



**ICML**  
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On Machine Learning



**武汉大学**  
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# Robustness Verification for Contrastive Learning

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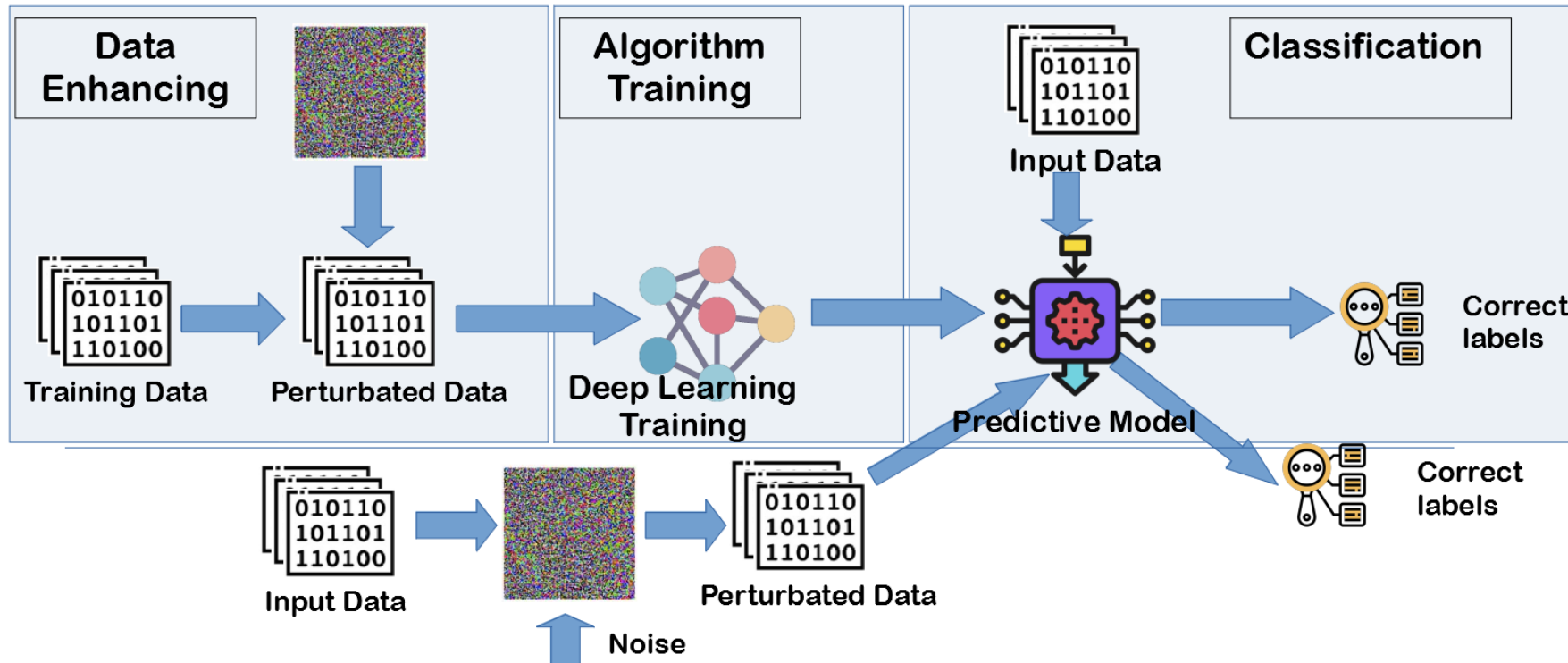
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- Background
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# Background: Adversarial Training

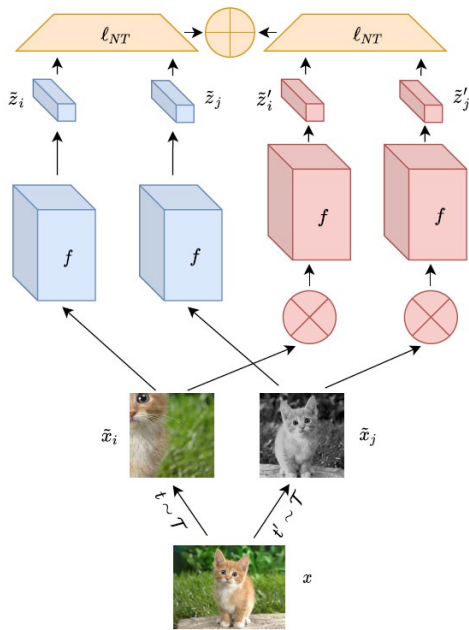
- Define the perturbation:  $\delta = \arg \max_{\|\delta'\|_{\infty} \leq \epsilon} \ell(\theta, x + \delta')$
- Adversarial training aims to solve the optimization problem:

