

A Random Matrix Analysis of Data Stream Clustering: Coping With Limited Memory Resources

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Random matrix framework for data stream clustering

- Observed data: $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_t, \dots \in \mathbb{R}^p$

$$\mathbf{x}_t \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\pm\boldsymbol{\mu}, \mathbf{I}_p)$$

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- Memory

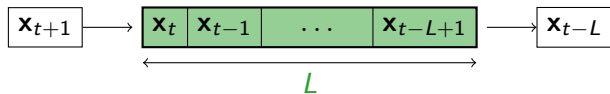
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- Clustering** on the $n \geq L$ previous points

$$\mathbf{X} = [\mathbf{x}_{t-n+1} \quad \mathbf{x}_{t-n+2} \quad \dots \quad \mathbf{x}_t] \in \mathbb{R}^{p \times n}$$

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$$p/n \rightarrow c$$

$$(2L-1)/n \rightarrow \varepsilon$$

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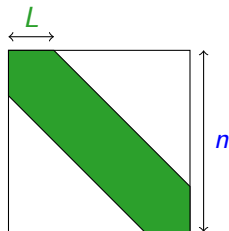
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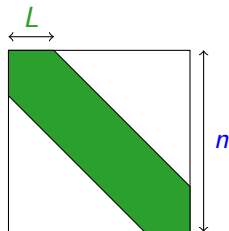
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$$\mathbf{K} = \frac{\mathbf{X}^T \mathbf{X}}{p}$$

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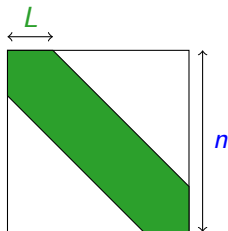
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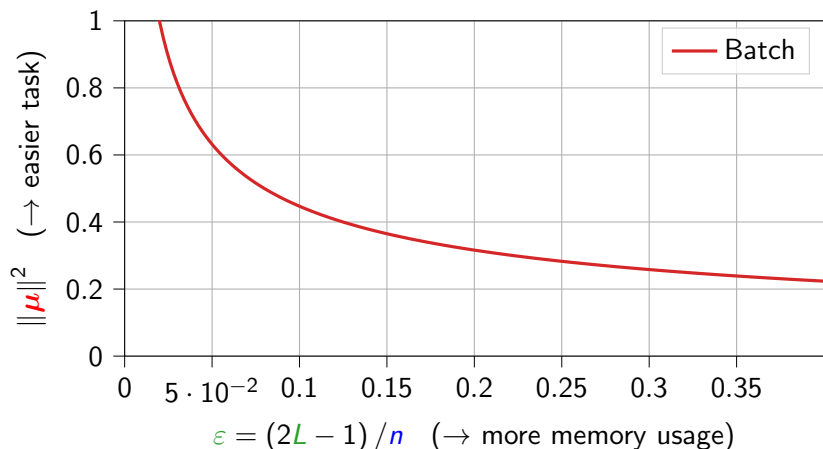
$$\mathbf{K}_L = \frac{\mathbf{X}^T \mathbf{X}}{p} \odot \underbrace{\begin{bmatrix} 1 & \dots & 1 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 1 & \dots & \vdots & 1 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \dots & 1 & \dots & 1 \end{bmatrix}}_{\mathbf{T}}$$

Data stream clustering: improving over batch clustering

- Size- L memory \rightsquigarrow *batch clustering* vs. $\mathbf{K}_L = \frac{1}{p} \mathbf{X}^\top \mathbf{X} \odot \mathbf{T}$

