Bayesian Nonparametric Learning for Point Processes with Spatial Homogeneity: A Spatial Analysis of NBA Shot Locations

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Modeling shot location data

In professional basketball, shot location data remains to be a fundamental metric for evaluating players and has aroused great research interests (e.g., Reich et al., 2006; Miller et al., 2014; Jiao et al., 2021).

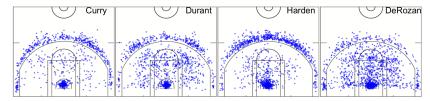


Figure: Shot data Display (2017-2018 season). On half court image, each point represents one shot.

Key Questions and Our Contributions

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- random nature of shot location data
- identifying clusters of regions on which players have similar shooting behavior while incorporating the prior belief that spatially contiguous regions are similar

Our contributions

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- A Gibbs sampler that enables efficient Bayesian inference across models of different dimensions without RJMCMC or samplers allocation

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Point Process Data

- A spatial point pattern is a data set y = (s₁, s₂, ..., s_ℓ) consists of locations (s₁, s₂, ..., s_ℓ) of points that are observed in a bounded region B ⊆ R², which is a realization of spatial point process Y.
- N_Y(A) = ∑_{i=1}^ℓ 1(s_i ∈ A) is a counting process associated with the spatial point process Y, which counts the number of points of Y for area A ⊆ B.
- For the Poisson process \mathbf{Y} over \mathcal{B} , which has the intensity function $\lambda(\mathbf{s})$, $N_{\mathbf{Y}}(A) \sim \text{Poisson}(\lambda(A))$, where $\lambda(A) = \int_A \lambda(\mathbf{s}) d\mathbf{s}$.
- We signify that a set of points $y = (s_1, s_2, ..., s_\ell)$ follows a Poisson process as

$$\mathbf{y} \sim \mathcal{PP}(\lambda(\cdot)). \tag{1}$$

Poisson Process

- Let A₁, A₂, · · · , A_n be a partition of B, i.e., disjoint subsets such that ⋃ⁿ_{i=1} A_i = B.
- For each region A_i, i = 1, · · · , n, we have constant intensity λ_i over region A_i. The likelihood is written as:

$$L = \prod_{i=1}^{n} f_{\text{poisson}}(N_{\mathbf{Y}}(A_i)|\lambda_i), \qquad (2)$$

where f_{poisson} is the probability density of Poisson distribution. In later sections, we use $N(A_i)$ to denote $N_Y(A_i)$

Dirichlet Process Mixture Model

$$\begin{aligned} y_i | Z_i, \beta_{Z_i} &\sim F(\beta_{Z_i}) \\ Z_i | p &\sim \textit{Discrete}(p_1, \cdots, p_K) \\ \beta_{Z_i} &\sim G_0 \quad p &\sim \textit{Dirichlet}_K(\alpha/K, \cdots, \alpha/K) \end{aligned}$$
(3)

- Z_i stands for the cluster of ith observation
- \triangleright β_{c_i} means the parameter of c_i th cluster
- α stands for the precision parameter
- G₀ is the base measure in Dirichlet process
- Issue: Incorporating spatial information?

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Incorporating Spatial Homogeneity

We impose a Markov random field constraint (Besag et al., 1995; Orbanz and Buhmann, 2008)
 M(λ₁,...,λ_n) := ¹/_{Z_H} exp {−H(λ₁,...,λ_n)} on λ to encourage rate parameters in nearby regions to be similar

$$G \sim \mathsf{DP}(\alpha, G_0)$$
$$(\lambda_1, \dots, \lambda_n) \sim \mathcal{M}(\lambda_1, \dots, \lambda_n) \prod_{i=1}^n G(\lambda_i)$$
(4)
$$\mathcal{N}(A_i) \mid \lambda_1, \dots, \lambda_n \sim \mathsf{Poisson}(\lambda_i \mu(A_i)) \ i = 1, \dots, n,$$

Cost Function

$$\blacktriangleright H(\lambda_1,\ldots,\lambda_n) := \sum_{C \in \mathcal{C}} H_C(\lambda_C)$$

 C denotes the set of all cliques, or completely connected subsets in the underlying *neighborhood graph* \$\mathcal{N} = (V_\mathcal{N}, E_\mathcal{N}, W_\mathcal{N})\$

Pairwise interactions

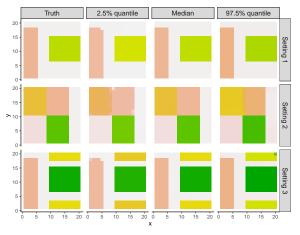
$$H(\lambda_i|\boldsymbol{\lambda}_{-i}) := -\eta \sum_{j \in \partial(i)} I(\lambda_i = \lambda_j) = -\eta \sum_{j \in \partial(i)} I(z_j = z_i) \quad (5)$$

