x_i)$
 end for
 $\beta \leftarrow$ regression coefficient for a set of n points (ξ_j, η_j)
 $\hat{d}_i \leftarrow D + \beta$
end for
return $(\hat{d}_1, \dots, \hat{d}_m)$



(a) $\mathcal{U}(0, 1)$



(b) $\mathcal{N}(0, 1)$

Figure 3: LIDL estimates for points from distributions that break some of the assumptions for different values of δ (marked with different colors).

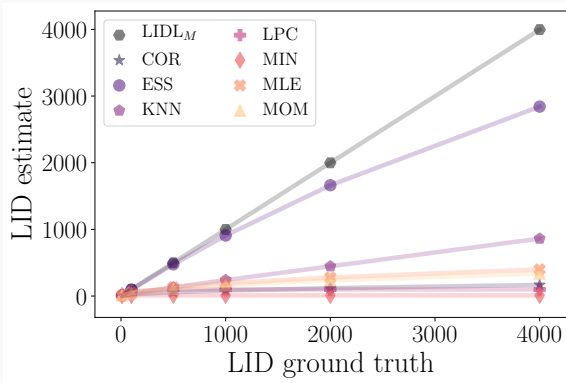
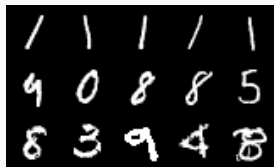


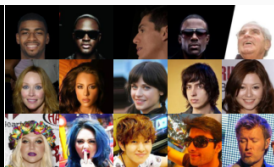
Figure 4: LID estimates for d dimensional uniform distribution on a hypercube. The dimensionality d of the distribution is plotted on the horizontal axis and the estimates for different algorithms on the vertical axis.



MNIST



Celeb-A



Fashion-MNIST





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