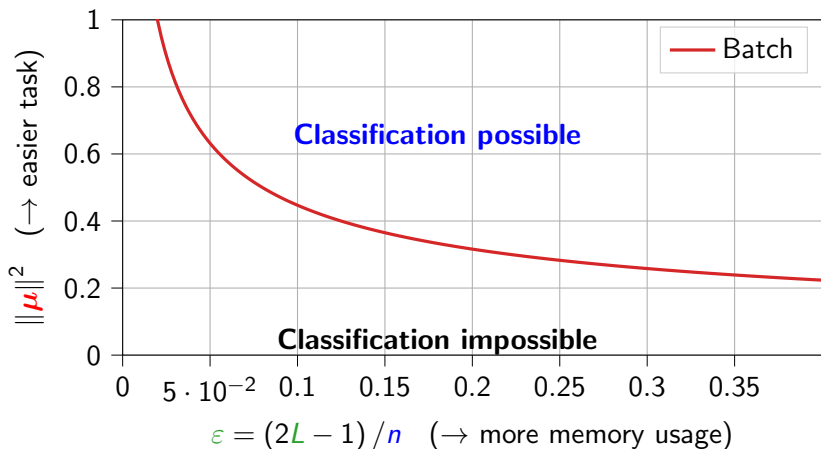
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- Spectral clustering phase transition ($n/p = 100 \iff c = 0.01$)



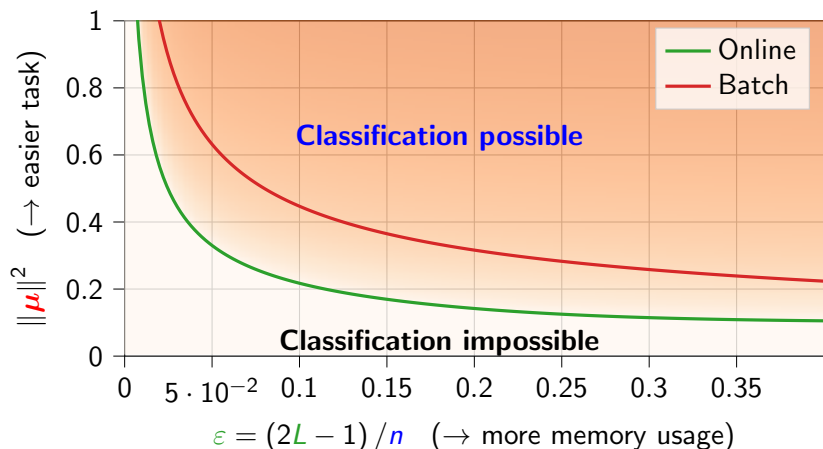
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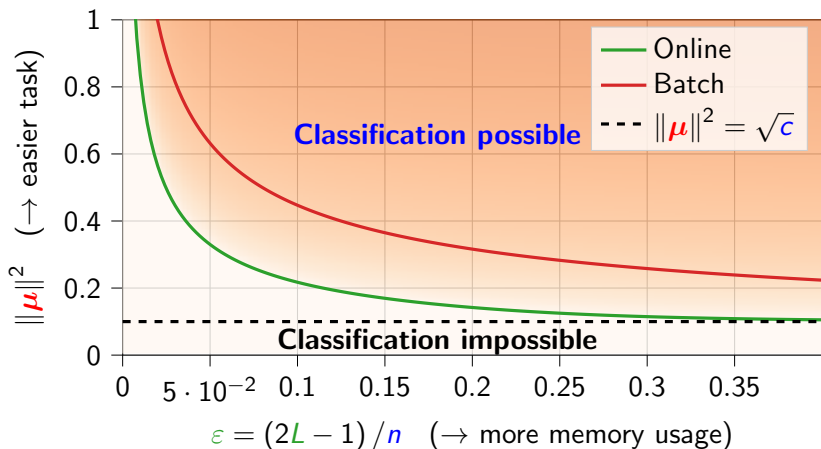
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From theory to practice: online kernel spectral clustering

- **BigGAN images** (VGG features, $p = 4\,096$)