$$\min_{\theta} \mathbb{E}_{x \in \mathcal{X}} \ell(\theta, x + \delta)$$

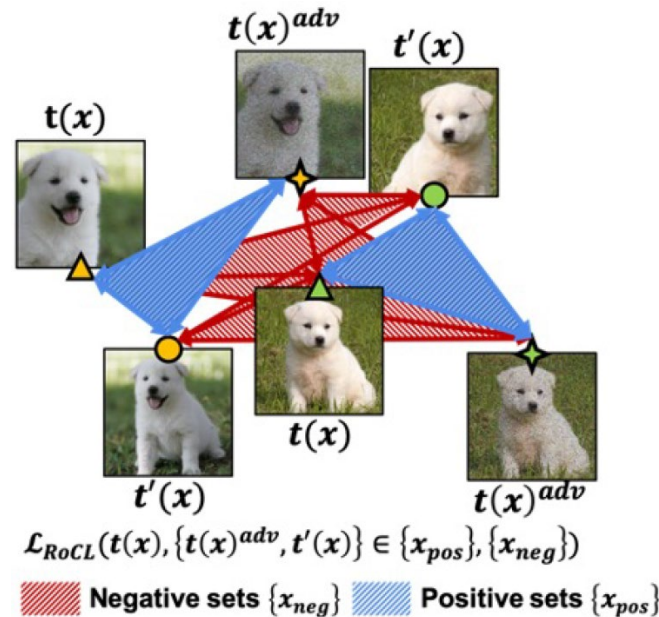


# Background: Contrastive Adversarial Training

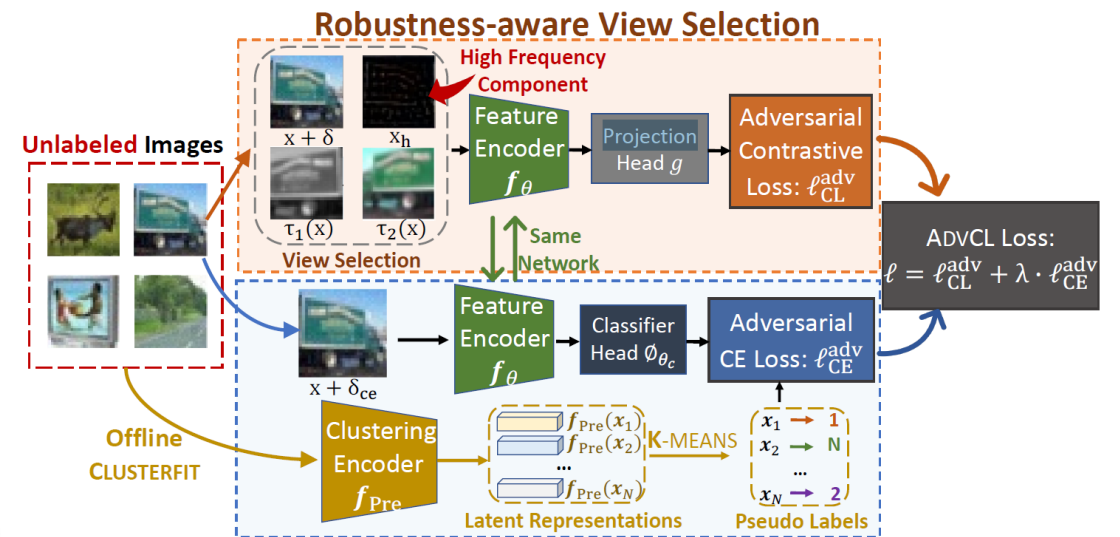
- Labeling scarcity amplified in adversarial robust training
  - Sample complexity is significantly higher than standard training
- Prior works explore using unlabeled data to generate robust models
  - Combine adversarial training with **contrastive learning**



ACL, Jiang et al., 2020



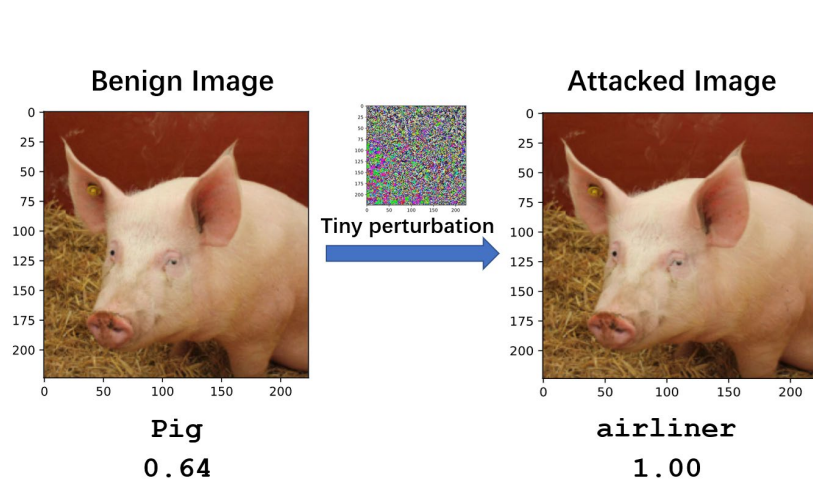
ROCL, Kim et al., 2020



AdvCL, Fan et al., 2021

# Motivation

- Existing contrastive AT methods use the empirical robustness metric to evaluate the robustness of encoders, an approach that relies on **attack algorithms, image labels and downstream tasks**



attack algorithms

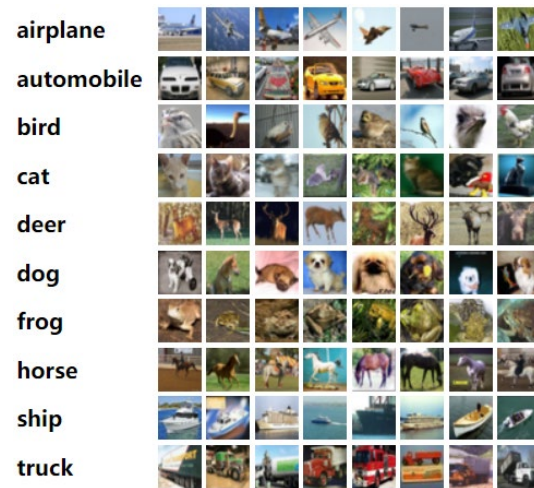
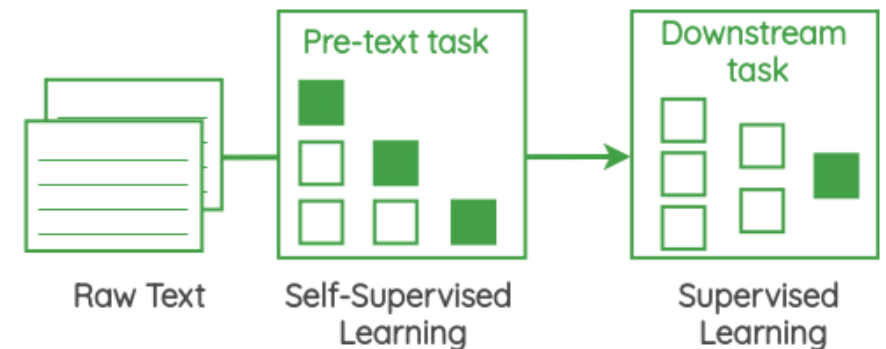


