

Agnostic Learnability of Halfspaces via Logistic Loss

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Problem setting

Comparison of prior results and our results

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we have i.i.d. samples from P .
- ▶ Goal: compete with the optimal linear classifier \bar{u} with zero-one/misclassification risk $\text{OPT} > 0$ over P , i.e.,

$$\mathcal{R}_{0-1}(\bar{u}) := \Pr_{(x,y) \sim P} (\text{sign}(\langle \bar{u}, x \rangle) \neq y) = \text{OPT}.$$

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Logistic regression

A natural heuristic is logistic regression.

Notation: let $\ell_{\log}(z) := \ln(1 + e^{-z})$, and let

$$\mathcal{R}_{\log}(w) := \mathbb{E}_{(x,y) \sim P} [\ell_{\log}(y \langle w, x \rangle)]$$

denote the population logistic risk of w over P .

We can sample a training set and minimize the empirical risk, or have a sequence of samples and run stochastic optimization.

Prior lower and upper bounds for logistic regression

Known upper and lower bounds don't match:

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- ▶ standard concentration and anti-concentration conditions;
- ▶ a mixture of log-concave distributions (e.g., a Gaussian mixture) is a nice example.

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Q. Can we close these gaps? → precise scope of this work!

Our lower and upper bounds for logistic regression

- ▶ $\Omega(\sqrt{\text{OPT}})$ lower bound for “well-behaved” sub-exponential distributions;
matching $\tilde{O}(\sqrt{\text{OPT}})$ upper bound from (Frei et al., 2021).

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matching $\tilde{O}(\sqrt{\text{OPT}})$ upper bound from (Frei et al., 2021).
- ▶ $\tilde{O}(\text{OPT})$ upper bound with additional “radial Lipschitzness.”

Upper bounds beyond logistic regression

- ▶ Diakonikolas et al. (2020) designed a nonconvex SGD method that achieves $O(\text{OPT}) + \epsilon$ risk using $\tilde{O}(d/\epsilon^4)$ samples. They can also handle heavy-tailed distributions.

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- ▶ Other prior algorithms achieving $O(\text{OPT}) + \epsilon$ risk involve solving multiple rounds of convex program (Awasthi et al., 2014; Daniely, 2015).
- ▶ We design a simple two-phase convex program (logistic regression followed by Perceptron) that achieves $O(\text{OPT} \ln(1/\text{OPT})) + \epsilon$ risk using $\tilde{O}(d/\epsilon^2)$ samples.

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Our $\Omega(\sqrt{\text{OPT}})$ lower bound

Theorem

There exists a distribution on $\mathbb{R}^2 \times \{-1, +1\}$, such that:

- ▶ *the feature distribution is isotropic and a mixture of log-concave distributions;*
- ▶ *the population logistic risk \mathcal{R}_{\log} has a global minimizer w^* with*

$$\mathcal{R}_{0-1}(w^*) = \Omega(\sqrt{\text{OPT}}).$$

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$$\mathcal{R}_{0-1}(w^*) = \Omega(\sqrt{\text{OPT}}).$$

- ▶ Matches $\tilde{O}(\sqrt{\text{OPT}})$ upper bound from (Frei et al., 2021).

Our $\tilde{O}(\text{OPT})$ upper bound under radial Lipschitzness

Assumption

There exists a measurable function $\kappa : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ such that for any two-dimensional subspace V , letting p_V denote the density of the projection of feature distribution onto V , then

$$|p_V(r, \theta) - p_V(r, \theta')| \leq \kappa(r)|\theta - \theta'|.$$

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- ▶ Holds if p_V is Lipschitz continuous (e.g., Gaussian mixtures).
- ▶ Does not hold for general log-concave distributions.

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Theorem

If the distribution is well-behaved, sub-exponential and radially-Lipschitz, then with learning rate $\tilde{\Theta}(1/d)$, using $\text{poly}(d, 1/\epsilon, \ln(1/\delta))$ samples and iterations, with probability $1 - \delta$, projected gradient descent outputs w_t with

$$\mathcal{R}_{0-1}(w_t) = \tilde{O}(\text{OPT}) + \epsilon.$$

Why radial Lipschitzness?

Lemma

If the distribution is well-behaved, sub-exponential and radially-Lipschitz, and suppose \hat{w} satisfies

$\mathcal{R}_{\log}(\hat{w}) \leq \mathcal{R}_{\log}(\|\hat{w}\|\bar{u}) + \epsilon'$, then

$$\mathcal{R}_{0-1}(\hat{w}) = \tilde{O} \left(\max \left\{ \text{OPT}, \sqrt{\frac{\epsilon'}{\|\hat{w}\|}}, \frac{C_{\kappa}}{\|\hat{w}\|^2} \right\} \right).$$

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- ▶ $C_{\kappa} = O(\ln(1/\text{OPT})^2)$ for Lipschitz continuous density.
- ▶ We can find \hat{w} with small ϵ' with PGD; $\|\hat{w}\| = \tilde{\Omega} \left(1/\sqrt{\text{OPT}} \right)$.

Our $\tilde{O}(\text{OPT})$ upper bound: two-phase algorithm

Key observation: the lemma holds for the hinge loss $\ell_h(z) := \max\{-z, 0\}$ **without** radial Lipschitzness!

Lemma

For **hinge loss**, if the distribution is well-behaved and sub-exponential, and suppose \hat{w} satisfies $\mathcal{R}_h(\hat{w}) \leq \mathcal{R}_h(\|\hat{w}\|\bar{u}) + \epsilon'$, then

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But, we are not quite done since the global minimizer of \mathcal{R}_h is 0...

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Ideas:

- ▶ first find a unit v that is $\tilde{O}(\sqrt{\text{OPT}})$ away from \bar{u} ;
- ▶ then minimize \mathcal{R}_h over $\mathcal{D} := \{w \mid \langle w, v \rangle \geq 1\}$.

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- ▶ then minimize \mathcal{R}_h over $\mathcal{D} := \{w \mid \langle w, v \rangle \geq 1\}$.
 - ▶ $\forall w \in \mathcal{D}, \|w\| \geq 1$.
 - ▶ $\|\hat{w}\|\bar{u}$ may not be in \mathcal{D} , but $(1 + \tilde{O}(\text{OPT}))\|\hat{w}\|\bar{u} \in \mathcal{D}$!
Since we choose v close to \bar{u} .

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Our $\tilde{O}(\text{OPT})$ upper bound: two-phase algorithm

Another ingredient: when minimizing hinge loss, we use SGD (instead of GD) for sample efficiency; basically it's **Perceptron** with a restricted domain and warm start given by v .

Theorem

If the distribution is well-behaved and sub-exponential, using $\tilde{O}(d/\epsilon^2)$ samples, SGD can achieve zero-one risk $O(\text{OPT} \ln(1/\text{OPT})) + \epsilon$.

Thanks, please come to our poster!