

Improved Rates for Differentially Private Stochastic Convex Optimization with Heavy-Tailed Data

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Problem formulation

Stochastic convex optimization (SCO)

A fundamental optimization problem in machine learning.

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Goal: given n i.i.d. samples from an unknown distribution \mathcal{D} , find \hat{w} to minimize

$$L_{\mathcal{D}}(\hat{w}) - \min_{w^* \in \mathcal{W}} L_{\mathcal{D}}(w^*).$$

Data may contain **sensitive** information.



(a) Navigation



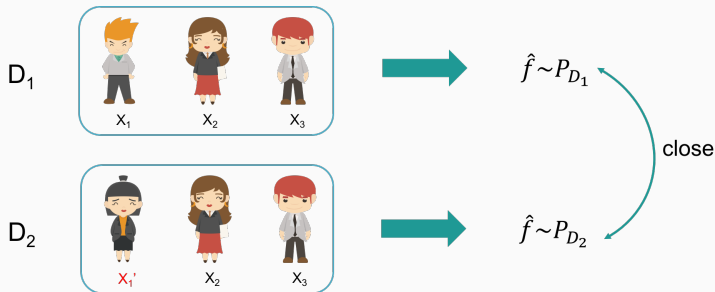
(b) Medical data

We want to protect the privacy while learning from samples.

Differential privacy (DP) [Dwork et al., 2006]

\hat{f} is (ϵ, δ) -DP for any D_1 and D_2 , with $d_{Ham}(D_1, D_2) \leq 1$, for all measurable S ,

$$\forall S, \Pr(\hat{f}(D_1) \in S) \leq e^\epsilon \cdot \Pr(\hat{f}(D_2) \in S) + \delta.$$



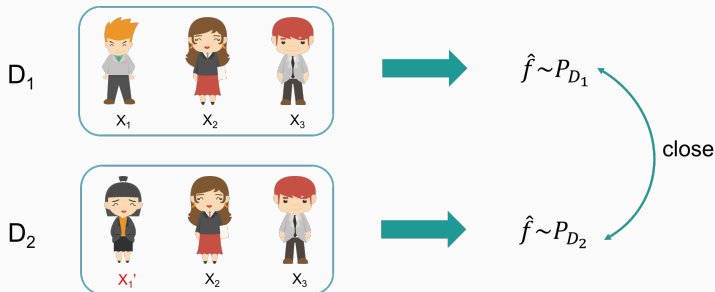
Pure DP: $\delta = 0$; **approximate DP:** $\delta \neq 0$

Concentrated Differential Privacy [Bun and Steinke, 2016]

\hat{f} is ϵ^2 -CDP if for any D_1 and D_2 , with $d_{Ham}(D_1, D_2) \leq 1$,

$$\forall \alpha \in (1, \infty), D_\alpha(\hat{f}(D_1), \hat{f}(D_2)) \leq \epsilon^2 \alpha,$$

where $D_\alpha(\hat{f}(D_1), \hat{f}(D_2))$ is the α -Rényi divergence.



ϵ^2 -CDP lies between $(O(\epsilon), 0)$ -DP and $(O(\epsilon), \delta)$ -DP.

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Let \mathcal{D} be a distribution over \mathbb{R}^d . We assume for every $w \in W$,

$$\mathbb{E}_{x \in \mathcal{D}} \left[|\langle \nabla\ell(w, x), e_j \rangle|^k \right] \leq 1, \forall j \in [d],$$

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- $k = 2$ throughout this talk.

CDP SCO with heavy-tailed gradients

Goal: given n i.i.d. samples from an unknown distribution \mathcal{D} , and the gradient distribution satisfying the heavy-tailed assumption, we want to design a ε^2 -CDP algorithm w^{priv} that minimizes

$$L_{\mathcal{D}}(w^{priv}) - \min_{w^* \in \mathcal{W}} L_{\mathcal{D}}(w^*).$$

Results

Convex setting:

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- Tight up to a logarithmic factor.

Our techniques

- Given n i.i.d. samples from an unknown heavy-tailed distribution \mathcal{D} over \mathbb{R}^d , privately estimate the distribution mean under ℓ_2 distance.

CDP mean estimation

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- ε -DP result: $\Theta\left(\sqrt{\frac{d}{n}} + \frac{d}{\sqrt{\varepsilon n}}\right)$.
- A new separation between pure DP and approximate DP!

CDP mean estimation (upper bound)

- We generalize the idea and analysis from [Kamath et al., 2020], which has a slightly different assumption.

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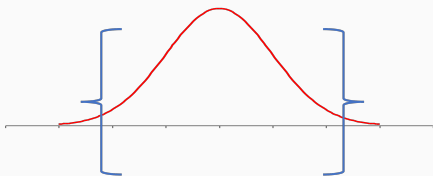
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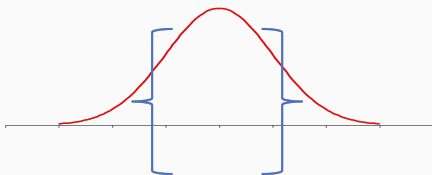
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- Smaller clipping range leads to larger bias and less variance.
- Wisely select the clipping range to balance the bias and variance!

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Theorem (privacy)

Our CDP SCO algorithm satisfies ϵ^2 -CDP suppose the mean estimation oracle satisfies ϵ^2/T -CDP.

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Proof: DP post-processing and composition.

Theorem (utility, informal)

Suppose the mean estimation oracle guarantees that the bias is smaller than B and the variance is smaller than G^2 , the algorithm outputs w^{priv} such that

$$\mathbb{E} [L_{\mathcal{D}}(w^{priv}) - L_{\mathcal{D}}(w^*)] \leq O\left(\frac{1}{\sqrt{T}} + \frac{G^2}{\sqrt{T}} + B\right).$$

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- Setting $G = B$ leads to the optimal performance for one single round.
- However, it is sub-optimal for CDP SCO.
- Instead we set $B = \frac{G^2}{\sqrt{T}}$ to balance the second and third terms.

- Following a similar argument in [Bassily et al., 2014], we reduce CDP mean estimation to CDP SCO.

CDP SCO lower bound

- Following a similar argument in [Bassily et al., 2014], we reduce CDP mean estimation to CDP SCO.
- We propose CDP Fano's inequality, generalizing the results in [Acharya et al., 2021] and [Bun and Steinke, 2016].

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Theorem (ε^2 -CDP Fano's inequality)

Let $\mathcal{V} = \{p_1, \dots, p_M\}$ be a set of distributions, θ be a parameter of interest, and ℓ be a loss function. Suppose for all $i \neq j$, it satisfies (a) $\ell(\theta(p_i), \theta(p_j)) \geq r$, (b) $d_{TV}(p_i, p_j) \leq \alpha$. Then for any ε^2 -CDP estimator $\hat{\theta}$,

$$\frac{1}{M} \sum_{i \in [M]} \mathbb{E} \left[\ell(\hat{\theta}(X), \theta(p_i)) \right] \geq \frac{r}{2} \left(1 - \frac{\varepsilon^2(n^2\alpha^2 + n\alpha(1 - \alpha)) + \log 2}{\log M} \right).$$

The End

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