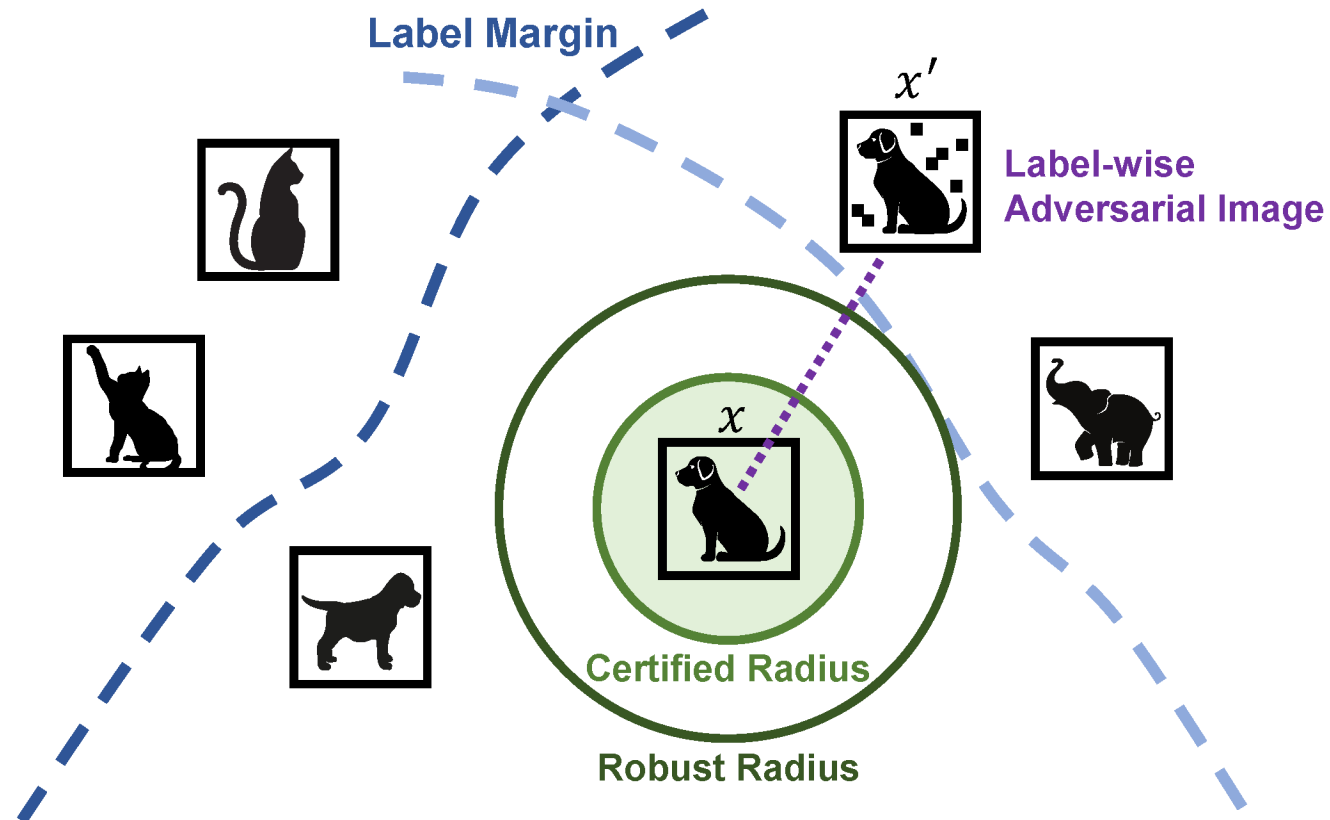
image labels



downstream tasks

# Background: Supervised Robustness Verification

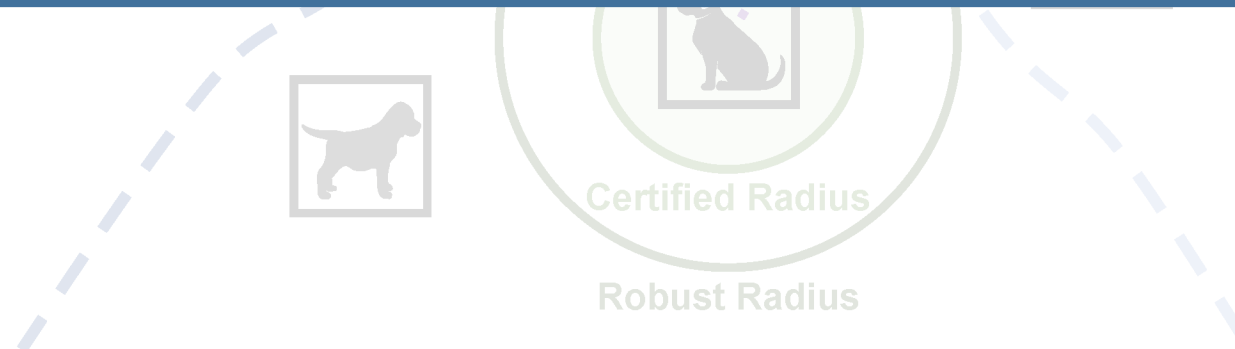
- **Robustness verification** means classifiers whose prediction at point  $x$  is verified to be constant within a neighborhood of  $x$ , regardless of what attack algorithm is applied



