

Near-Exact Recovery for Tomographic Inverse Problems via Deep Learning



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Helmholtz-Zentrum Berlin

(work done while at
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TU Berlin

(Machine Learning Group)



Jan Macdonald

TU Berlin

(Institute of Mathematics)



Maximilian März

TU Berlin

(Institute of Mathematics)



Utrecht University

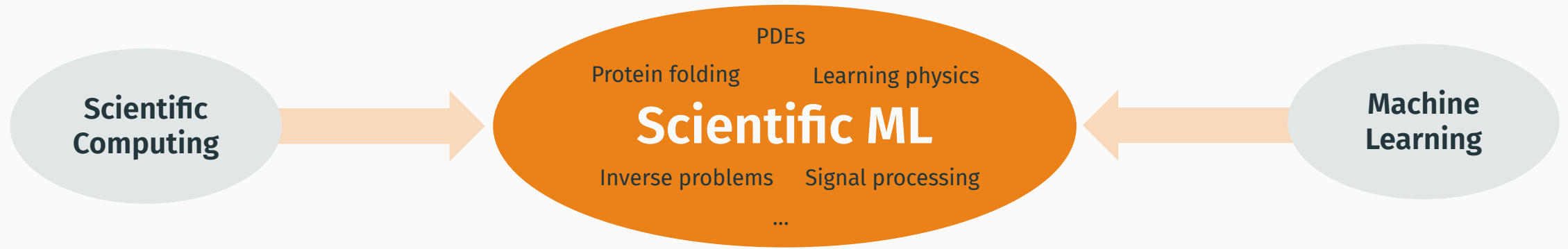


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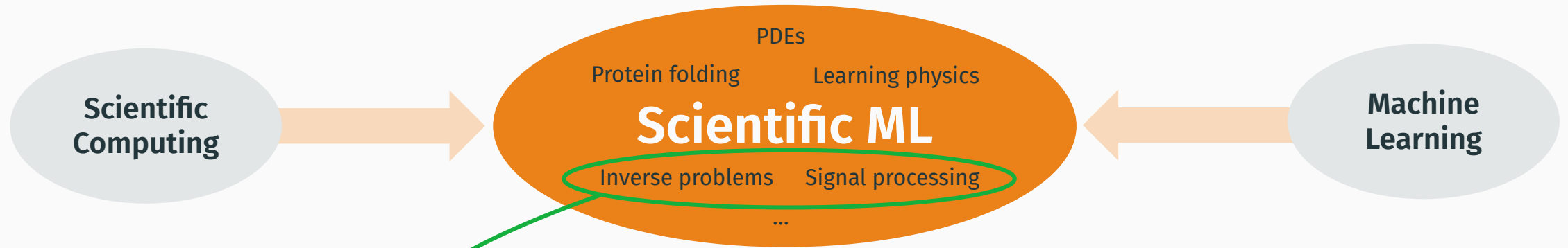
39th International Conference on Machine Learning

Baltimore, Jul 17 – Jul 23, 2022

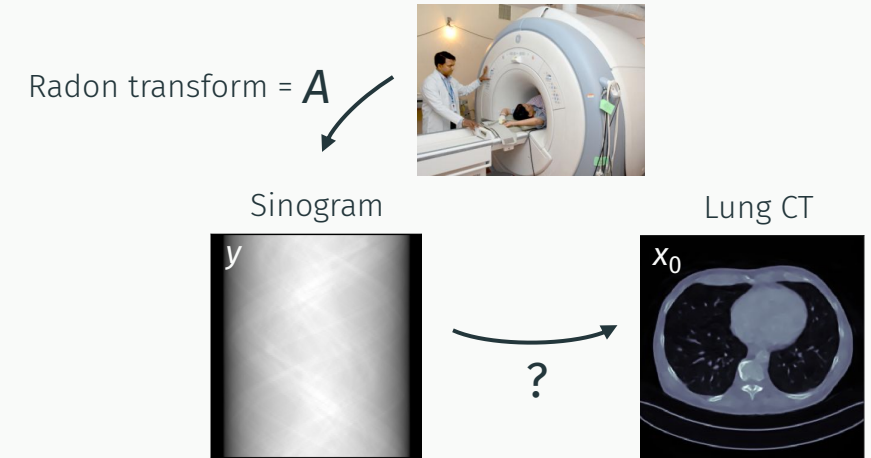
Ill-Posed Inverse Problems



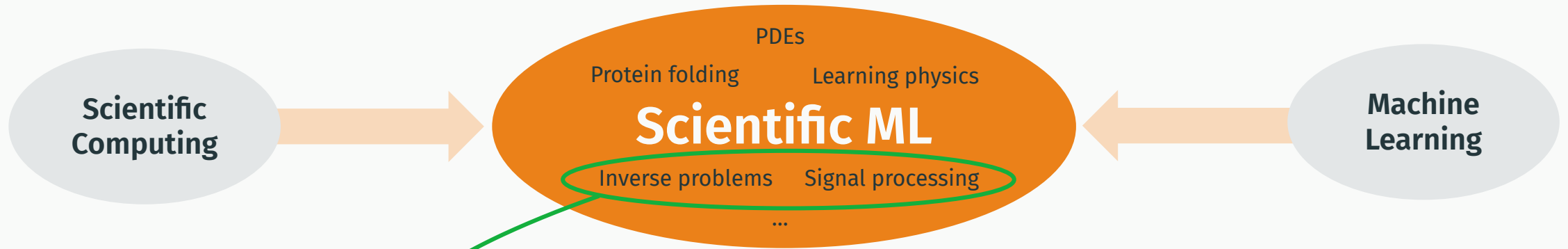
Ill-Posed Inverse Problems



Given a forward operator $A \in \mathbb{R}^{m \times d}$ and corrupted measurements $y = Ax_0 + e$ with $\|e\|_2 \leq \eta$, reconstruct the signal x_0 .

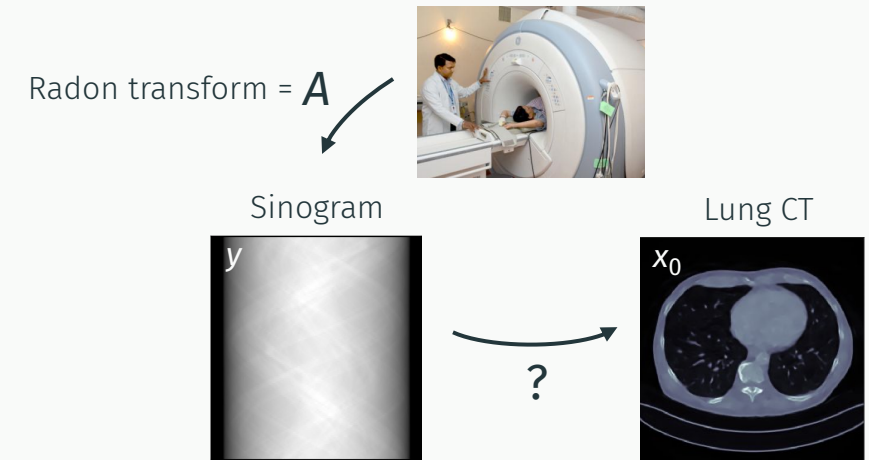


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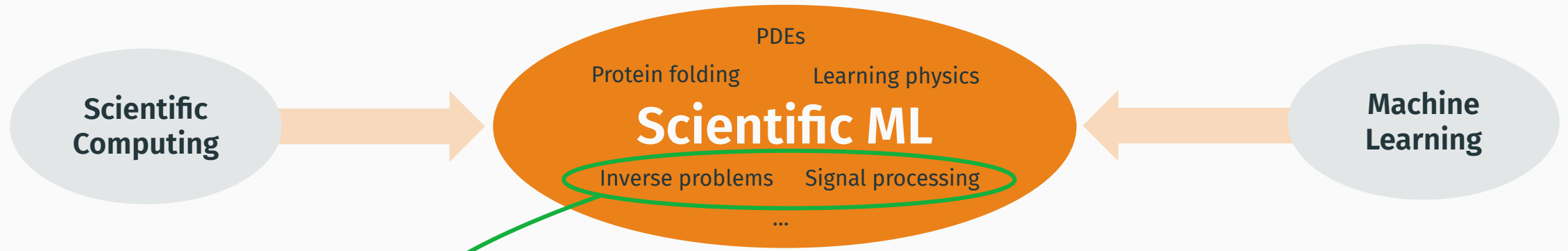


