

Estimating the Optimal Covariance with Imperfect Mean in Diffusion Probabilistic Models

<https://github.com/baoff/Extended-Analytic-DPM>

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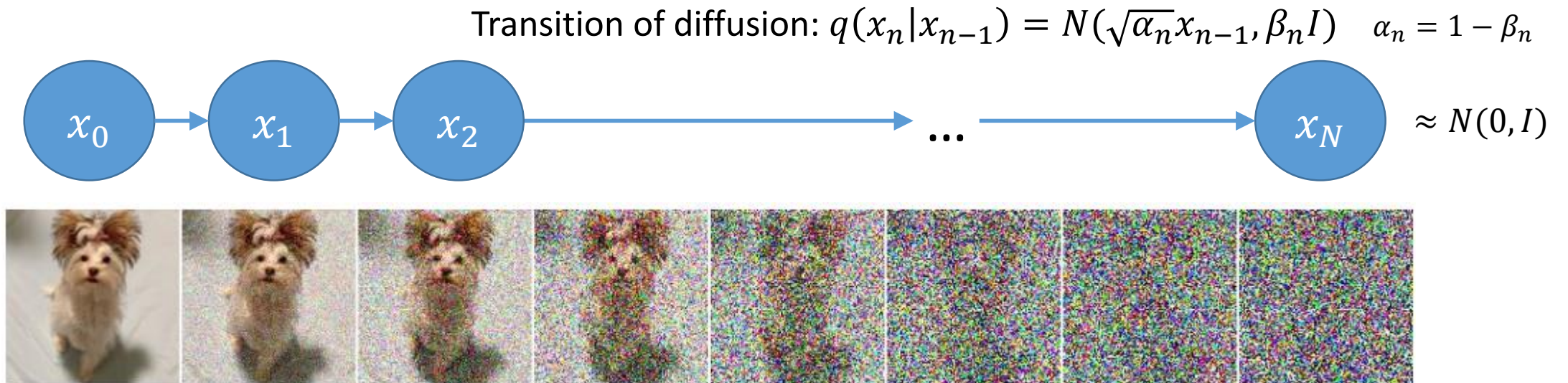
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Diffusion Probabilistic Models (DPMs)

Ho et al. Denoising diffusion probabilistic models (DDPM), Neurips 2020.

Song et al. Score-based generative modeling through stochastic differential equations, ICLR 2021.

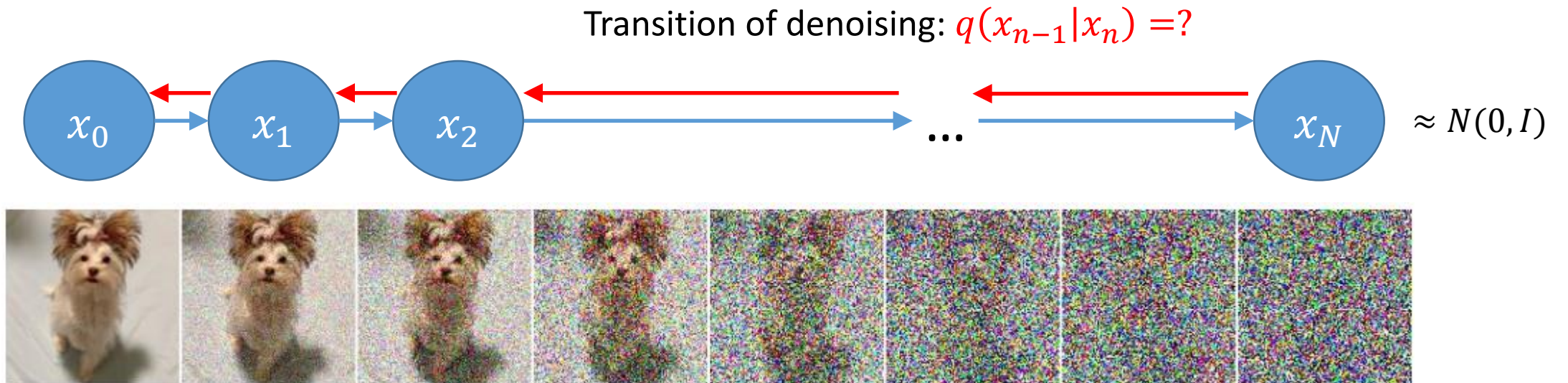
- Diffusion process gradually injects noise to data
- Described by a Markov chain: $q(x_0, \dots, x_N) = q(x_0)q(x_1|x_0) \dots q(x_N|x_{N-1})$