# Background: Supervised Robustness Verification

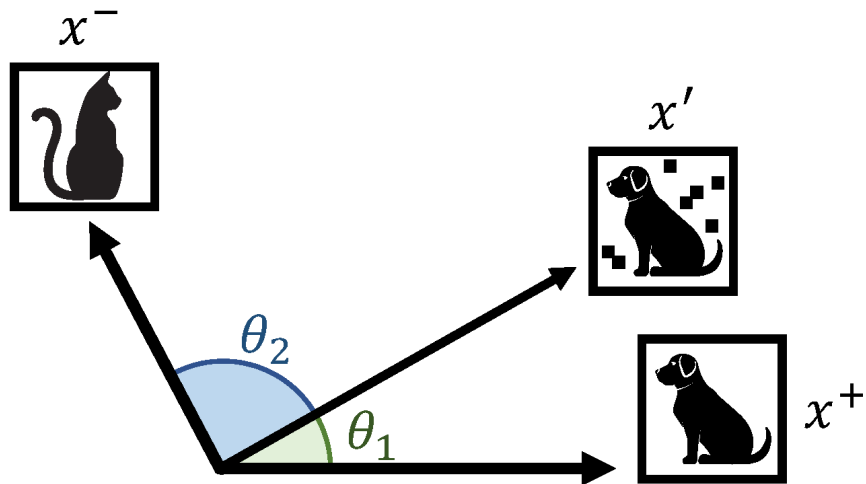
- **Robustness verification** means classifiers whose prediction at point  $x$  is verified to be constant within a neighborhood of  $x$ , regardless of what a

- Can we design a robustness verification framework for contrastive learning that does not require class labels and downstream tasks?
- Is there any relationship between the robust radius of the CL encoder and that of the downstream task?

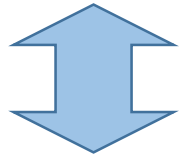


# RVCL Framework: Verification Problem

- Similar with supervised robustness verification, we define **the conditions under which the disturbance successfully attacks the encoder.**



$$\rho(f(x^+), f(x')) > \rho(f(x^-), f(x'))$$



$$(\tilde{\rho}(f(x^+)) - \tilde{\rho}(f(x^-)))^\top f(x') > 0$$

**Definition 4.1** (Verification problem for CL).

$$\tilde{f}(x^+, x^-, \epsilon) := \min_{x'} \mathbf{W}_{\text{CL}} f(x')$$

$$\text{s.t. } \phi_k(x') = \mathbf{W}_k \hat{\phi}_{k-1}(x') + \mathbf{b}_k, k \in [L],$$

