

MARINA: Faster Non-Convex Distributed Learning with Compression

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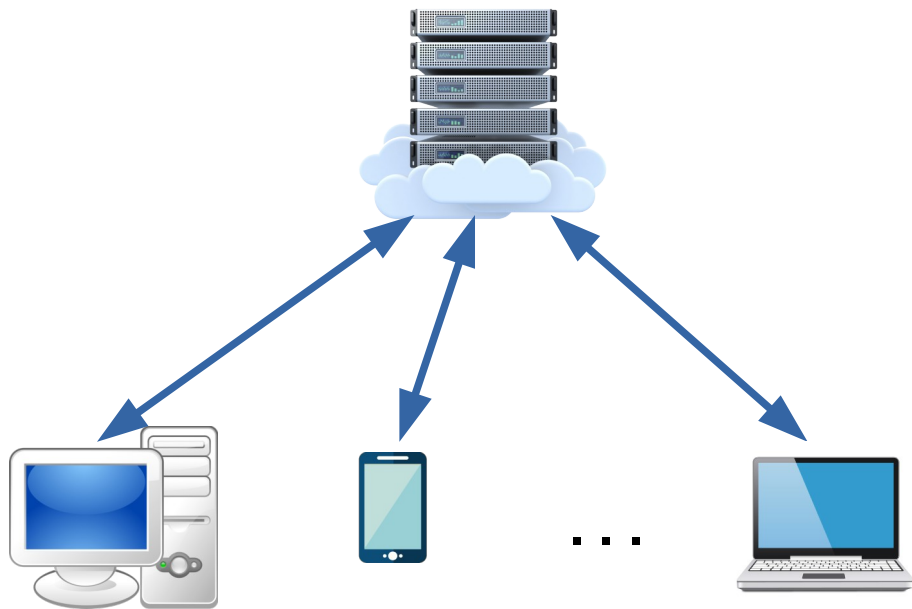


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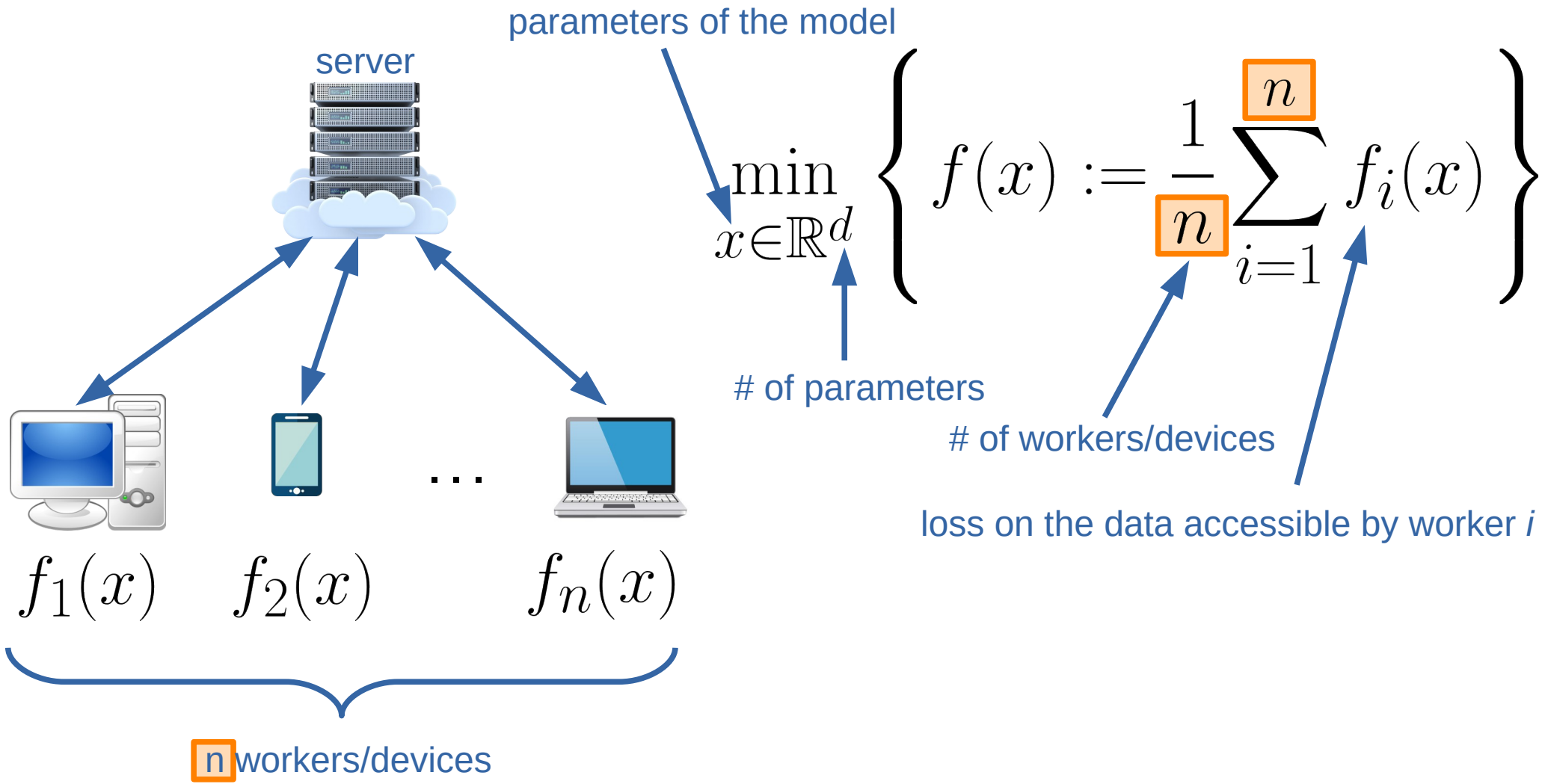


