# BAMDT: Bayesian Additive Semi-Multivariate Decision Trees for Nonparametric Regression 

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## Nonparametric Semi-Structured Regression

- Notations:
- $Y \in \mathbb{R}$ : response (e.g., housing price)
- $s \in \mathcal{M}$ : structured features with known multivariate structures (e.g., spatial locations on a constrained domain)
- $x \in \mathcal{X}$ : unstructured features with unknown or without multivariate structures (e.g., square footage, housing age)
- $\mathcal{D} \subset \mathcal{M} \times \mathcal{X}$ : joint feature space.
- Nonparametric regression models

$$
\begin{equation*}
Y=f(\mathrm{~s}, \mathrm{x})+\epsilon \tag{1}
\end{equation*}
$$

where $f$ is an unknown mean function and $\epsilon \stackrel{\text { iid }}{\sim} \mathrm{N}\left(0, \sigma^{2}\right)$ with unknown $\sigma^{2}$.

- Goal: estimate unknown $f$ and predict for $\left(s_{\text {new }}, x_{\text {new }}\right)$.


## Main Challenges

- Structured feature space $\mathcal{M}$ has a (known) non-trivial geometry (e.g., irregular boundary, interior hole, irregular 3-d surfaces)
- Irregular discontinuities in $f$ (e.g., housing price)
- Potentially high-dimensional unstructured features $x$
- Potential interactions between s and x


Figure: Examples of complex constrained domains

## Existing Methods

- Spline smoothing (Ramsay, 2002; Lai and Schumaker, 2007; Wang and Ranalli, 2007; Wood et al., 2008; Scott-Hayward et al., 2014; Sangalli et al., 2013) and Gaussian process regression (Lin et al., 2019; Niu et al., 2019; Borovitskiy et al., 2020; Dunson et al., 2022):
- Respect complex domain boundaries and intrinsic geometries in $\mathcal{M}$
- Assume globally smooth $f X$
- Usually assume an additive model for x , e.g., $f(\mathrm{~s}, \mathrm{x})=\mathrm{x}^{\top} \boldsymbol{\beta}+f(\mathrm{~s}) \boldsymbol{x}$
- Tensor product splines have too many basis functions for high-dimensional $\times x$


## Existing Methods

- Bayesian additive (univariate decision) regression trees (BART; Chipman et al., 2010):
- Each tree generates axis-parallel partitions of the feature space
- Approximate $f$ with summation of simple piecewise constant functions
- Local adaptivity to discontinuities and different levels of smoothness in $f$
- Capture some interaction effects among features
- Address feature scaling and feature selection issues with high dimensional $\times$
- May not fully respect intrinsic geometries in $\mathcal{M}$ or capture irregular discontinuities in $f X$
- Bayesian additive spanning trees (BAST; Luo et al., 2021):
- Using flexible spanning tree partitions for $\mathcal{M}$, which respects its intrinsic geometry
- Not straightforward to include unstructured features $\times X$
- Lack of a coherent model for prediction $X$


## Semi-Multivariate Decision Trees (sMDTs)

Each node $\eta$ represents a subset $\mathcal{D}_{\eta} \subset \mathcal{D}$.

1. Start with a root node representing $\mathcal{D}$.
2. Split a terminal node $\eta$ with probability $p_{\text {split }}(\eta)$. If $\eta$ splits, choose one split rule to obtain a bipartition $\left\{\mathcal{D}_{\eta, 1}, \mathcal{D}_{\eta, 2}\right\}$ of $\mathcal{D}_{\eta}$ :
2.1 With probability $p_{m}$, perform a multivariate split using the structured features $s$.
2.2 Otherwise, perform a univariate split using one of the unstructured features $x$.


Figure: An example of sMDT
3. Apply Step 2 to each offspring node of $\eta$.

## Univariate Split Rules

- A node $\eta$ in an sMDT represents a subset $\mathcal{D}_{\eta} \subset \mathcal{D}$.
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- A univariate split rule divides $\mathcal{D}_{\eta}$ into

$$
\mathcal{D}_{\eta, 1}=\left\{(\mathrm{x}, \mathrm{~s}) \in \mathcal{D}_{\eta}: x_{j(\eta)} \leq c_{\eta}\right\}, \quad \mathcal{D}_{\eta, 2}=\mathcal{D}_{\eta} \backslash \mathcal{D}_{\eta, 1}
$$

for some coordinate $j(\eta) \in\{1, \ldots, p\}$ where $p=\operatorname{dim}(\mathrm{x})$.


## Multivariate Split Rules

- Project $\mathcal{D}_{\eta}$ to $\mathcal{M}$ to obtain $\mathcal{M}_{\eta}$. Partition $\mathcal{M}_{\eta}$ into $\left\{\mathcal{M}_{\eta, 1}, \mathcal{M}_{\eta, 2}\right\}$.