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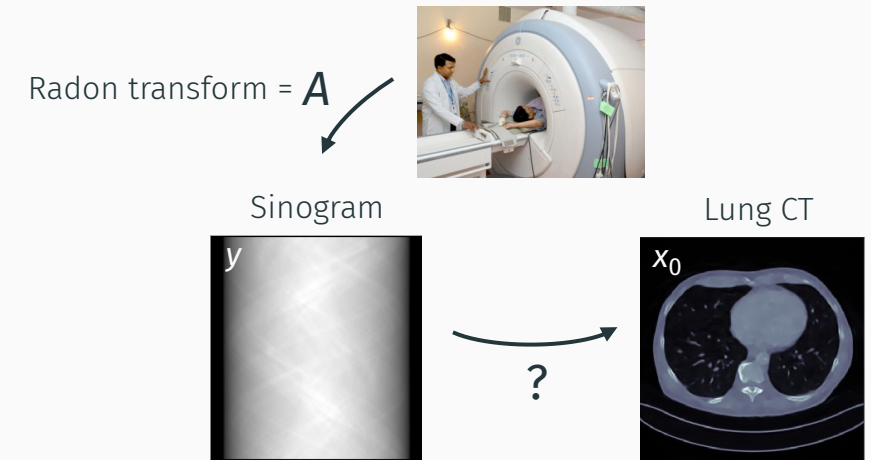


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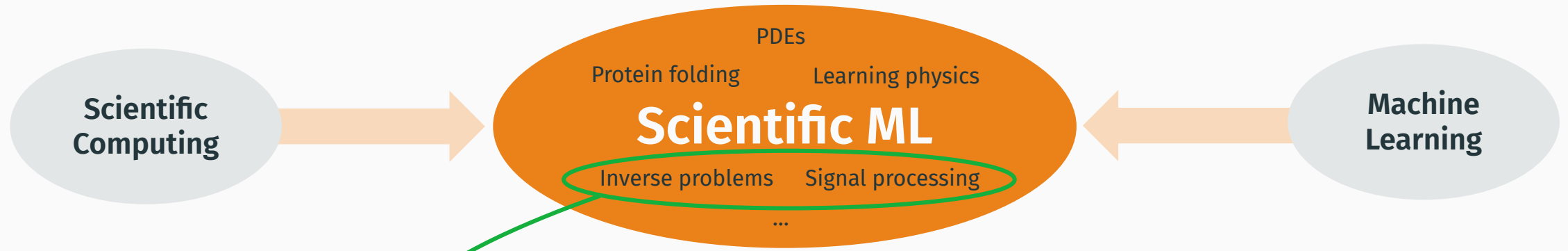
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Classical variational methods

$$x_0 \approx \arg \min_x \|y - Ax\|_2^2 + \lambda \cdot R(x)$$



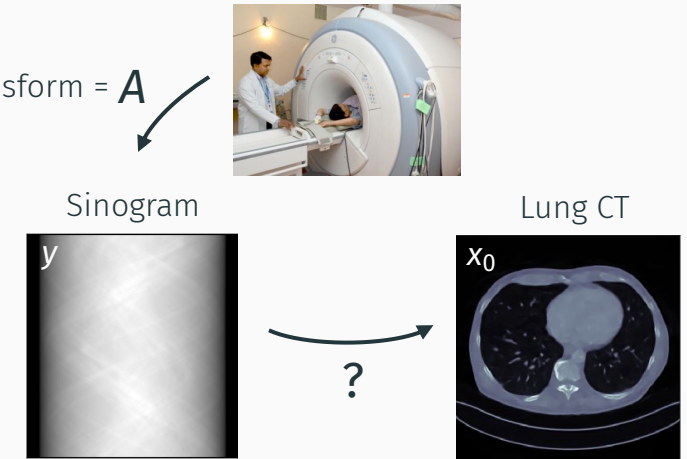
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Radon transform = A



Classical variational methods

$$x_0 \approx \arg \min_x \|y - Ax\|_2^2 + \lambda \cdot R(x)$$

Modern **deep learning** methods

$$x_0 \approx \text{Net}[\hat{\theta}](y)$$

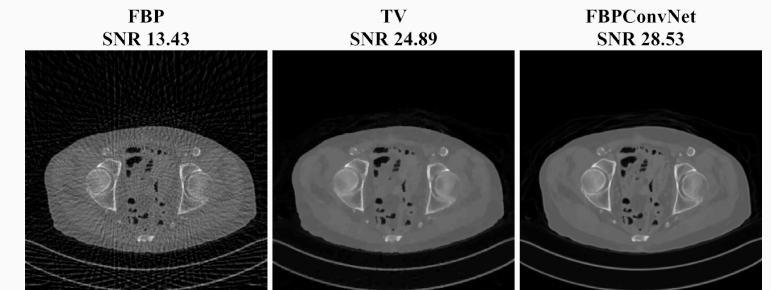
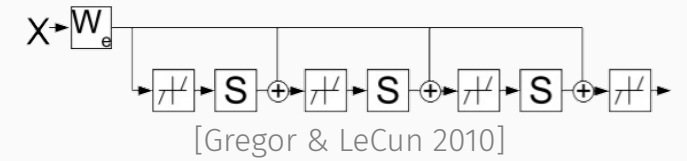
$\min_{\theta} \frac{1}{M} \sum_{i=1}^M \|\text{Net}[\theta](y^i) - x_0^i\|_2^2$

“Infer knowledge directly from data $\{(y^i, x_0^i)\}_{i=1}^M$.”

Is Deep Learning for Inverse Problems Reliable?

- ▶ Since 2016: Paradigm shift from sparsity-based regularization to deep learning [Arridge et al. 2019; Ongie et al. 2020]
(post-processing, unrolling, gen. models, PnP, learned reg., DIP, ...)

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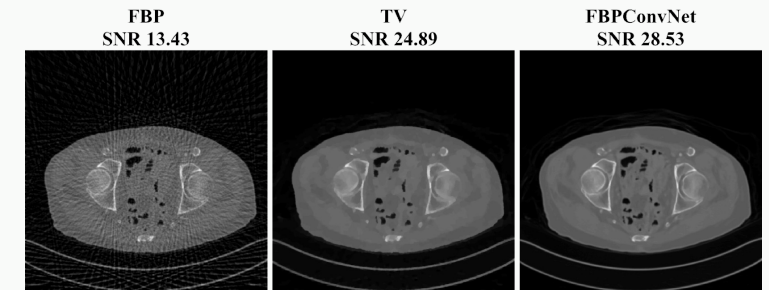
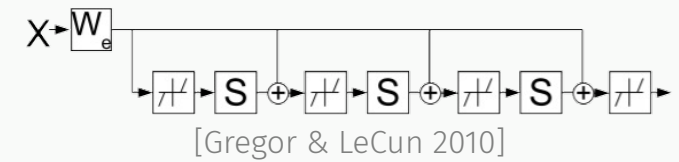
[Jin et al. 2017]

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- ▶ A lack of theoretical foundation has sparked a controversial debate about reliability [Antun et al. 2020]

$$\|x_0 - \text{Net}(y)\|_2 \leq \underbrace{\|x_0 - \text{Net}(Ax_0)\|_2}_{\text{Accuracy}} + \underbrace{\|\text{Net}(Ax_0) - \text{Net}(y)\|_2}_{\text{Robustness}}$$