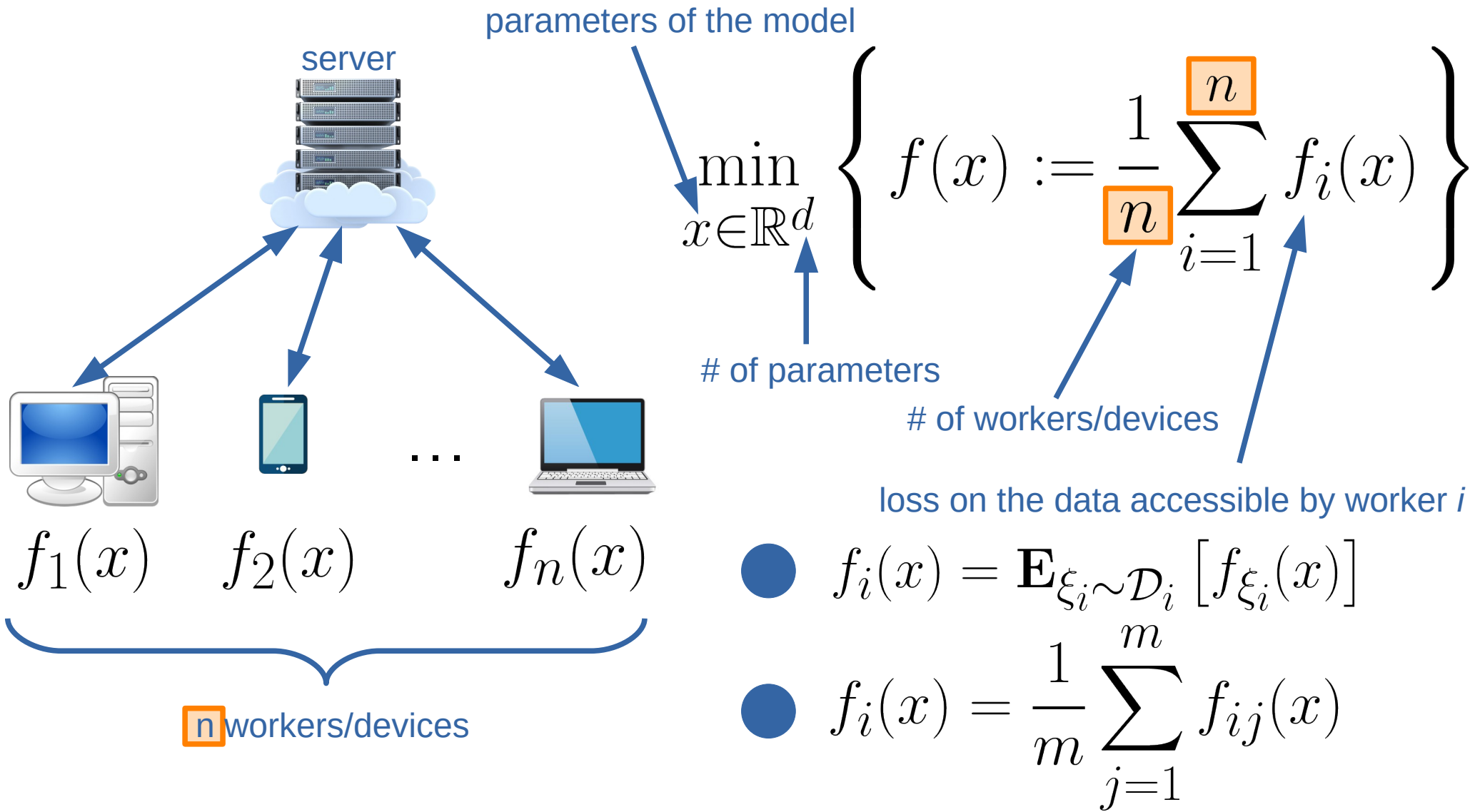
Peter Richtárik
Professor of Computer Science
