# Expression might be enough: representing pressure and demand for reinforcement learning based traffic signal control

#### **ICML 2022**

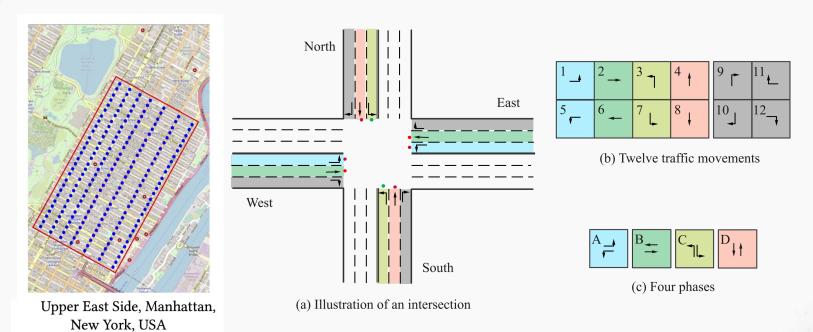
Liang Zhang<sup>1</sup>, Qiang Wu<sup>2\*</sup>, Jun Shen<sup>3</sup>, Linyuan Lü<sup>2</sup>, Bo Du<sup>4</sup>, Jianqing Wu<sup>5</sup>

<sup>1</sup>School of Life Sciences, Lanzhou University, Lanzhou, China
<sup>2</sup>Institute of Fundamental and Frontier Sciences, University of Electronic Science and Technology of China, Chengdu, China
<sup>3</sup>School of Computing and Information Technology, University of Wollongong, Wollongong, Australia
<sup>4</sup>SMART Infrastructure Facility, University of Wollongong, Wollongong, Australia
<sup>5</sup>School of Information Engineering, Jiangxi University of Science and Technology

# **Traffic Signal Control**

Cite [Wei et al., 2019a]

Traffic signal control aims to maximize the throughput and minimize the average travel time of all the vehicles.



# **Related Works -- Typical Traditional Methods**

SOTL [Cools et al., 2013]

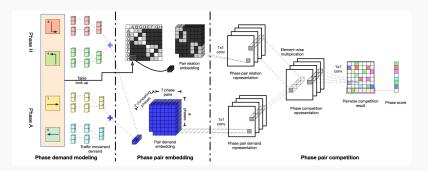
## **Self Organizing Traffic Lights**

```
Input: minimal phase duration t_{min}; threshold \theta and \mu; distance \omega
Parameters: vehicle counter c_i^r and c_i^g; records of time step t_{step}
for (time step) do
   if (t_{step}>t_{min}) then
      c_i^r = vehicles approaching red phase
      c_i^g = vehicles approaching green phase within \omega
      if not (0 < c_i^r < \mu) then
          if (c_i^r > \theta) then
             switch light;
          end if
      end if
   end if
end for
```

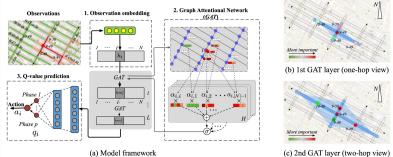
Max Pressure [Varaiya 2013] Efficient-MP [Wu et al., 2021] North East CIG CIG CIG CIG West South

## Related Works -- Recent RL Methods

#### FRAP [Zheng et al. 2019]



#### CoLight [Wei et al. 2019a]



#### PressLight [Wei et al. 2019b]

PressLight introduces pressure into the state and reward design.

#### Efficient-XLight [Wu et al. 2021]

Efficient-XLight proposes efficient traffic movement pressure and adopts it as an effective state representation.

# **Advanced-XLight**

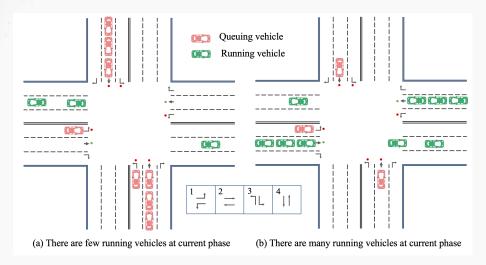
#### Main idea

Pay attention to both moving and waiting vehicles, find a trad-off to determine whether to maintain or change current signal phase.

#### **Main Contribution**

- Propose a novel traditional method Advanced Max-Pressure
- Propose a novel RL template Advanced-XLight

# **Advanced-XLight -- Definitions**



#### **Effective range**

The effective range is the maximum distance to the intersection that a vehicle can pass through within  $t_{duration}$ 

#### Effective running vehicle number

The effective running vehicle number is the number of running vehicles of the incoming lanes within the effective range to the intersection

## **Traffic movement pressure**

The average queue length between upstream and downstream

#### **Phase demand**

The demand of each phase is the sum of the effective running vehicle number from the phase