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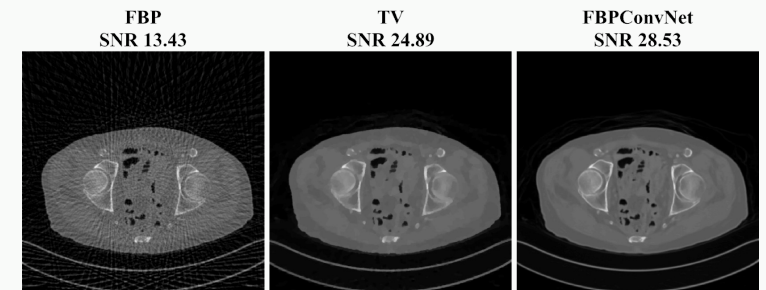
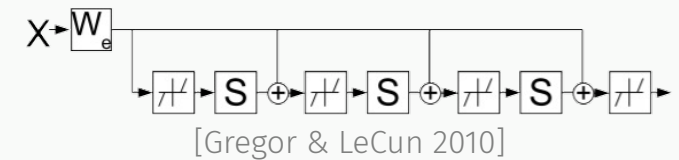
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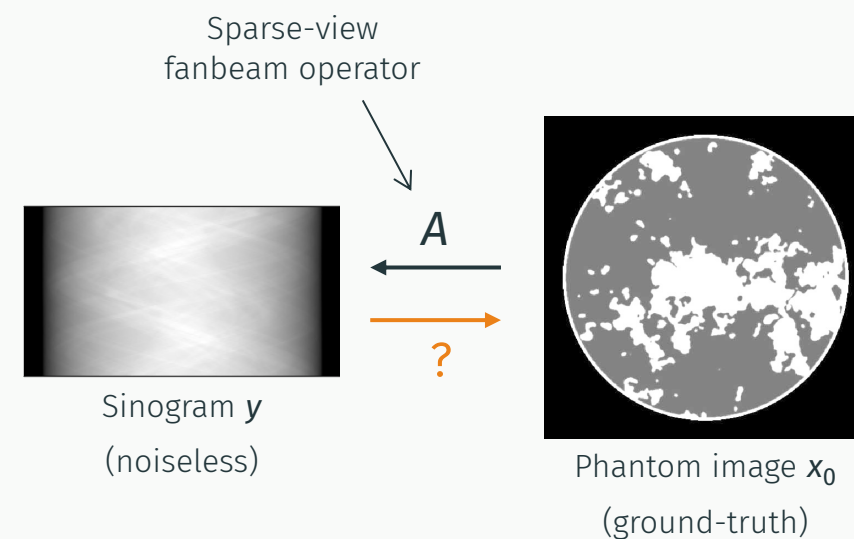
Optimistic results in

Solving Inverse Problems With Deep Neural Networks – Robustness Included?

Genzel, Macdonald, März [IEEE TPAMI 2022]

“Do CNNs Solve the CT Inverse Problem?” [Sidky et al. 2021]

- ▶ Based on research by Emil Sidky et al. on **sparse-view breast CT**
- ▶ Answer for post-processing by U-net: **No!**
- ▶ Goal of AAPM Challenge: *“The challenge seeks the data-driven methodology that provides the most accurate reconstruction of sparse-view CT data.”*



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Deep Learning for Inverse Problems: Sparse-View Computed Tomography Image Reconstruction (DL-sparse-view CT)

An AAPM Grand Challenge

Overview

The American Association of Physicists in Medicine (AAPM) is sponsoring a “Grand Challenge” on deep-learning for image reconstruction leading up to the 2021 AAPM Annual Meeting. The DL-sparse-view CT challenge will provide an opportunity for investigators in CT image reconstruction using data-driven techniques to compete with their colleagues on the accuracy of their methodology for solving the inverse problem associated

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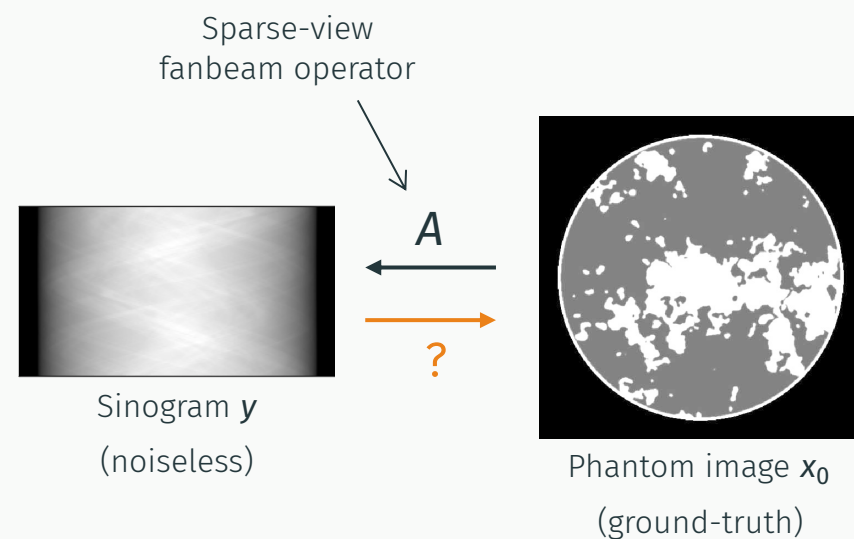
- ▶ Challenge dataset: $M = 4000$ pairs of
 - **breast-phantom images** ($d=512 \times 512$)
 - noiseless **sparse-view sinograms** (128 views)
 - (sparse-view FBP images)

- ▶ Evaluation by RMSE ($= \frac{1}{M} \sum_{i=1}^M \sqrt{\|x_0^i - \hat{x}_0^i\|_2^2 / d}$)

↪ **TV minimization can solve the problem** (RMSE $\approx 1e-6$)

- ▶ Timeline: Mar 17 – Jun 1, 2021

↪ Approx. 60 groups participated (25 in final phase)



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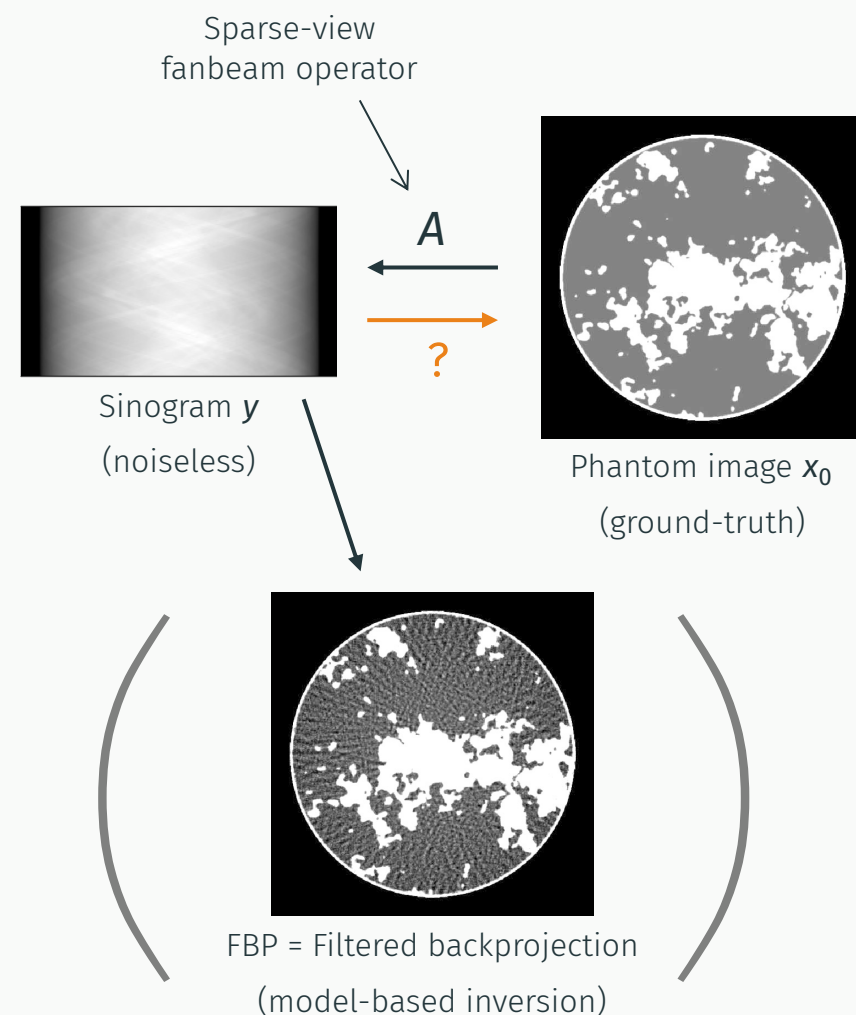
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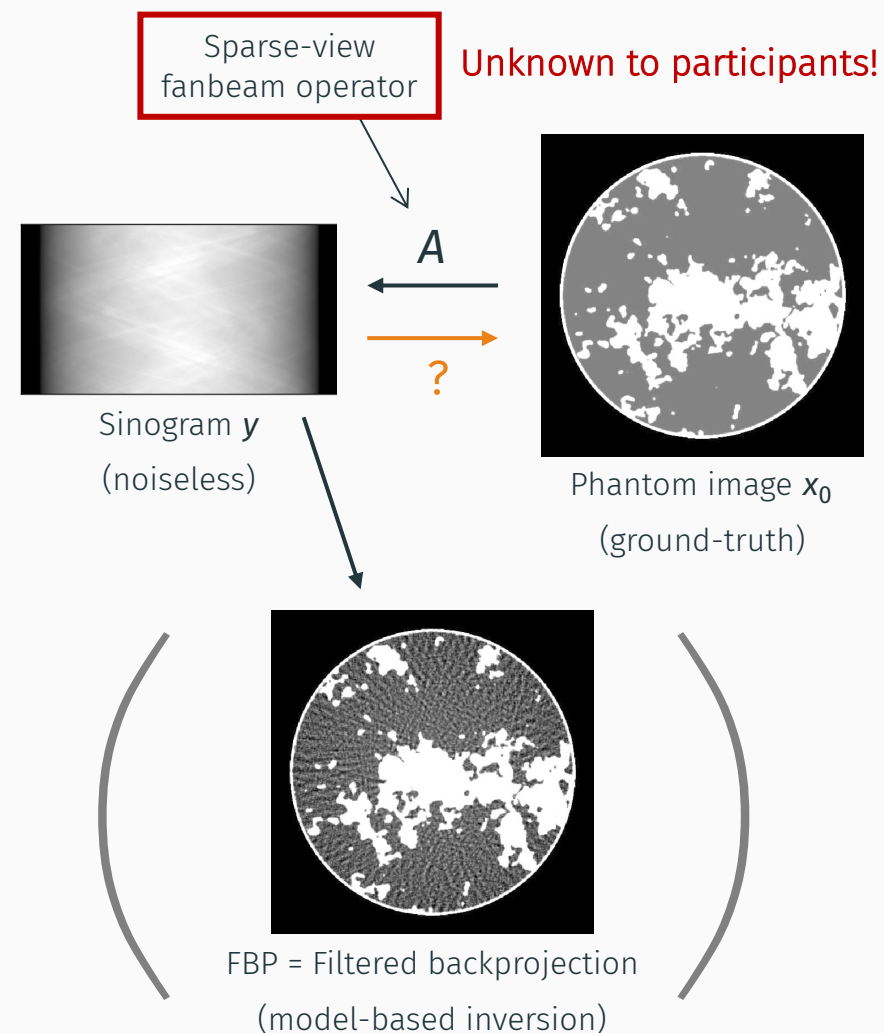
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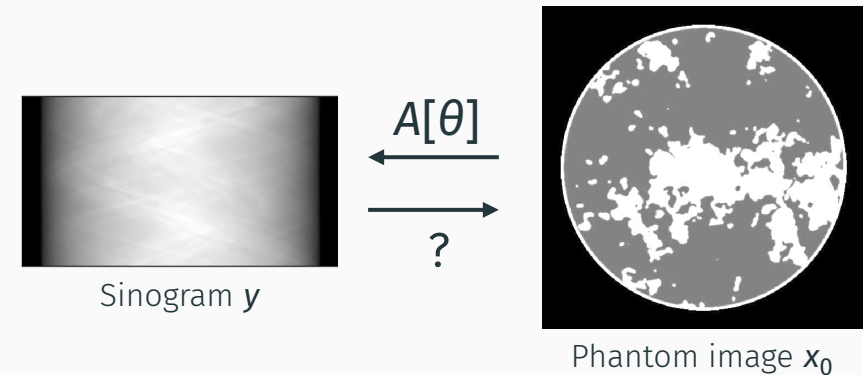
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Our Approach to the AAPM Challenge