Diffusion process: $q(x_0, \dots, x_N) = q(x_0)q(x_1|x_0) \dots q(x_N|x_{N-1})$

Demo Images from *Song et al. Score-based generative modeling through stochastic differential equations, ICLR 2021.*

- Diffusion process in the reverse direction \Leftrightarrow **denoising process**
- Reverse factorization: $q(x_0, \dots, x_N) = q(x_0|x_1) \dots q(x_{N-1}|x_N)q(x_N)$



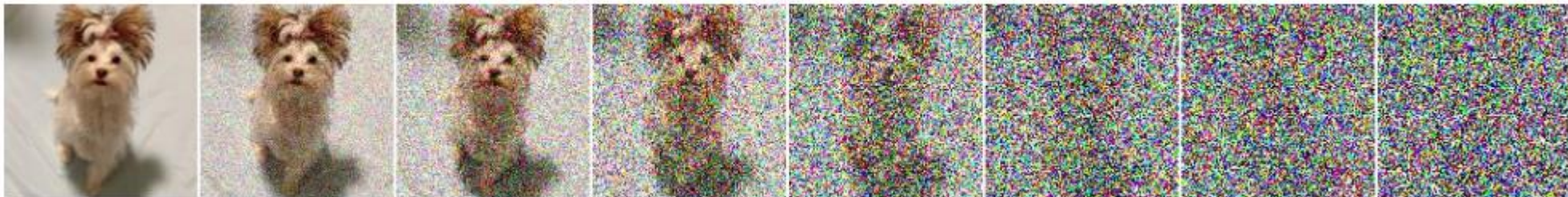
Diffusion process: $q(x_0, \dots, x_N) = q(x_0)q(x_1|x_0) \dots q(x_N|x_{N-1})$
 $= q(x_0|x_1) \dots q(x_{N-1}|x_N)q(x_N)$

- Approximate diffusion process in the reverse direction

Model transition: $p(x_{n-1}|x_n) = N(\mu_n(x_n), \Sigma_n(x_n))$

↓ approximate

Transition of denoising: $q(x_{n-1}|x_n) = ?$



Diffusion process: $q(x_0, \dots, x_N) = q(x_0)q(x_1|x_0) \dots q(x_N|x_{N-1})$
 $= q(x_0|x_1) \dots q(x_{N-1}|x_N)q(x_N)$

The model: $p(x_0, \dots, x_N) = p(x_0|x_1) \dots p(x_{N-1}|x_N)p(x_N)$

- We hope $q(x_0, \dots, x_N) \approx p(x_0, \dots, x_N)$ $p(x_{n-1}|x_n) = N(\mu_n(x_n), \Sigma_n(x_n))$
- Achieved by minimizing their KL divergence (i.e., maximizing the ELBO)

$$\min_{\mu_n(\cdot), \Sigma_n(\cdot)} \text{KL}(q(x_{0:N}) || p(x_{0:N})) \Leftrightarrow \max_{\mu_n(\cdot), \Sigma_n(\cdot)} \mathbf{E}_q \log \frac{p(x_{0:N})}{q(x_{1:N}|x_0)}$$

(Analytic-DPM) Suppose $\Sigma_n(x_n) = \sigma_n^2$. The optimal solution is

$$\mu_n^*(x_n) = \frac{1}{\sqrt{\alpha_n}} \left(x_n - \frac{\beta_n}{\sqrt{\beta_n}} \mathbf{E}_{q(x_0|x_n)}[\epsilon_n] \right),$$

Noise prediction network:

$$\hat{\epsilon}_n(x_n) \approx \mathbf{E}_{q(x_0|x_n)}[\epsilon_n]$$

$$\sigma_n^{*2} = \frac{\beta_n}{\alpha_n} \left(1 - \frac{\beta_n}{\beta_n} \mathbf{E}_{q_n(x_n)} \frac{\|\mathbf{E}_{q(x_0|x_n)}[\epsilon_n]\|^2}{d} \right).$$

- Isotropic variance is simple
- Irrelevant to state x_n
- Assume the mean is optimal

Bao et al. Analytic-DPM: an Analytic Estimate of the Optimal Reverse Variance in Diffusion Probabilistic Models, ICLR 2022.

Estimating the Optimal Covariance with Imperfect Mean in Diffusion Probabilistic Models

- What is the optimal diagonal covariance $\Sigma_n(x_n) = \text{diag}(\sigma_n^2(x_n))$?