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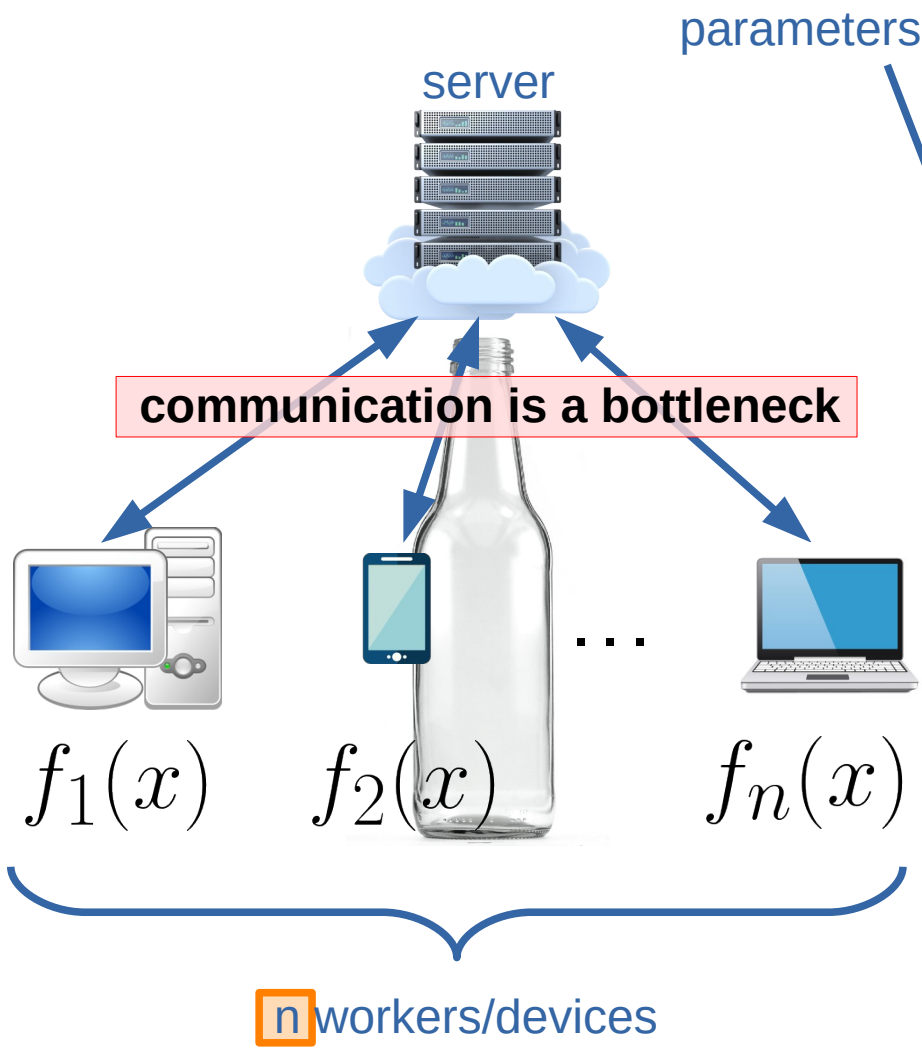
1. The Problem