# **Advanced-XLight**

#### Algorithm 1 Advanced Max-Pressure control **Parameter**: time t = 0, action duration $t_{duration}$ , weights $W_1$ , current phase $a_{cur}$ For each intersection, get p(s) $a_{cur} = \arg\max(p(s)|, s \in \mathcal{S}_i)$ for (time-step) do t = t + 1if $t = t_{duration}$ then For each intersection, get p(s) and d(s)if $d(a_{cur}) \times W_1 > max\{p(s)\}$ then Maintain the current phase else $a_{cur} = \arg\max(p(s)|, s \in \mathcal{S}_i)$ end if Set the phase as $a_{cur}$ . t=0end if end for

## **Advanced Traffic State (ATS)**

The traffic movement pressure and effective running vehicle number are proposed as ATS

#### **Advanced-XLight**

```
Parameter: current phase time t, action duration t_{duration} for (time step) do

t = t+1

if (t=t_{duration}) then

Get ATS for each intersection

Set the phase by X RL model

t=0

end if
end for
```

## **Advanced-MPLight**

Based on the framework of MPLight, using current phase and ATS as the state

## **Advanced-CoLight**

Based on the framework of CoLight, using current phase and ATS as the state

# **Experiments**

| Method            | JiNan  |        |        | HangZhou |        | New York |
|-------------------|--------|--------|--------|----------|--------|----------|
|                   | 1      | 2      | 3      | 1        | 2      | 1        |
| FixedTime         | 428.11 | 368.77 | 383.01 | 495.57   | 406.65 | 1507.12  |
| MaxPressure       | 273.96 | 245.38 | 245.81 | 288.54   | 348.98 | 1179.55  |
| Efficient-MP      | 269.87 | 239.75 | 240.03 | 284.44   | 327.62 | 1122.00  |
| MPLight           | 297.46 | 270.05 | 276.15 | 314.60   | 357.61 | 1321.40  |
| CoLight           | 272.06 | 252.44 | 249.56 | 297.02   | 347.27 | 1065.64  |
| AttendLight       | 277.53 | 250.29 | 248.82 | 293.89   | 345.72 | 1586.09  |
| PRGLight          | 291.27 | 257.52 | 261.74 | 301.06   | 369.98 | 1283.37  |
| Efficient-MPLight | 261.81 | 241.35 | 238.80 | 284.49   | 321.08 | 1301.83  |
| Efficient-CoLight | 256.84 | 239.58 | 236.72 | 282.07   | 324.27 | 1032.11  |
| Advanced-MP       | 253.61 | 238.62 | 235.21 | 279.47   | 318.67 | 1060.41  |
| Advanced-MPLight  | 251.29 | 234.78 | 231.76 | 273.26   | 312.68 | 1198.64  |
| Advanced-CoLight  | 245.73 | 232.63 | 229.01 | 270.45   | 310.74 | 970.05   |

Table 1. Overall comparison. For average travel time, the smaller the better.

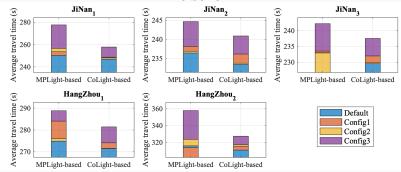


Figure 2. Model performance under different observation ranges.

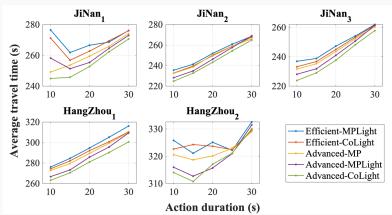


Figure 1. Model performance under different action duration.

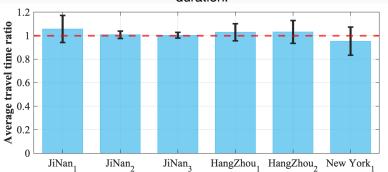
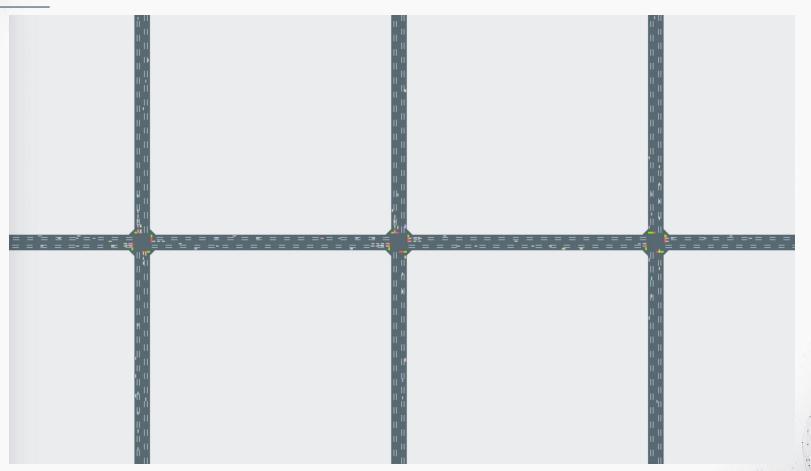


Figure 3. The transferability of Advanced-MPLight.

# **Instance Demonstration**



## Reference

[Wu et al., 2021] Wu Q, Zhang L, Shen J, et al. Efficient Pressure: Improving efficiency for signalized intersections[J]. arXiv preprint arXiv:2112.02336, 2021.

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