Theorem 1. Suppose $\Sigma_n(x_n) = \text{diag}(\sigma_n^2(x_n))$. The optimal solution is

$$\mu_n^*(x_n) = \frac{1}{\sqrt{\alpha_n}} \left(x_n - \frac{\beta_n}{\sqrt{\beta_n}} \mathbf{E}_{q(x_0|x_n)}[\epsilon_n] \right),$$

$$\sigma_n^*(x_n)^2 = \frac{\bar{\beta}_{n-1}}{\bar{\beta}_n} \beta_n + \frac{\beta_n^2}{\bar{\beta}_n \alpha_n} \left(\underbrace{\mathbf{E}_{q(x_0|x_n)}[\epsilon_n^2]}_{\approx h_n(x_n)} - \underbrace{\mathbf{E}_{q(x_0|x_n)}[\epsilon_n]^2}_{\approx \hat{\epsilon}_n(x_n)^2} \right).$$

$$\approx h_n(x_n) \qquad \approx \hat{\epsilon}_n(x_n)^2$$

predict SN: $\min_{h_n} \mathbf{E}_{q(x_0, x_n)} \|h_n(x_n) - \epsilon_n^2\|^2$
 squared noise (SN)

See a more general version of Theorem 1 for more general $q(x_{0:N})$ in the full paper
 See extension to score-based SDE (Song et al.) in the full paper

- In practice, $\hat{\epsilon}_n(x_n)$ and $\mu_n(x_n)$ are not optimal
- What is the optimal diagonal covariance $\Sigma_n(x_n) = \text{diag}(\sigma_n^2(x_n))$?

Theorem 2. Suppose $\Sigma_n(x_n) = \text{diag}(\sigma_n^2(x_n))$. For any mean $\mu_n(x_n)$ parameterized by $\hat{\epsilon}_n(x_n)$, the optimal covariance is

$$\tilde{\sigma}_n^*(x_n)^2 = \frac{\bar{\beta}_{n-1}}{\bar{\beta}_n} \beta_n + \frac{\beta_n^2}{\bar{\beta}_n \alpha_n} \mathbf{E}_{q(x_0|x_n)} \left[(\epsilon_n - \hat{\epsilon}_n(x_n))^2 \right].$$

$$\approx g_n(x_n)$$



predict NPR: $\min_{g_n} \mathbf{E}_{q(x_0, x_n)} \left\| h_n(x_n) - \boxed{(\epsilon_n - \hat{\epsilon}_n(x_n))^2} \right\|^2$

noise prediction residual (NPR):

Experimental Results

- Likelihood results
- NPR-DPM (predicting NPR) consistently outperforms Analytic-DPM

		CIFAR10 (LS)						CIFAR10 (CS)					
# TIMESTEPS K		10	25	50	100	200	1000	10	25	50	100	200	1000
ET	DDPM, $\tilde{\beta}_n$	74.95	24.98	12.01	7.08	5.03	3.73	75.96	24.94	11.96	7.04	4.95	3.60
	DDPM, β_n	6.99	6.11	5.44	4.86	4.39	3.75	6.51	5.55	4.92	4.41	4.03	3.54
	A-DDPM	5.47	4.79	4.38	4.07	3.84	3.59	5.08	4.45	4.09	3.83	3.64	3.42
	NPR-DDPM	5.40	4.64	4.25	3.98	3.79	3.57	5.03	4.33	3.99	3.76	3.59	3.41
OT	DDPM, β_n	5.38	4.34	3.97	3.82	3.77	3.75	5.51	4.30	3.86	3.65	3.57	3.54
	A-DDPM	4.11	3.68	3.61	3.59	3.59	3.59	3.99	3.56	3.47	3.44	3.43	3.42
	NPR-DDPM	3.91	3.64	3.59	3.58	3.57	3.57	3.88	3.52	3.45	3.42	3.41	3.41