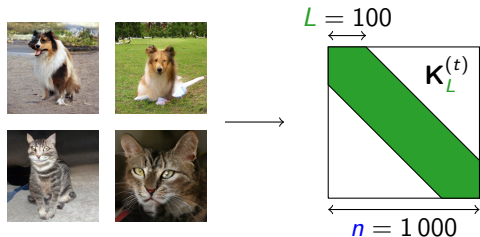
$T = 20\,000$



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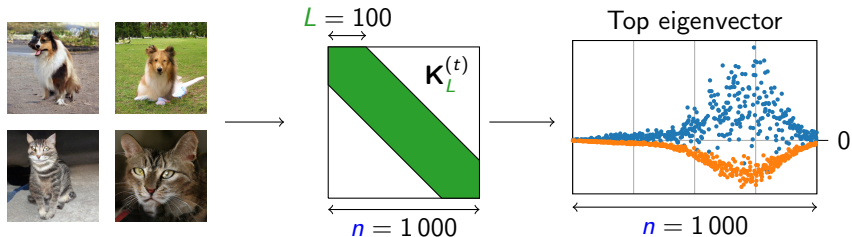
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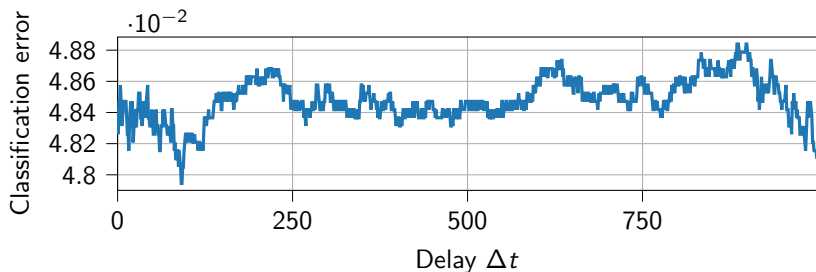
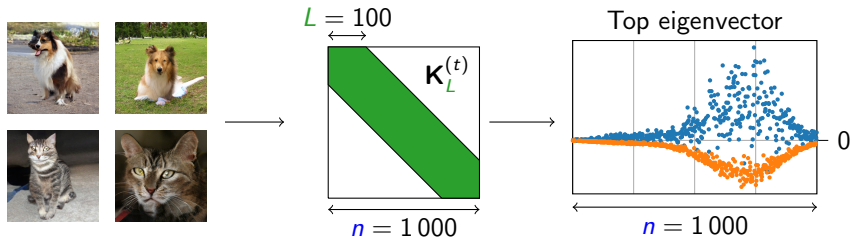
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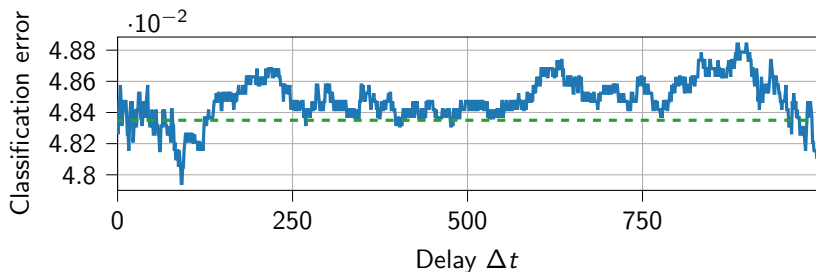
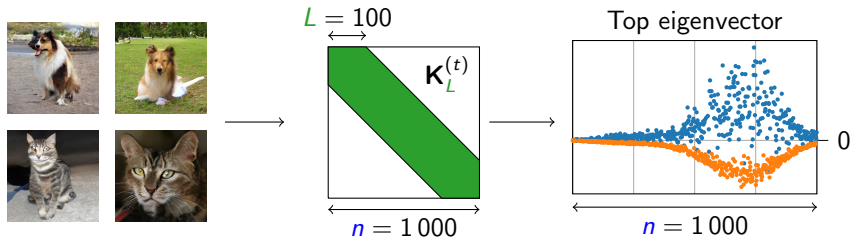
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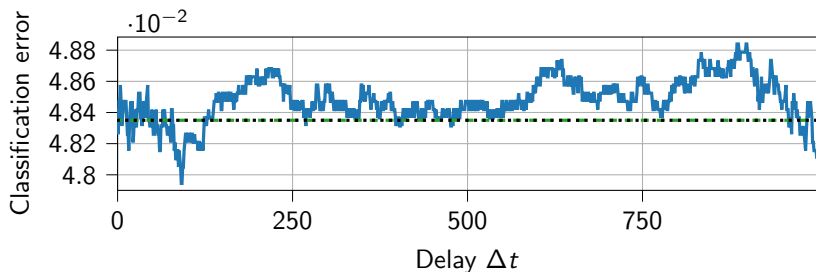
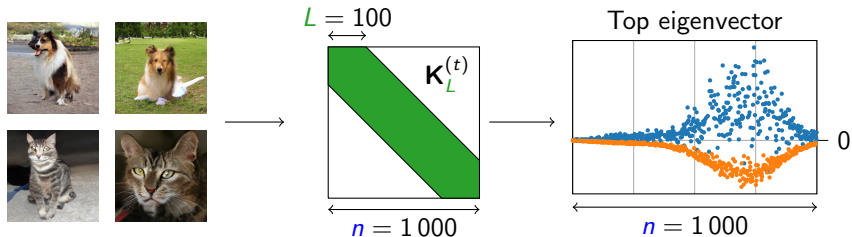
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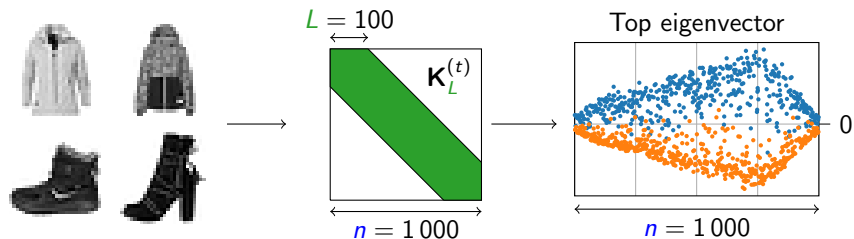
$T = 20\,000$