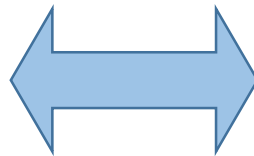
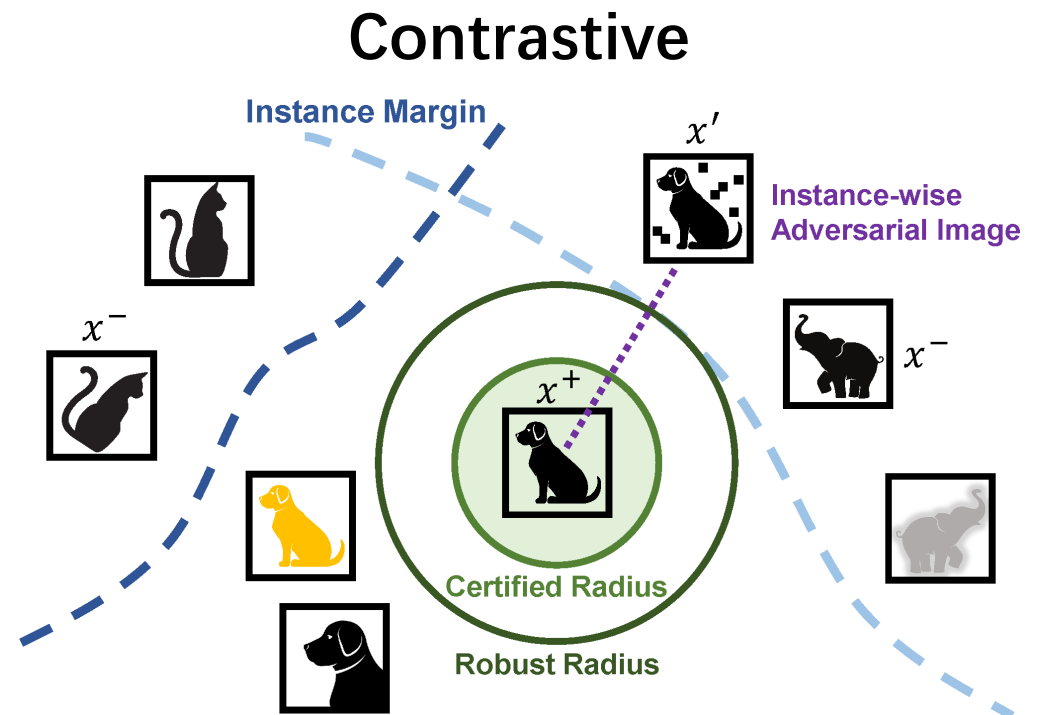
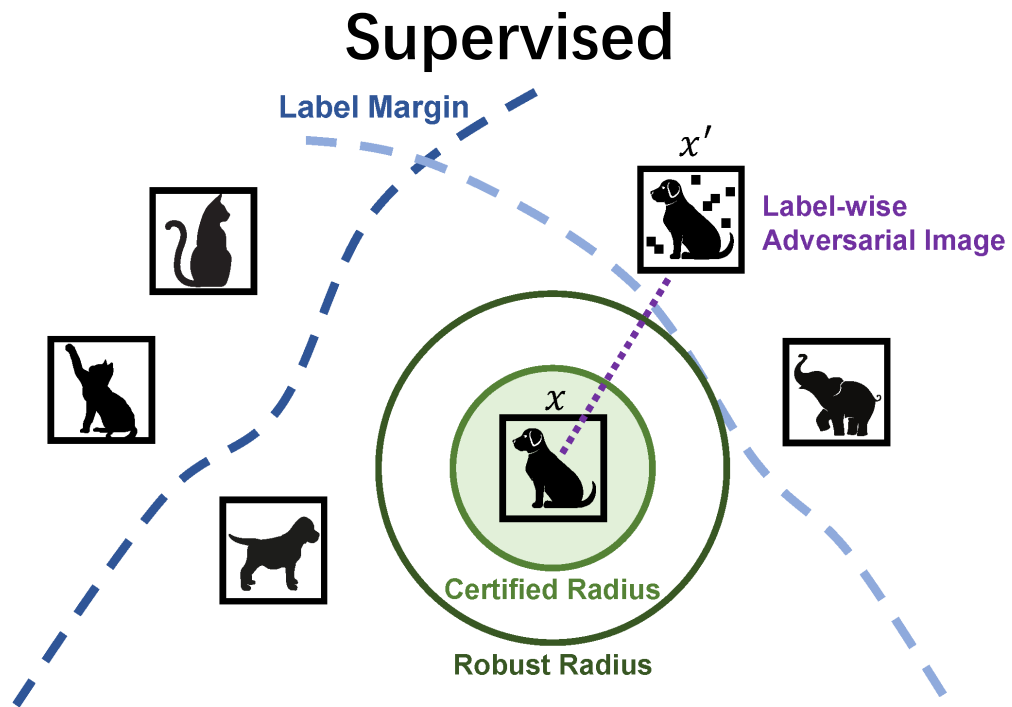
$$\hat{\phi}_k(x') = \sigma(\phi_k(x')), k \in [L - 1],$$

$$\mathbf{W}_{\text{CL}} = (\tilde{\rho}(f(x^+)) - \tilde{\rho}(f(x^-)))^\top \in \mathbb{R}^{1 \times d_L},$$

$$f(x') = \phi_L(x'), x' \in \mathcal{B}_\infty(x^+, \epsilon).$$



# RVCL Framework: Verification Problem



$$\tilde{g}(x, y, \epsilon) := \min_{x'} y \cdot g(x')$$

$$\text{s.t. } \phi_k(x') = \mathbf{W}_k \hat{\phi}_{k-1}(x') + \mathbf{b}_k, k \in [L],$$

$$\hat{\phi}_k(x') = \sigma(\phi_k(x')), k \in [L - 1],$$

$$g(x') = \mathbf{W}_{LE} \phi_L(x') + \mathbf{b}_{LE},$$

$$x' \in \mathcal{B}_\infty(x, \epsilon).$$

$$\tilde{f}(x^+, x^-, \epsilon) := \min_{x'} \mathbf{W}_{CL} f(x')$$

$$\text{s.t. } \phi_k(x') = \mathbf{W}_k \hat{\phi}_{k-1}(x') + \mathbf{b}_k, k \in [L],$$

$$\hat{\phi}_k(x') = \sigma(\phi_k(x')), k \in [L - 1],$$

$$\mathbf{W}_{CL} = (\tilde{\rho}(f(x^+)) - \tilde{\rho}(f(x^-)))^\top \in \mathbb{R}^{1 \times d_L},$$

$$f(x') = \phi_L(x'), x' \in \mathcal{B}_\infty(x^+, \epsilon).$$

# RVCL Framework: Metrics

- By defining the robust radius and certified radius for contrastive learning, we can provide several **robustness metrics** similar to the supervised situation

## Robust radius:

$$R_{\text{CL}}(f; x^+, x^-) := \inf_{\substack{\rho(f(x'), f(x^+)) \\ < \rho(f(x'), f(x^-))}} \|x' - x^+\|_{\infty}$$

$$= \sup_{\epsilon} \epsilon \text{ s.t. } \tilde{f}(x^+, x^-, \epsilon) > 0$$

$$\underline{R}_{\text{CL}}(f; x^+, x^-) := \sup_{\epsilon} \epsilon \text{ s.t. } \underline{f}(x^+, x^-, \epsilon) > 0$$

## Average certified radius (ACR) for CL:

$$\text{ACR}_{\text{CL}} := \frac{1}{K|U_{\text{test}}|} \sum_{z \in U_{\text{test}}} \sum_{i=1}^K \underline{R}_{\text{CL}}(f; x^+, x_i^-)$$