$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{n} \sum_{i=1}^n f_i(x) \right\}$$







parameters of the model

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{n} \sum_{i=1}^n f_i(x) \right\}$$

of parameters

of workers/devices

loss on the data accessible by worker i

● $f_i(x) = \mathbf{E}_{\xi_i \sim \mathcal{D}_i} [f_{\xi_i}(x)]$

● $f_i(x) = \frac{1}{m} \sum_{j=1}^m f_{ij}(x)$

How to Handle Communication Bottleneck?

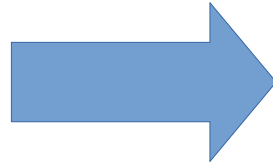
One of the possible solutions: **send less information at communication rounds**

How to Handle Communication Bottleneck?

One of the possible solutions: **send less information at communication rounds**

Workers send dense vectors

$$g = \begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix}$$

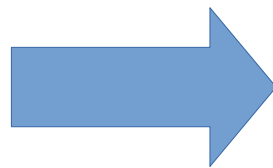


How to Handle Communication Bottleneck?

One of the possible solutions: **send less information at communication rounds**

Workers send dense vectors

$$g = \begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix}$$



Workers send compressed/sparse vectors

$$Q(g) = \frac{5}{2} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ -7 \\ 0 \end{pmatrix}$$

Unbiased compression (quantization)

$$x \rightarrow \mathcal{Q}(x) \quad \mathbb{E}[\mathcal{Q}(x)] = x$$

$$\mathbb{E}\|\mathcal{Q}(x) - x\|^2 \leq \omega\|x\|^2$$

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Example: RandK (for $K = 2$)

$$\begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix} \rightarrow$$

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Example: RandK (for $K = 2$)

$$\begin{pmatrix} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{pmatrix} \longrightarrow \frac{5}{2} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ -7 \\ 0 \end{pmatrix}$$

Pick $K = 2$ components uniformly at random

Unbiased compression (quantization)

$$x \rightarrow \mathcal{Q}(x) \quad \mathbb{E}[\mathcal{Q}(x)] = x$$

$$\mathbb{E}\|\mathcal{Q}(x) - x\|^2 \leq \omega \|x\|^2$$

Example: RandK (for $K = 2$)

$$d = 5 \left\{ \begin{array}{c} \left(\begin{array}{c} 1 \\ -15 \\ 0.2 \\ -7 \\ 10 \end{array} \right) \rightarrow \left(\begin{array}{c} 5 \\ 2 \\ 0 \\ 0 \\ -7 \\ 0 \end{array} \right) \end{array} \right. \quad \omega = \frac{d}{K} - 1$$