- ▶ **Step 1:** Fully **data-driven** operator identification based on a parameterized **fwd. model** $A[\theta]$

$$\min_{\theta} \sum_i \|A[\theta](x_0^i) - y^i\|_2^2$$

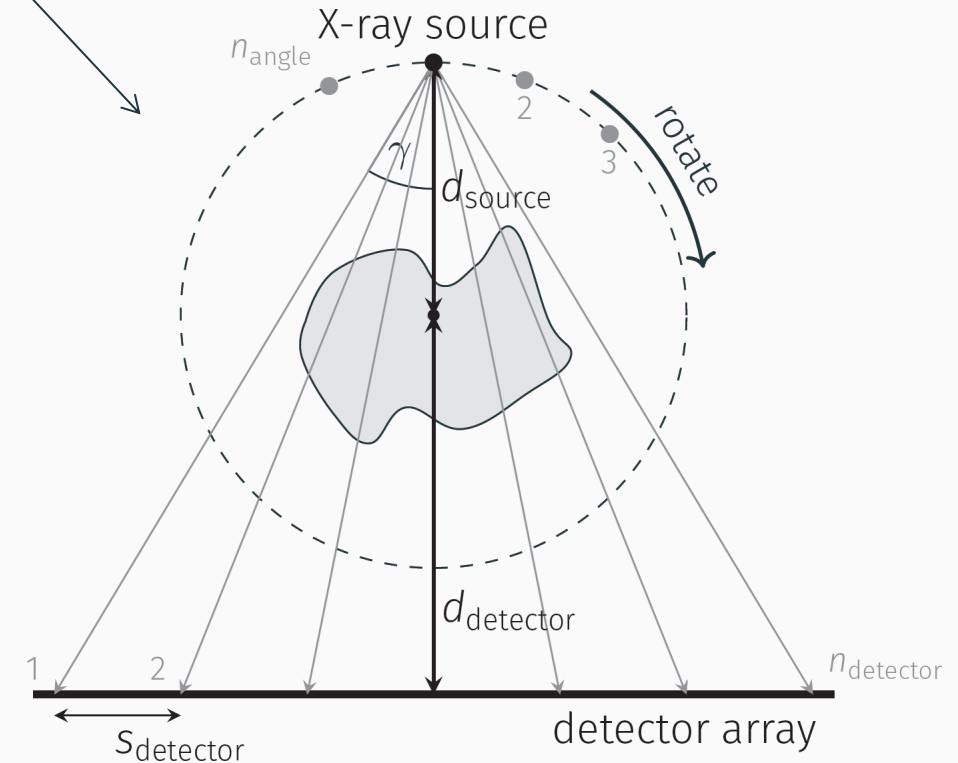
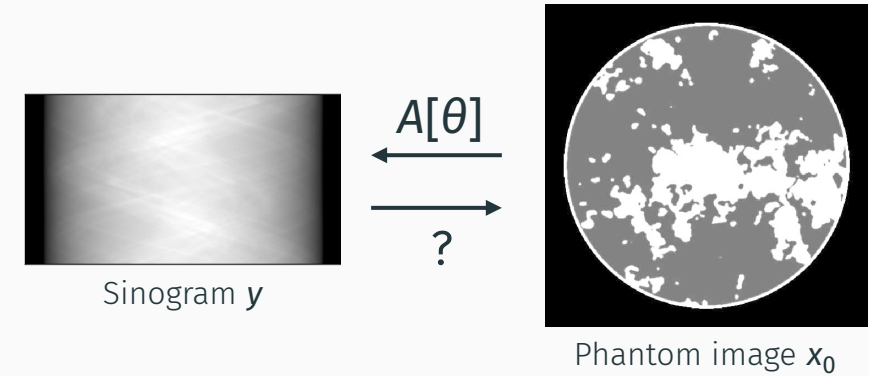


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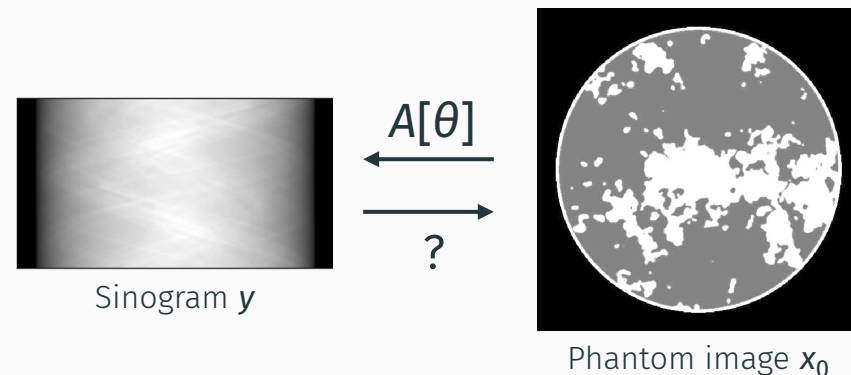
Deep-learning-style optimization (backprop/autodiff)