		CELEBA 64X64						IMAGENET 64X64					
# TIMESTEPS K		10	25	50	100	200	1000	25	50	100	200	400	4000
ET	DDPM, $\tilde{\beta}_n$	33.42	13.09	7.14	4.60	3.45	2.71	105.87	46.25	22.02	12.10	7.59	3.89
	DDPM, β_n	6.67	5.72	4.98	4.31	3.74	2.93	5.81	5.20	4.70	4.31	4.04	3.65
	A-DDPM	4.54	3.89	3.48	3.16	2.92	2.66	4.78	4.42	4.15	3.95	3.81	3.61
	NPR-DDPM	4.46	3.78	3.40	3.11	2.89	2.65	4.66	4.22	3.96	3.80	3.71	3.60
OT	DDPM, β_n	4.76	3.58	3.16	2.99	2.94	2.93	4.56	4.09	3.84	3.73	3.68	3.65
	A-DDPM	2.97	2.71	2.67	2.66	2.66	2.66	3.83	3.70	3.64	3.62	3.62	3.61
	NPR-DDPM	2.88	2.69	2.66	2.66	2.65	2.65	3.73	3.65	3.62	3.60	3.60	3.60

- Sample quality results (FID)
- Both NPR-DPM & SN-DPM outperform Analytic-DPM

# TIMESTEPS K	CIFAR10 (LS)						CIFAR10 (CS)					
	10	25	50	100	200	1000	10	25	50	100	200	1000
DDPM, $\tilde{\beta}_n$	44.45	21.83	15.21	10.94	8.23	5.11	34.76	16.18	11.11	8.38	6.66	4.92
DDPM, β_n	233.41	125.05	66.28	31.36	12.96	3.04	205.31	84.71	37.35	14.81	5.74	3.34
A-DDPM	34.26	11.60	7.25	5.40	4.01	4.03	22.94	8.50	5.50	4.45	4.04	4.31
NPR-DDPM	32.35	10.55	6.18	4.52	3.57	4.10	19.94	7.99	5.31	4.52	4.10	4.27
SN-DDPM	24.06	6.91	4.63	3.67	3.31	3.65	16.33	6.05	4.17	3.83	3.72	4.07
DDIM	21.31	10.70	7.74	6.08	5.07	4.13	34.34	16.68	10.48	7.94	6.69	4.89
A-DDIM	14.00	5.81	4.04	3.55	3.39	3.74	26.43	9.96	6.02	4.88	4.92	4.66
NPR-DDIM	13.34	5.38	3.95	3.53	3.42	3.72	22.81	9.47	6.04	5.02	5.06	4.62
SN-DDIM	12.19	4.28	3.39	3.23	3.22	3.65	17.90	7.36	5.16	4.63	4.63	4.51

# TIMESTEPS K	CELEBA 64X64						IMAGENET 64X64					
	10	25	50	100	200	1000	25	50	100	200	400	4000
DDPM, $\tilde{\beta}_n$	36.69	24.46	18.96	14.31	10.48	5.95	29.21	21.71	19.12	17.81	17.48	16.55
DDPM, β_n	294.79	115.69	53.39	25.65	9.72	3.16	170.28	83.86	45.04	28.39	21.38	16.38
A-DDPM	28.99	16.01	11.23	8.08	6.51	5.21	32.56	22.45	18.80	17.16	16.40	16.34
NPR-DDPM	28.37	15.74	10.89	8.23	7.03	5.33	28.27	20.89	18.06	16.96	16.32	16.38
SN-DDPM	20.60	12.00	7.88	5.89	5.02	4.42	27.58	20.74	18.04	16.61	16.37	16.22
DDIM	20.54	13.45	9.33	6.60	4.96	3.40	26.06	20.10	18.09	17.84	17.74	19.00
A-DDIM	15.62	9.22	6.13	4.29	3.46	3.13	25.98	19.23	17.73	17.49	17.44	18.98
NPR-DDIM	14.98	8.93	6.04	4.27	3.59	3.15	28.84	19.62	17.63	17.42	17.30	18.91
SN-DDIM	10.20	5.48	3.83	3.04	2.85	2.90	28.07	19.38	17.53	17.23	17.23	18.89

- Sample quality results (FID)
- Both NPR-DPM & SN-DPM outperform Analytic-DPM

# TIMESTEPS K	CIFAR10 (VP SDE)					
	10	25	50	100	200	1000
EULER-MARUYAMA	292.20	170.17	90.79	47.46	21.92	2.55
ANCESTRAL SAMPLING	235.28	129.29	68.52	31.99	12.81	2.72
PROBABILITY FLOW	107.74	21.34	7.78	4.33	3.27	2.82
A-DPM	35.10	11.57	6.54	4.71	3.61	2.98
NPR-DPM	33.70	10.44	5.83	3.97	3.05	3.04
SN-DPM	25.30	7.34	4.46	3.27	2.83	2.71

Thanks!