for unbiasedness

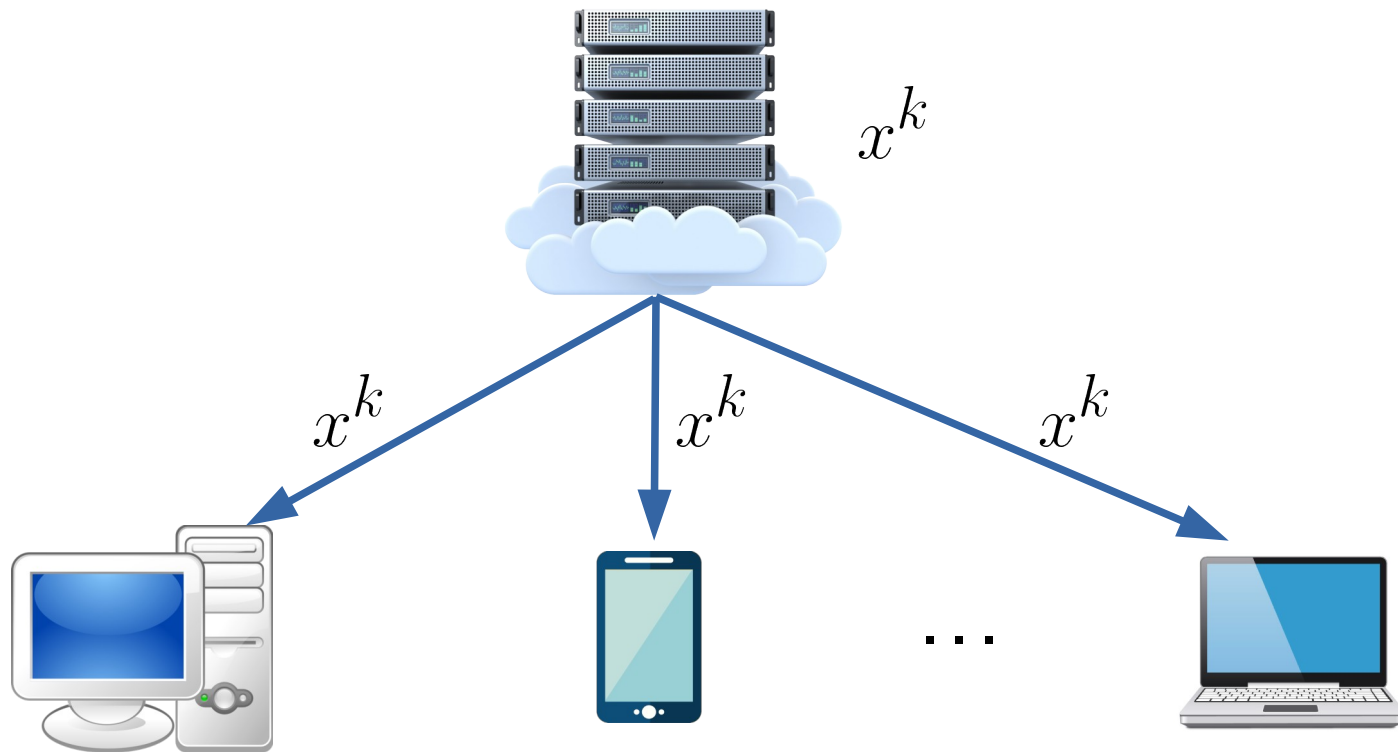
Pick $K = 2$ components uniformly at random

2. Quantized Gradient Descent (QGD)



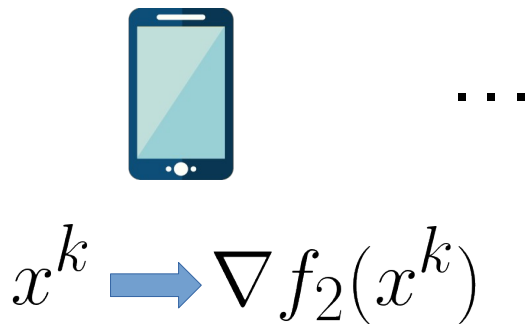
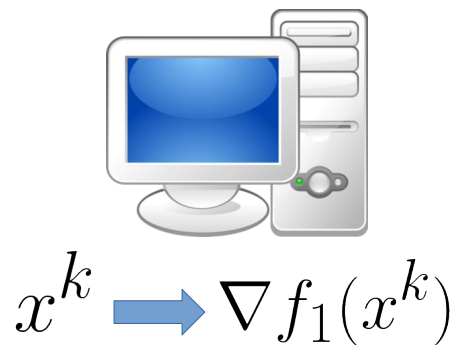
Alistarh, Dan, Demjan Grubic, Jerry Li, Ryota Tomioka, and Milan Vojnovic. "**QSGD: Communication-efficient SGD via gradient quantization and encoding.**" *In Advances in Neural Information Processing Systems*, pp. 1709-1720. 2017.

1 Server broadcasts the parameters

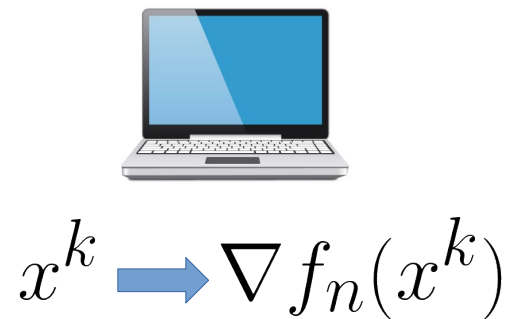


1 Server broadcasts the parameters

2 Devices compute the gradients



...