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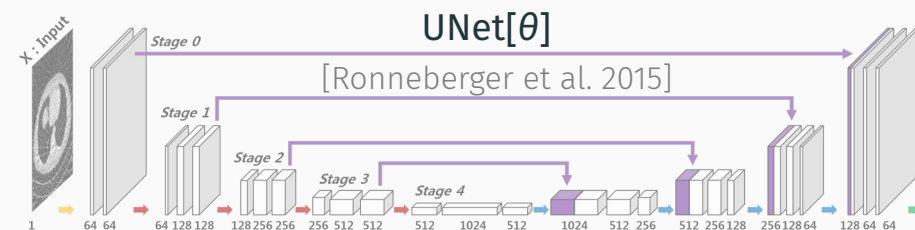
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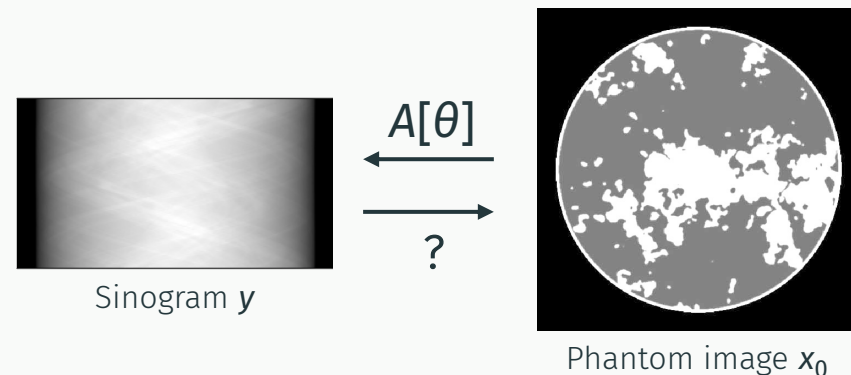
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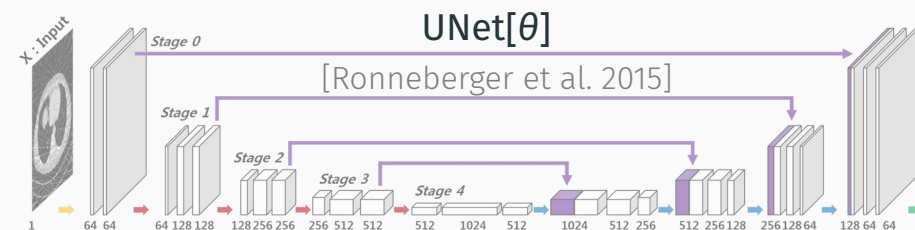


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↑ computational backbone
 ↑ “learned” (depends on $A[\theta]$)

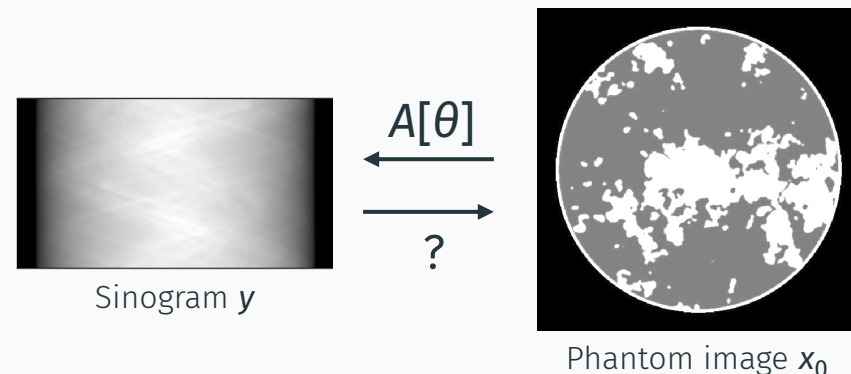
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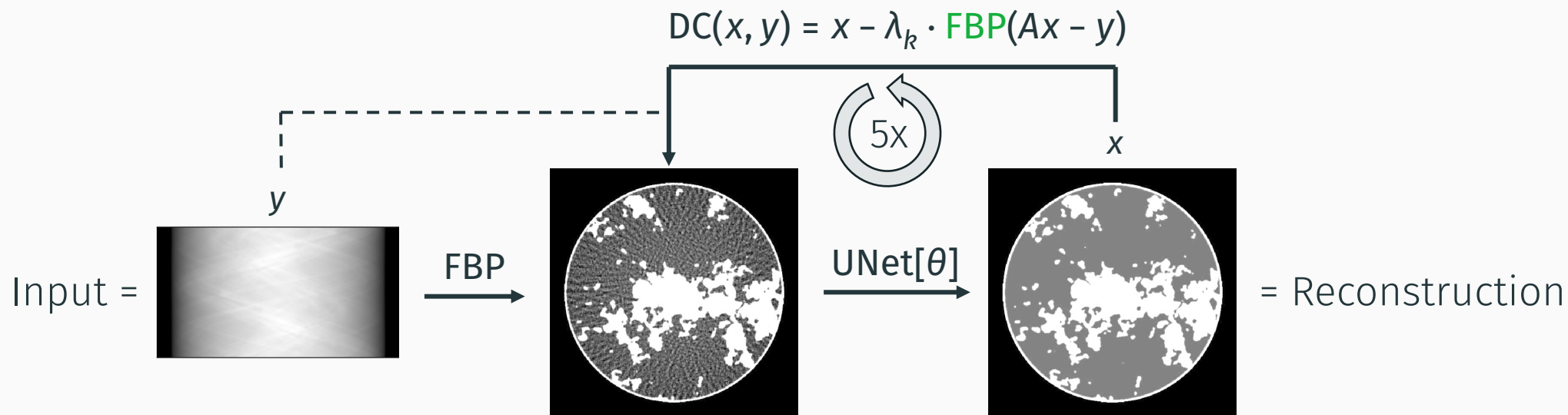


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[Jin et al. 2017; Kang et al. 2017; ...]

- ▶ Step 3: Construct an **iterative scheme** (= **ItNet**)

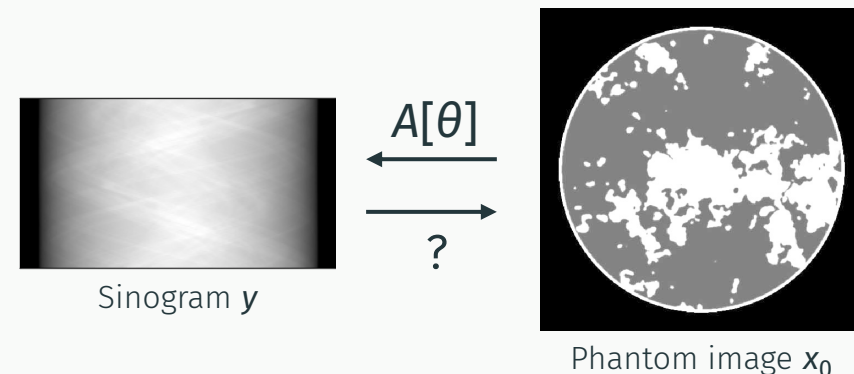
[Aggarwal et al. 2018; Schlemper et al. 2019; Hammernik, Schlemper, et al. 2021; ...]



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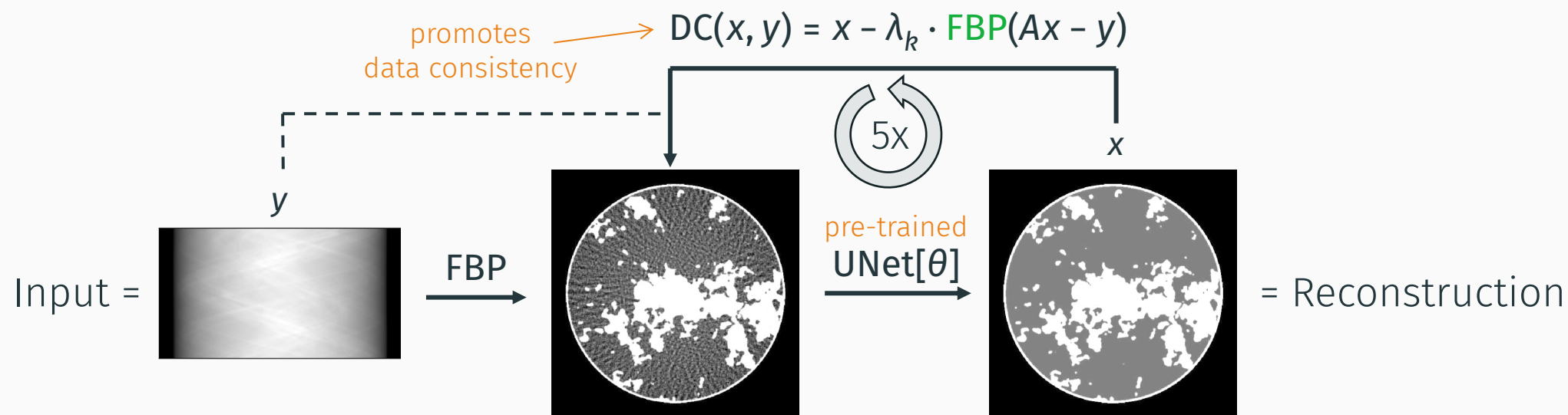