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\mathcal{D}_{\eta, k}=\mathcal{D}_{\eta} \cap\left(\mathcal{M}_{\eta, k} \times \mathcal{X}\right), \quad \text { for } k=1,2
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$s_{h}$

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- Main challenges:
- $\mathcal{M}_{\eta}$ varies with nodes $\eta$ and can be disconnected.
- How to partition $\mathcal{M}_{\eta}$ such that both $\mathcal{D}_{\eta, 1}$ and $\mathcal{D}_{\eta, 2}$ contain non-empty subsets of observations?
- How to partition $\mathcal{M}_{\eta}$ into subsets with flexible shapes while respecting its intrinsic geometry?


## Manifold Bipartitions via Predictive Spanning Trees

- Notations:
- $\mathcal{S}^{*}$ : Reference knots on $\mathcal{M}$.
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Figure: A predictive spanning tree bipartition

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2. Randomly sample two knots $s^{*}$ and $t^{*}$ from $\mathcal{S}_{\eta}^{*}$.
3. Randomly sample an edge $e^{*}$ from the unique path in $\mathcal{G}_{T}^{*}$ connecting $\mathrm{s}^{*}$ and $\mathrm{t}^{*}$.


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## A Bayesian Sum-of-multivariate-decision-trees Model

- Let $T$ denote an sMDT. Define a piecewise constant mapping from $\mathcal{D}$ to $\mathbb{R}$

$$
g(\mathrm{~s}, \mathrm{x} \mid T, \boldsymbol{\mu})=\mu_{j}, \quad \text { if }(\mathrm{s}, \mathrm{x}) \in \mathcal{D}_{j}
$$

- BAMDT models $f(s, x)$ with smmation of piecewise constant functions:

$$
f(\mathrm{~s}, \mathrm{x})=\sum_{m=1}^{M} g\left(\mathrm{~s}, \mathrm{x} \mid T_{m}, \boldsymbol{\mu}_{m}\right)
$$

- Regularization prior:

$$
p\left(\left\{T_{m}, \boldsymbol{\mu}_{m}\right\}_{m=1}^{M}, \sigma^{2}\right)=\left\{\prod_{m=1}^{M} p\left(\boldsymbol{\mu}_{m} \mid T_{m}\right) p\left(T_{m}\right)\right\} p\left(\sigma^{2}\right),
$$

- Generative prior model for $\left\{T_{m}\right\}$ that encourages shallow sMDTs.
- Shrinkage Gaussian prior for $\mu_{m}$.


## Bayesian Inference

- To draw a posterior sample from [ $T_{m} \mid-$ ] with $\boldsymbol{\mu}_{m}$ marginalized out, perform one of the following moves.
- Grow: Randomly choose a terminal node of $T_{m}$ and split it following Step 2 of the sMDT generating process.
- Prune: Randomly choose a node of $T_{m}$ with two terminal nodes and remove it (and its children) from $\mathcal{T}_{m}$.
- Importance metric for a feature $z$ :
- Defined as the proportion of the split rules involving $z$ in the ensemble.
- $z$ can be $s, x_{1}, \ldots$, or $x_{p}$.


## Bitten Torus Example

- Simulate spatially correlated features $\times$ with $p \in\{2,10\}$.
- The true function only depends on $s$ and $x_{1}$.
- When $p=10$, avg. \% of splits involving ( $s, x_{1}$ ) in BAMDT is $73 \%$ (vs 63\% in BART).

Table: Average prediction performance over 50 replicates for $p=10$.

|  | MSPE | MAPE | CRPS |
| :--- | :---: | :---: | :---: |
| BAMDT | 1.17 | 0.62 | 0.49 |
| BART | 2.09 | 0.79 | 0.65 |
| GP-iso | 1.56 | 0.80 | 0.64 |
| GP-aniso | 1.60 | 0.82 | 0.65 |
| BAST-s | 1.61 | 0.81 | 0.59 |
| BAST-KNN | 2.06 | 0.85 | 0.63 |



Figure: True function and predictive surfaces on $\mathcal{M}$ in the setting of $p=2$

## Application to Sacramento Housing Data

- Model $\log$ (housing price) using spatial locations, square footage, \#bedrooms, and \#bathrooms.
- BAMDT provides more accurate prediction than its competing methods based on 5 -fold CV.


Figure: Observed data and predicted price for a representative house.

## Conclusion and Future Work

- A novel Bayesian ensemble model, BAMDT, is developed for nonparametric semi-structured regression problems with complex structured feature spaces using flexible semi-multivariate decision trees as weak learners.
- Next steps:
- Extension to unknown manifolds where geodesic distance metrics need to be estimated.
- Adopting BAMDT as a nonparametric prior model for latent functions in many Bayesian hierarchical modeling settings.
- Theoretical guarantee such as posterior concentration results.


## Thanks!!

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