From theory to practice: online kernel spectral clustering

- Fashion-MNIST images (raw, $p = 784$)

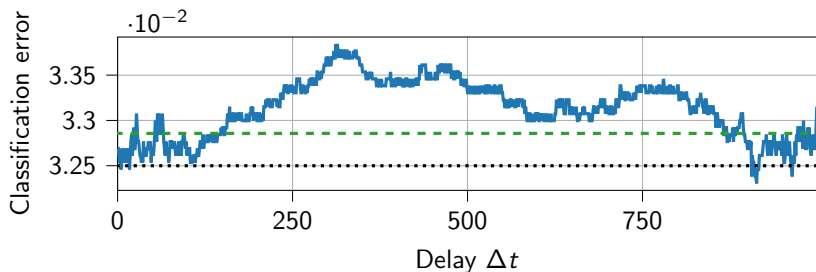
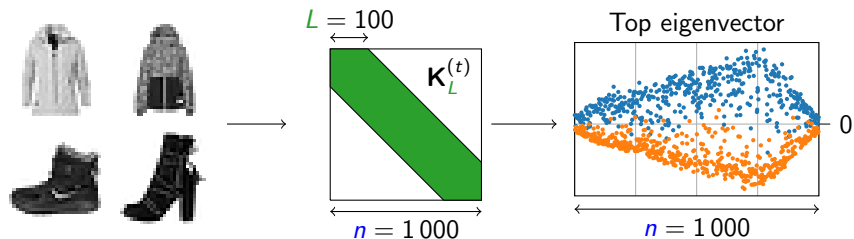
$T = 14\,000$



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