 η: a parameter controlling the extent of spatial homogeneity with larger values dictating higher degree of spatial homogeneity

Algorithm Sketch

- A collapsed Gibbs sampler that enables the iterative updating of model parameters and latent variables
- Dahl's method (Dahl, 2006) for post MCMC inference identifying the *best* post burn-in iteration for estimation
- Selecting the optimal tuning parameter via Bayesian information criteria

Simulation study: Ground truth





Comparison to other methods

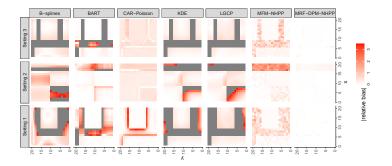
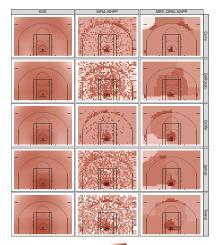


Figure: Absolute relative bias of posterior mean estimates. Dark grey: regions with absolute relative bias > 3.5.

NBA Data Analysis

- 20 top players in the 2017-2018 NBA regular season.
- The attacking half of the basketball court is divided into 50 × 35 = 1750 equally-sized grid boxes of 1ft × 1ft following Miller et al. (2014).
- Parallel MCMC chains with η ∈ {0, 0.5, ..., 6} for 5000 iterations using random initial values
- ► Assessing predictive performance via *p*-thinning approach (Illian et al., 2008) mean absolute error (MAE) defined as $MAE = \frac{1}{n} \sum_{i=1}^{n} \left| \frac{1-p}{p} \widehat{\lambda}(A_i) N(A_i) \right|$, where $\widehat{\lambda}(A_i)$ is the estimated intensity of region A_i based on a random subset of points (training data) and $N(A_i)$ is the number of observed points falling into region A_i in the hold-out data.

NBA Data Results



log(lambda) _4-4-2 0 2

MAE Comparison for predictive assessment

	position	MRF-DPM-NHPP	MFM-NHPP	LGCP	CAR-Poisson	BART	KDE	B -splines	Miller
DeAndre Jordan	С	0.041	0.044	0.077	0.300	0.038	0.100	>> 1	0.109
Joel Embiid	С	0.147	0.143	0.150	0.304	0.137	0.167	0.181	0.181
Karl-Anthony Towns	С	0.162	0.156	0.193	0.317	0.149	0.215	0.241	0.245
Dwight Howard	С	0.077	0.083	0.117	0.300	0.075	0.144	0.171	0.172
Giannis Antetokounmpo	PF	0.158	0.153	0.201	0.321	0.153	0.228	0.252	0.255
Blake Griffin	PF	0.141	0.140	0.151	0.312	0.137	0.171	0.182	0.186
LaMarcus Aldridge	PF	0.181	0.199	0.207	0.317	0.176	0.226	0.232	0.236
Kristaps Porziņģis	PF	0.169	0.175	0.174	0.318	0.168	0.183	0.183	0.183
Stephen Curry	PG	0.137	0.134	0.146	0.302	0.131	0.158	0.160	0.152
Damian Lillard	PG	0.192	0.201	0.229	0.331	0.190	0.251	0.269	0.269
Chris Paul	PG	0.128	0.126	0.130	0.296	0.129	0.138	0.138	0.138
Kyrie Irving	PG	0.167	0.177	0.186	0.315	0.167	0.200	0.209	0.208
Kevin Durant	SF	0.190	0.192	0.204	0.327	0.185	0.218	0.215	0.213
LeBron James	SF	0.200	0.199	0.241	0.329	0.181	0.273	0.292	0.298
Paul George	SF	0.200	0.200	0.233	0.334	0.194	0.250	0.255	0.249
Jimmy Butler	SF	0.149	0.156	0.162	0.311	0.150	0.174	0.181	0.181
James Harden	SG	0.192	0.196	0.237	0.330	0.182	0.264	0.287	0.280
DeMar DeRozan	SG	0.215	0.218	0.221	0.330	0.206	0.237	0.247	0.249
Russell Westbrook	SG	0.200	0.209	0.261	0.340	0.207	0.294	0.300	0.305
Klay Thompson	SG	0.188	0.190	0.191	0.321	0.182	0.204	0.203	0.20

Table 6: MAE results. The MAE for B-splines fitted to the training data from DeAndre Jordan is very large due to its poor fit at the boundary.

Thank you

Welcome to reading our paper!

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