## Robust instance accuracy:

$$\mathcal{A}_{\text{CL}}^{\epsilon} := \frac{1}{|U_{\text{test}}|} \sum_{z \in U_{\text{test}}} \mathbf{1}_{[\rho(f(x'), f(x^+)) - \rho(f(x'), f(x^-)) > 0]}$$

## Certified instance accuracy:

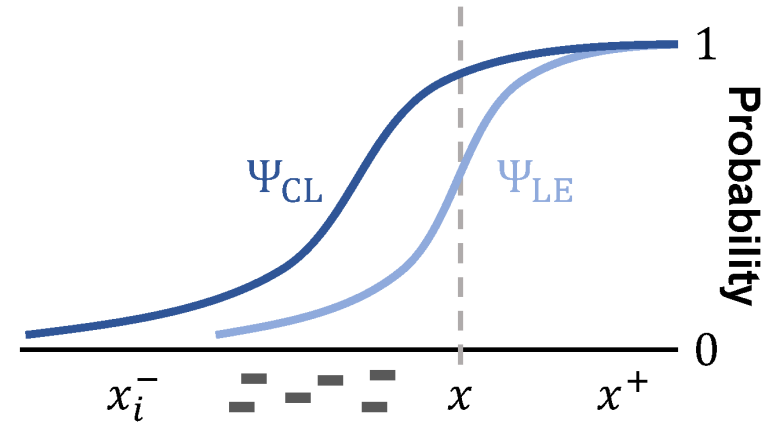
$$\underline{\mathcal{A}}_{\text{CL}}^{\epsilon} := \frac{1}{|U_{\text{test}}|} \sum_{z \in U_{\text{test}}} \mathbf{1}_{[\underline{f}(x^+, x^-, \epsilon) > 0]}$$

# RVCL Framework: Theoretical Analysis

- Single positive sample and multiple negative samples:

**Theorem 5.3** (Robust radius bound). *Given an encoder  $f : \mathcal{X} \rightarrow \mathbb{R}^d$  and an unlabeled sample  $z = (x^+, \{x_i^-\}_{i=1}^K)$ , the downstream predictor  $g : \mathbb{R}^d \rightarrow \mathbb{R}$  is trained on  $\hat{S} = \{(f(x^+), y_{c+}), (f(x_i^-), y_{c-})_{i=1}^K\}$ . Then, for different negative samples  $x_i^-$ , we have*

$$R_{\text{CL}}(f; x^+, x_i^-) \geq R_{\text{LE}}(g; x^+, y_{c+}).$$



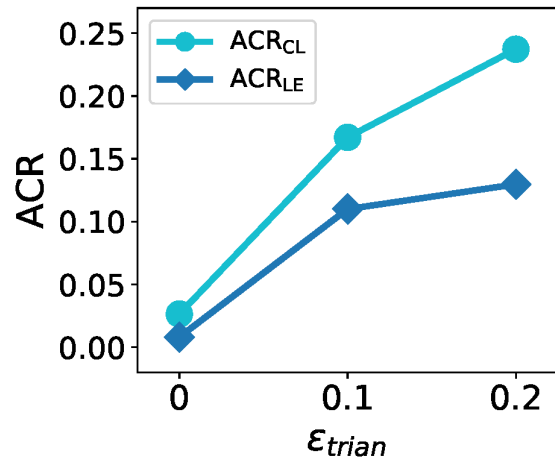
- Multiple positive samples:

**Theorem 5.5.** *Given an encoder  $f : \mathcal{X} \rightarrow \mathbb{R}^d$ , two positive samples  $x_1^+, x_2^+$  and one negative sample  $x^-$ , if  $\rho(f(x_1^+), f(x^-)) \geq \rho(f(x_2^+), f(x^-))$ , then*

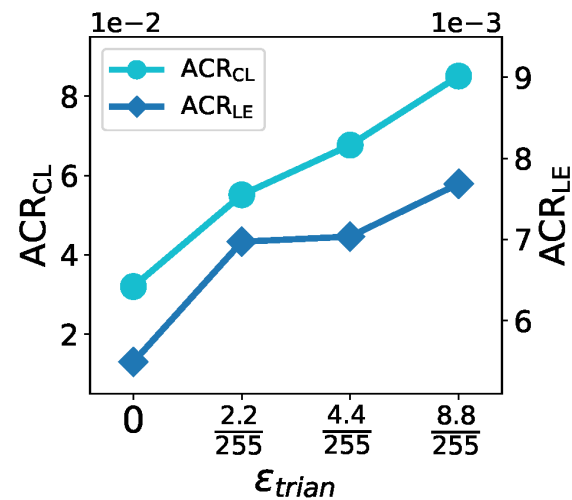
$$R_{\text{CL}}(f; x_1^+, x^-) \leq R_{\text{CL}}(f; x_2^+, x^-).$$

# Experiments: Average Certified Radius

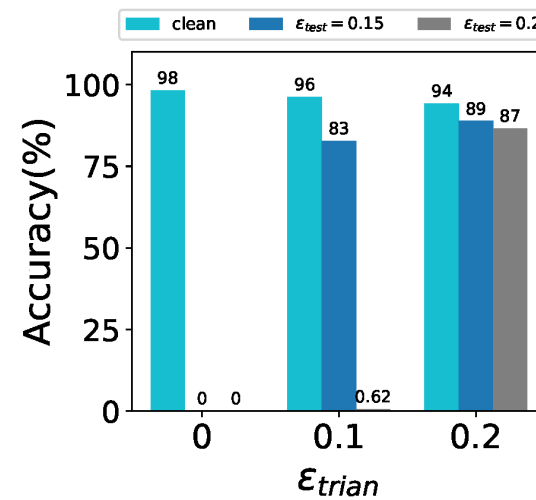
- It is effective to measure the robustness using  $ACR_{CL}$  without labels and downstream tasks
- $ACR_{CL}$  is larger than  $ACR_{LE}$  with the same  $\epsilon_{train}$