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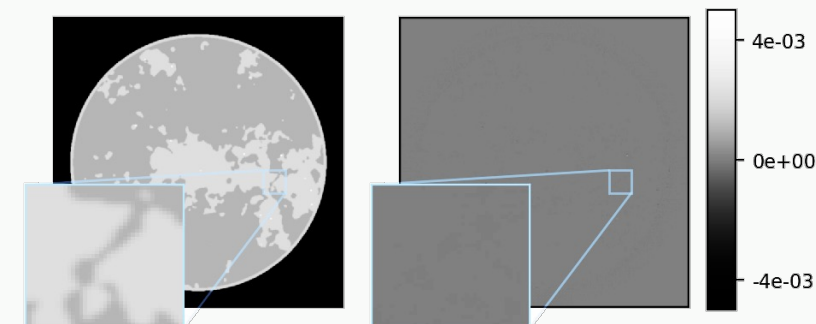
Challenge Results – Team: `robust-and-stable`

| | Baselines | | Our Network Variants | | Comparison Networks | |
|------|------------|---------|----------------------|----------------|---------------------|---------|
| | Chall. FBP | Our FBP | U-net | ItNet | Tiramisu | LPD |
| RMSE | 5.72e-3 | 3.40e-3 | 3.50e-4 | 6.37e-6 | 2.24e-4 | 1.24e-4 |

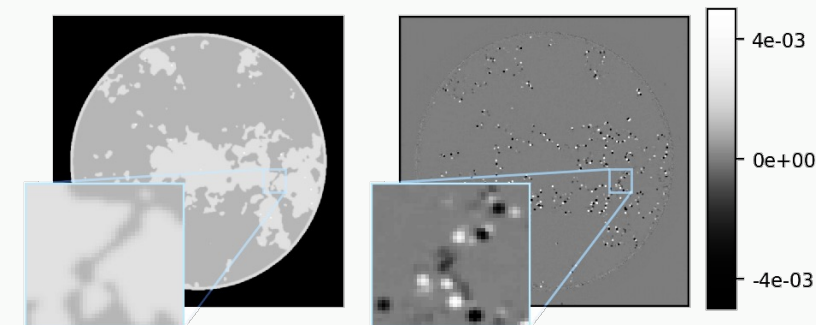
[Jégou et al. 2017; Adler & Öktem 2018]

| Results | | | | | |
|---------|----------------|---------|--------------------|--------------------------------|----------------|
| # | User | Entries | Date of Last Entry | Team Name | RMSE ▲ |
| 1 | Max | 3 | 05/31/21 | <code>robust-and-stable</code> | 0.00000637 (1) |
| 2 | TUM | 4 | 05/31/21 | YM & RH | 0.00003989 (2) |
| 3 | cebel67 | 4 | 05/31/21 | DEEP_UL | 0.00012923 (3) |
| 4 | deepx | 3 | 05/31/21 | | 0.00015935 (4) |
| 5 | Haimiao | 4 | 05/29/21 | HBB | 0.00018119 (5) |
| 6 | HKim | 2 | 05/31/21 | MIR | 0.00026678 (6) |
| 7 | luke199629 | 5 | 05/31/21 | | 0.00028064 (7) |
| 8 | yume | 3 | 05/26/21 | list | 0.00029180 (8) |

ItNet (RMSE = 6.23e-06)



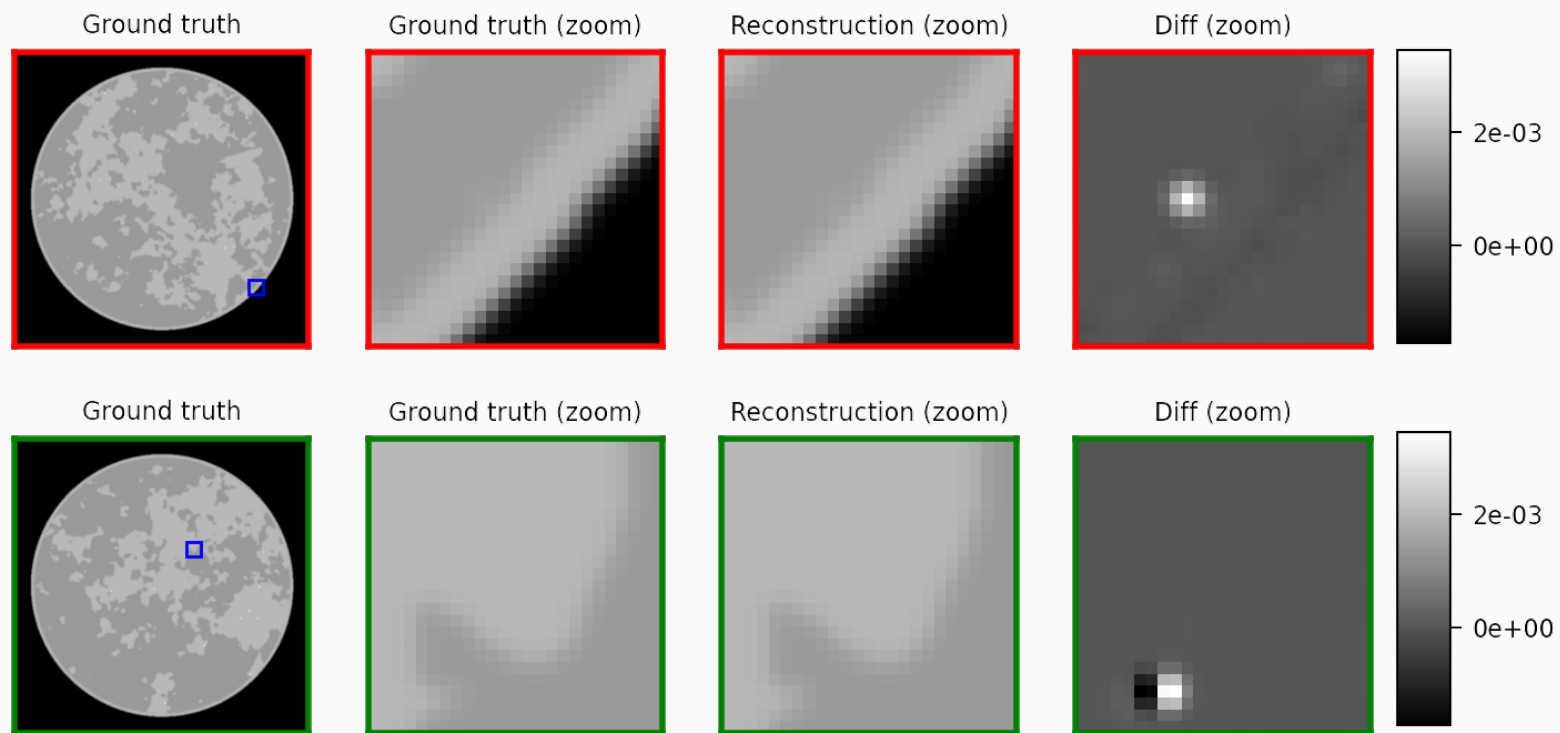
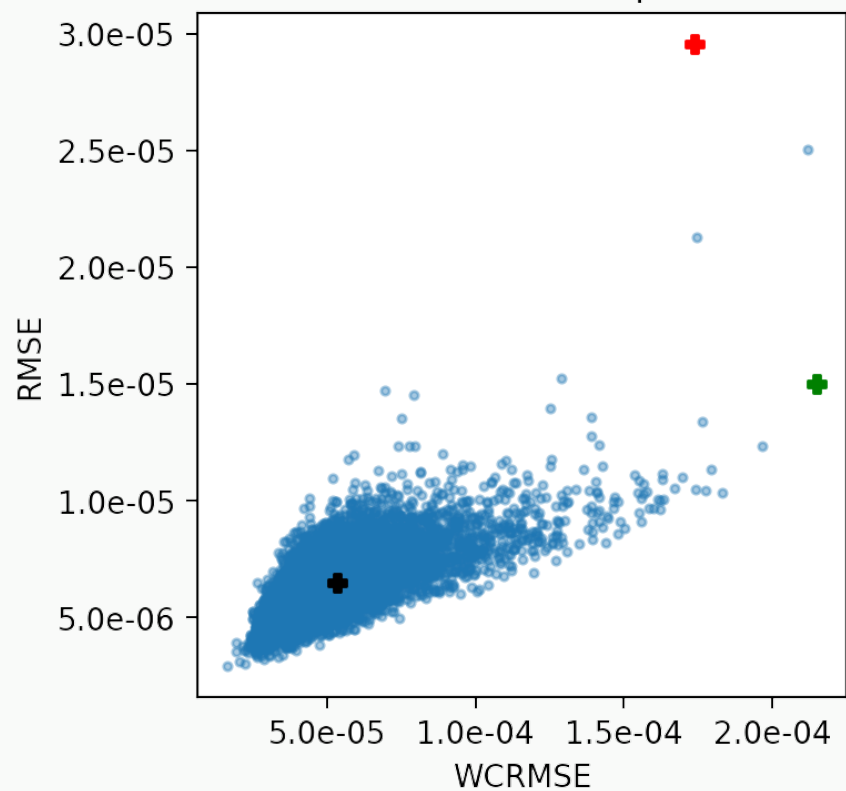
Tiramisu (RMSE = 2.75e-04)