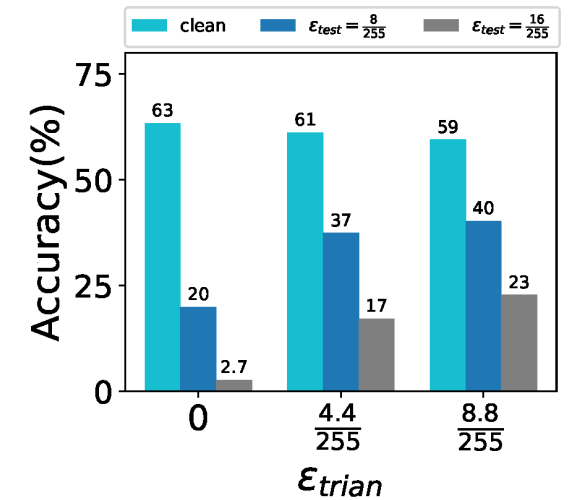
(a) ACR for MNIST



(b) ACR for CIFAR-10



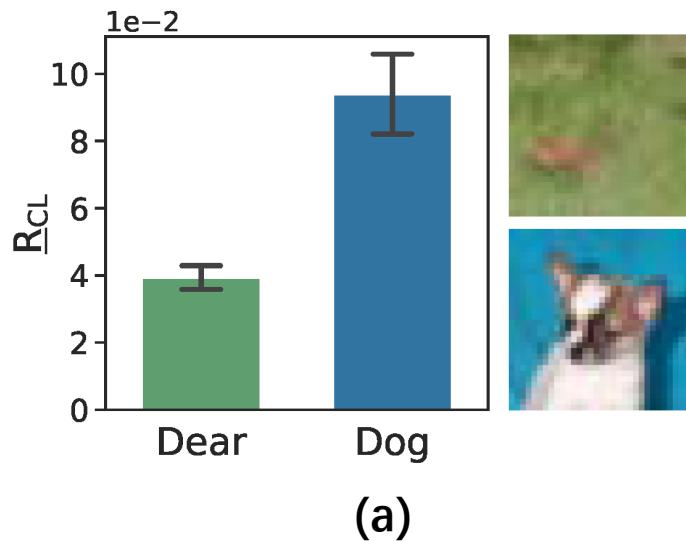
(c) MNIST Robust Test



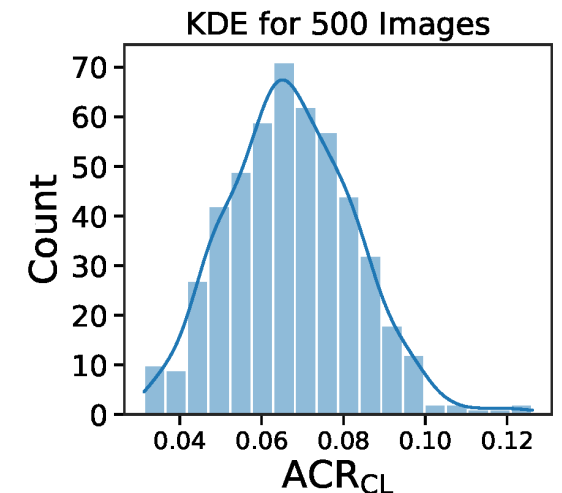
(d) CIFAR-10 Robust Test

# Experiments: Anti-disturbance Ability of Images

- The vague image which is difficult to identify the latent class has a low  $ACR_{CL}$
- These results verify that  $ACR_{CL}$  is able to quantify the anti-disturbance ability of images



(b)



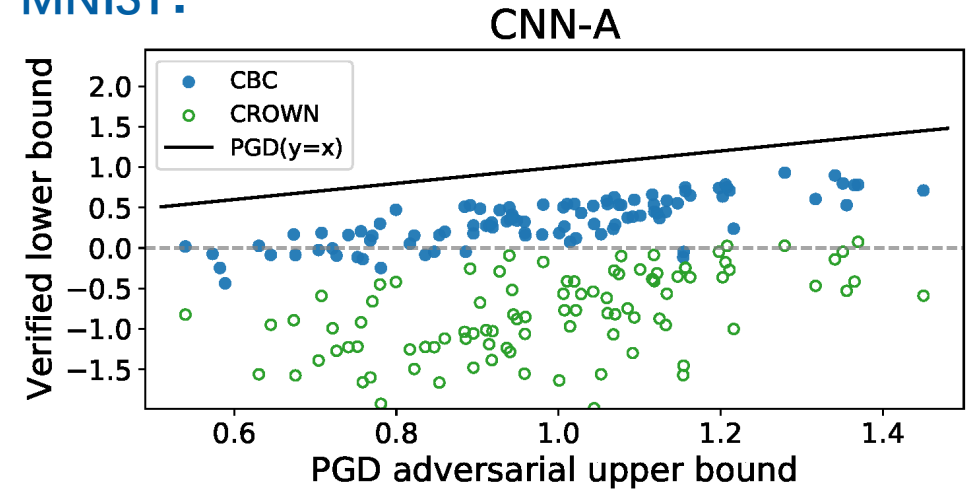
(c)