Further Analysis & Take-Aways (1/4)

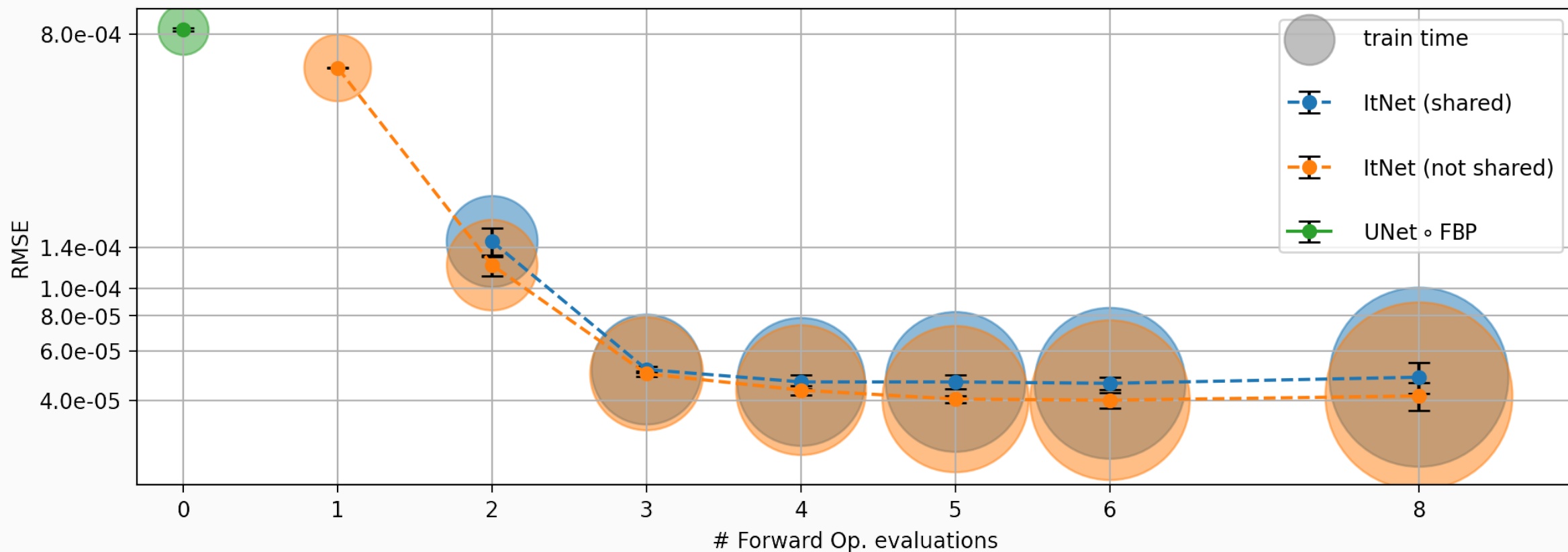
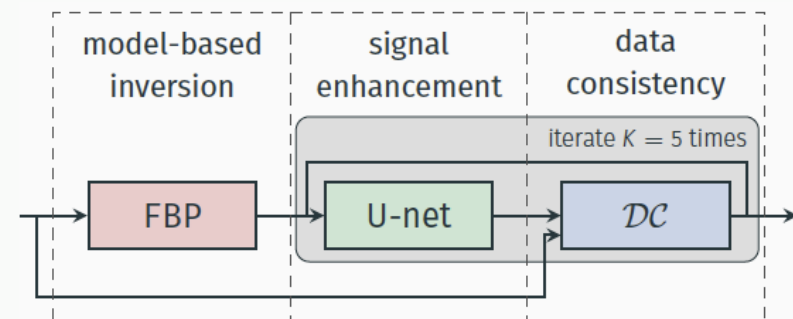
Near-exact image recovery via end-to-end NNs is possible
↳ “practical solution” to the inverse problem

10000 test samples



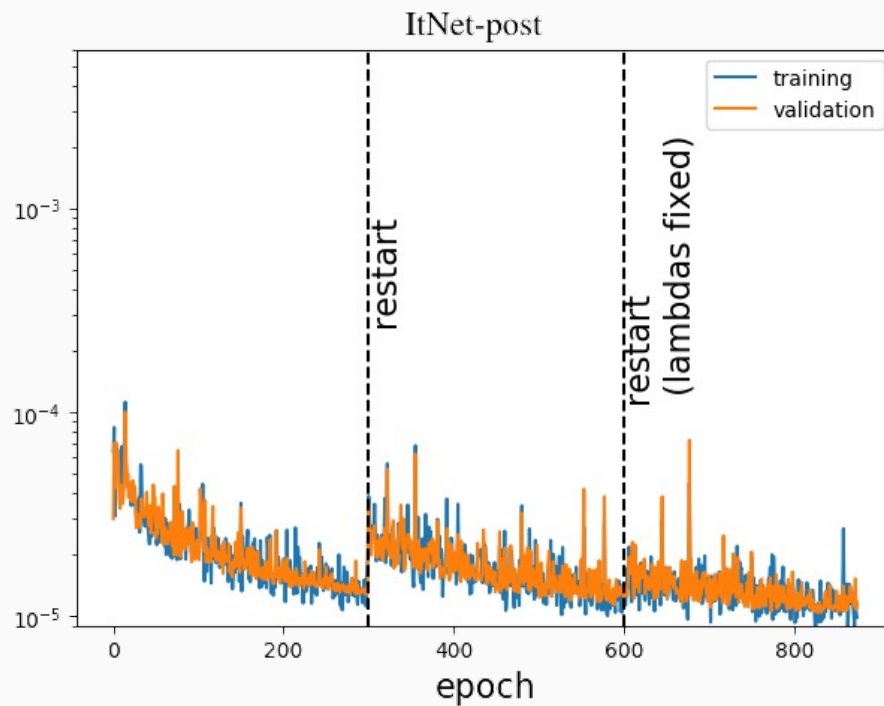
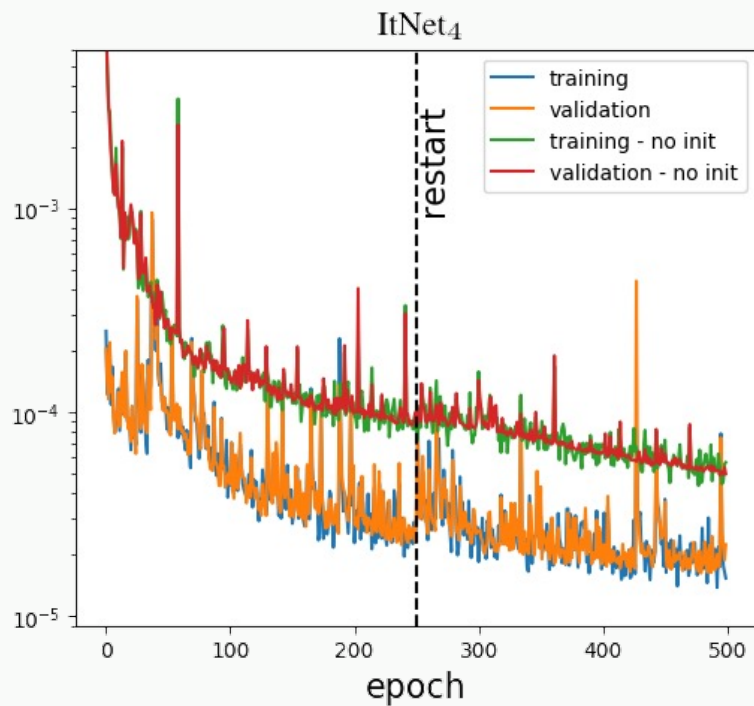
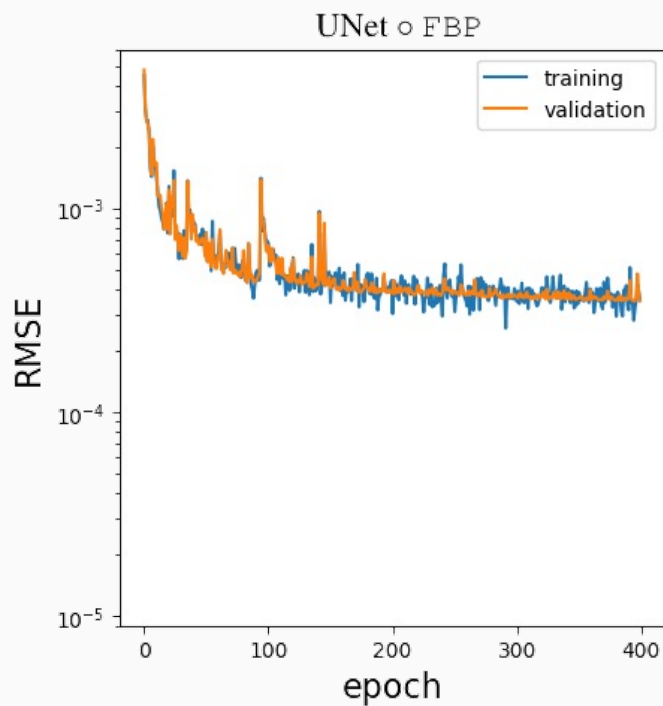
Further Analysis & Take-Aways (2/4)