# Experiments: Tightness of Verification

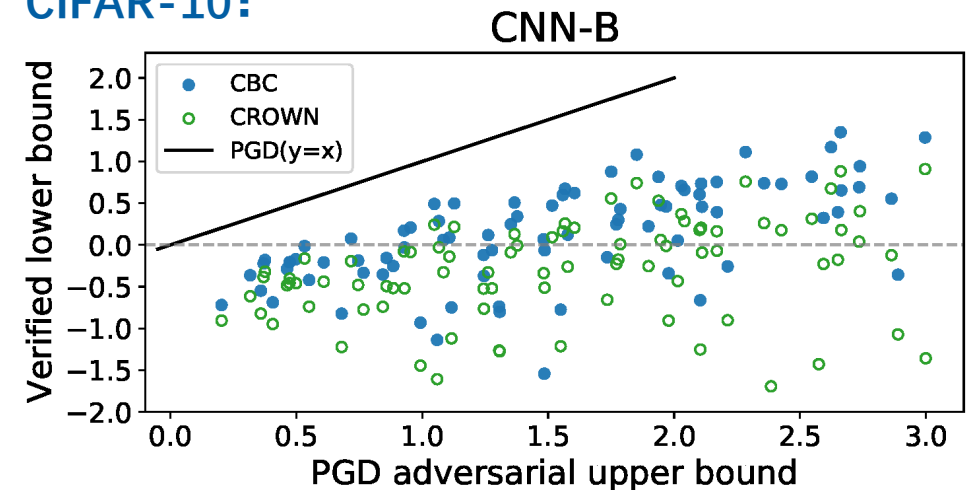
- A stronger supervised verifier can still achieve a tighter certified radius in the RVCL framework

$\epsilon_{test}$	Model	$\epsilon_{train}$	Instance Accuracy	Certified Instance Accuracy	
			PGD	CBC	CROWN
$\frac{2}{255}$	CNN-B	0	100%	97%	96%
		$\frac{2.2}{255}$	100%	100%	100%
		$\frac{4.4}{255}$	91%	26%	11%
$\frac{4}{255}$	Based	$\frac{8.8}{255}$	100%	55%	34%
		$\frac{8.8}{255}$	100%	68%	52%
	Deep	$\frac{4.4}{255}$	100%	99%	95%
		$\frac{4.4}{255}$	100%	96%	84%
$\frac{8}{255}$	CNN-A	$\frac{8.8}{255}$	99%	91%	81%
		$\frac{8.8}{255}$	1%	0%	0%

MNIST:

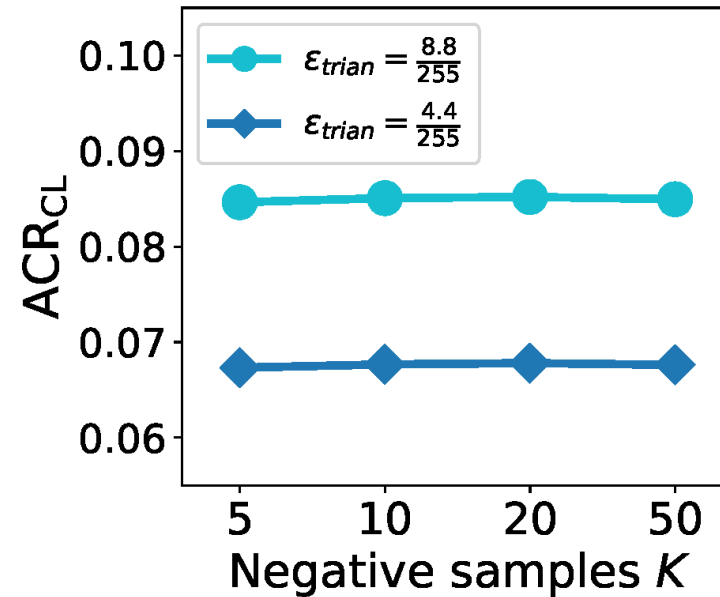
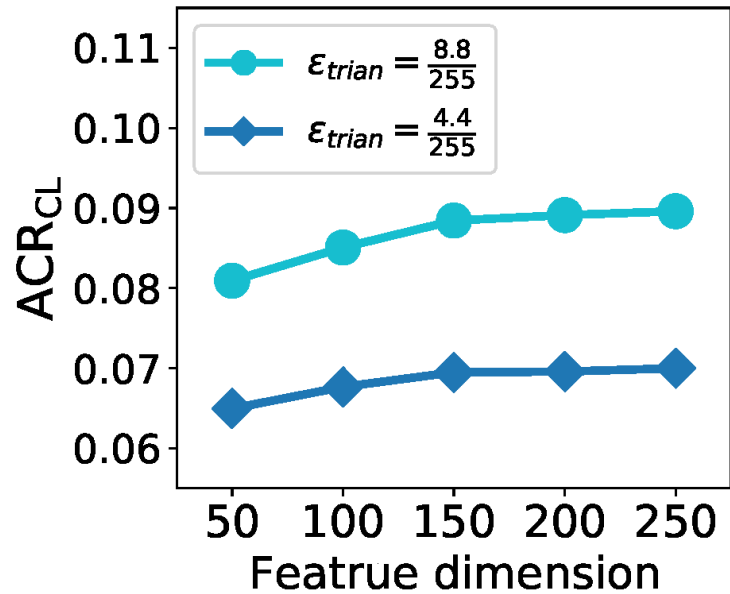


CIFAR-10:



# Experiments: Sensitive Analysis

- The results illustrate that  $ACR_{CL}$  is not sensitive to feature dimension and the number of negative samples



**THANK YOU**