Only very few iterations of fwd. operator required
↳ very different from classical solvers



Further Analysis & Take-Aways (3/4)

Model-based knowledge and pre-training is key
↳ “Simple models, but trained well!”

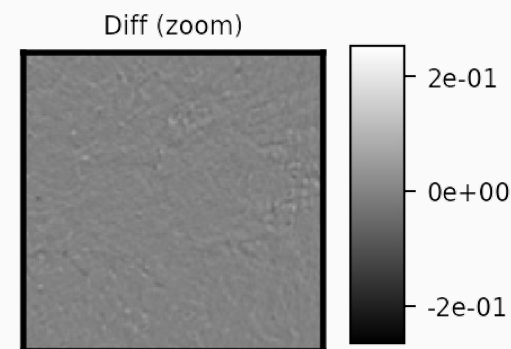
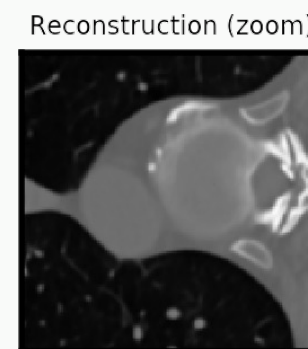
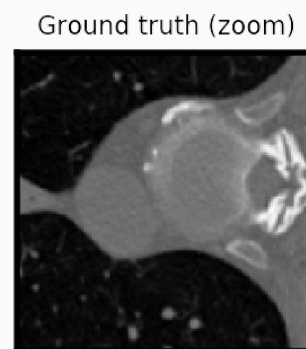
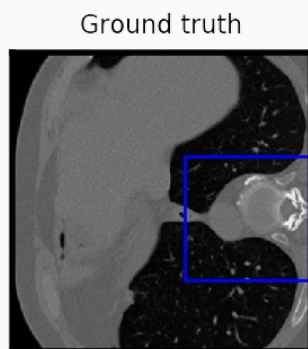
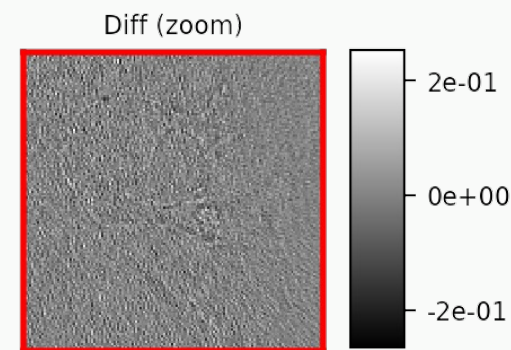
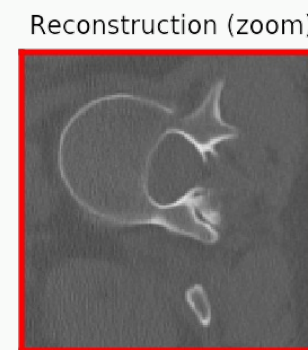
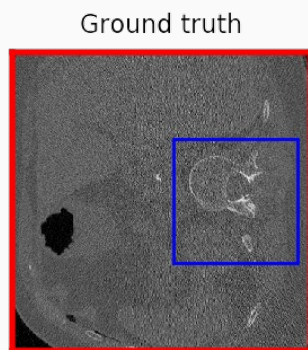
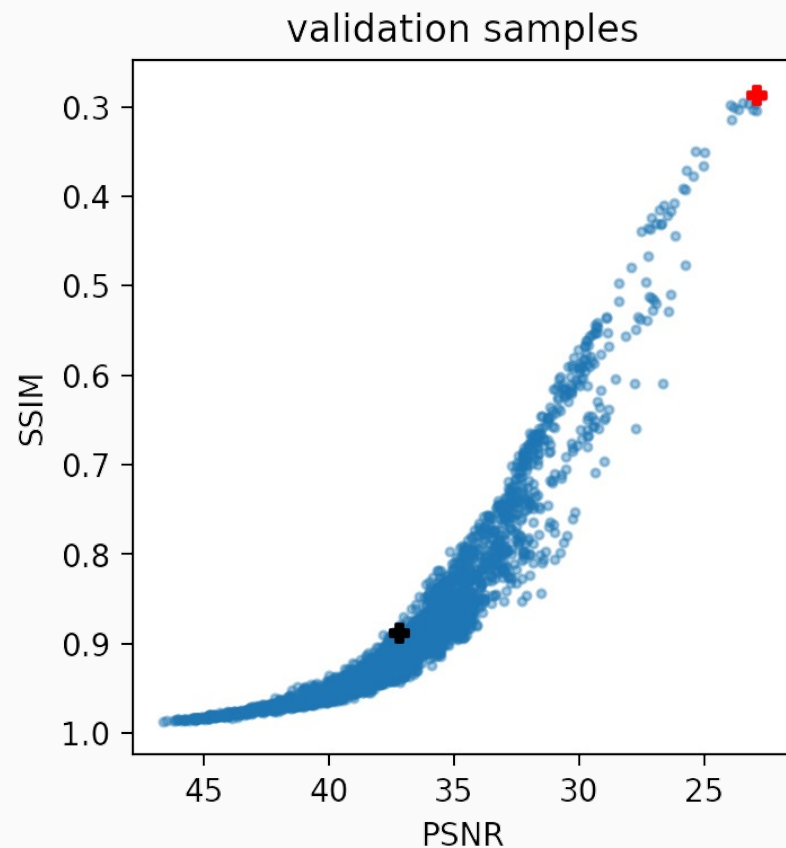


Further Analysis & Take-Aways (4/4)

ItNet is also SOTA for real-world CT image data

| # | User (Team) | Created | Mean Position |
|-----|-----------------|---------------|---------------|
| 1st | RobustAndStable | 4 Nov. 2021 | 1.3 |
| 2nd | RobustAndStable | 1 May 2021 | 2.8 |
| 2nd | iRIMforCT | 19 Aug. 2021 | 2.8 |
| 4th | RobustAndStable | 28 April 2021 | 5.5 |
| 5th | iRIMforCT | 31 July 2021 | 6.8 |

LoDoPaB-CT – Leuschner et al. 2021



THANK YOU!

Official Challenge Report:

E. Sidky & X. Pan. Report on the AAPM deep-learning sparse-view CT (DL-sparse-view CT) Grand Challenge. *Med. Phys.* (2022), arXiv:2109.09640

Our code:

<https://github.com/jmaces/aapm-ct-challenge>

Find us on

@MartinGenzel @Iguhiring @jan_maces @MaximilianMarz