- 1 Server broadcasts the parameters
- 2 Devices compute the gradients
- 3 Devices quantize the gradients



$$x^k \rightarrow \nabla f_1(x^k)$$

$$g_1^k = \mathcal{Q} \left(\nabla f_1(x^k) \right)$$



$$x^k \rightarrow \nabla f_2(x^k)$$

$$g_2^k = \mathcal{Q} \left(\nabla f_2(x^k) \right)$$

...



$$x^k \rightarrow \nabla f_n(x^k)$$

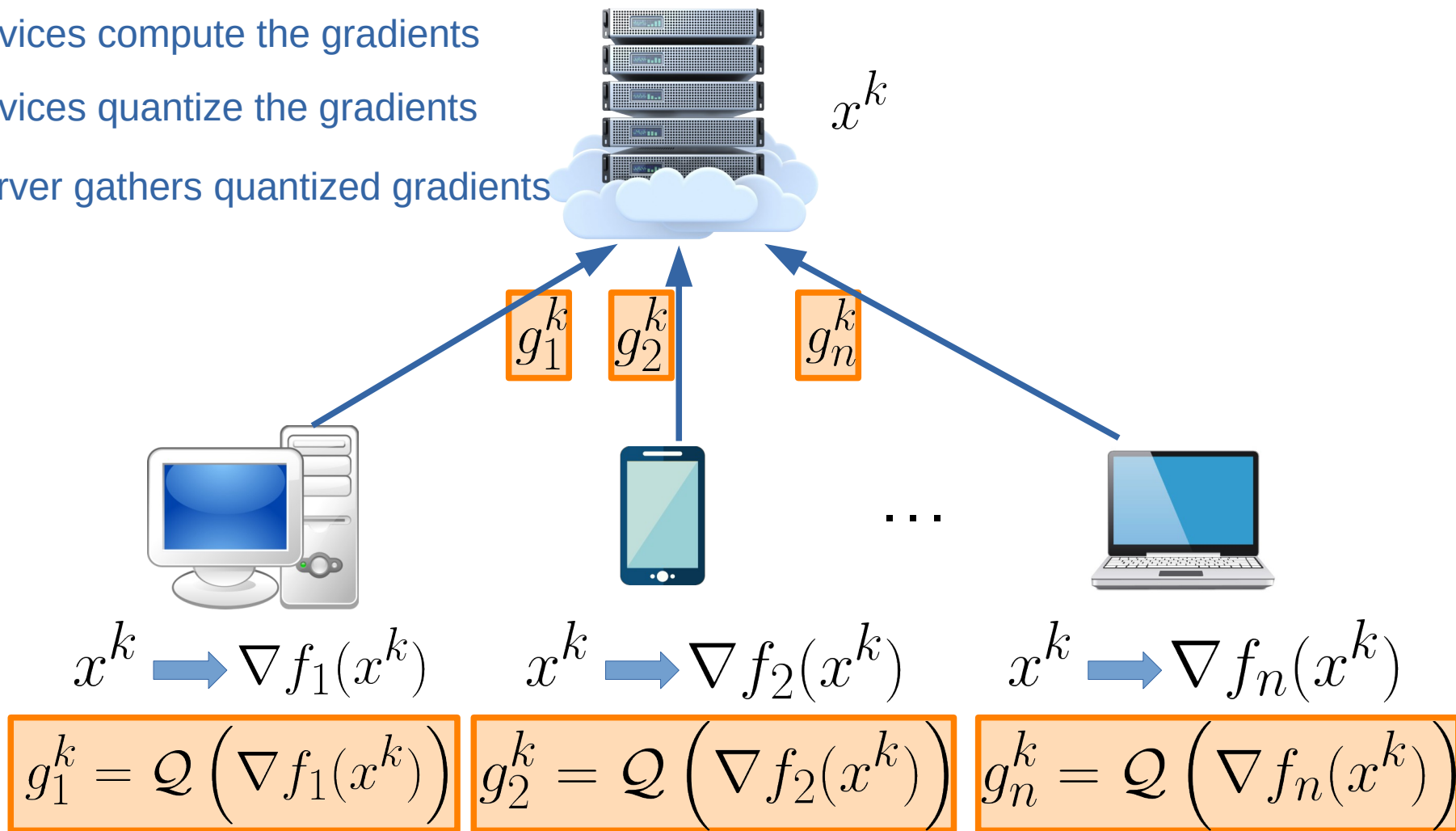
$$g_n^k = \mathcal{Q} \left(\nabla f_n(x^k) \right)$$

1 Server broadcasts the parameters

2 Devices compute the gradients

3 Devices quantize the gradients

4 Server gathers quantized gradients



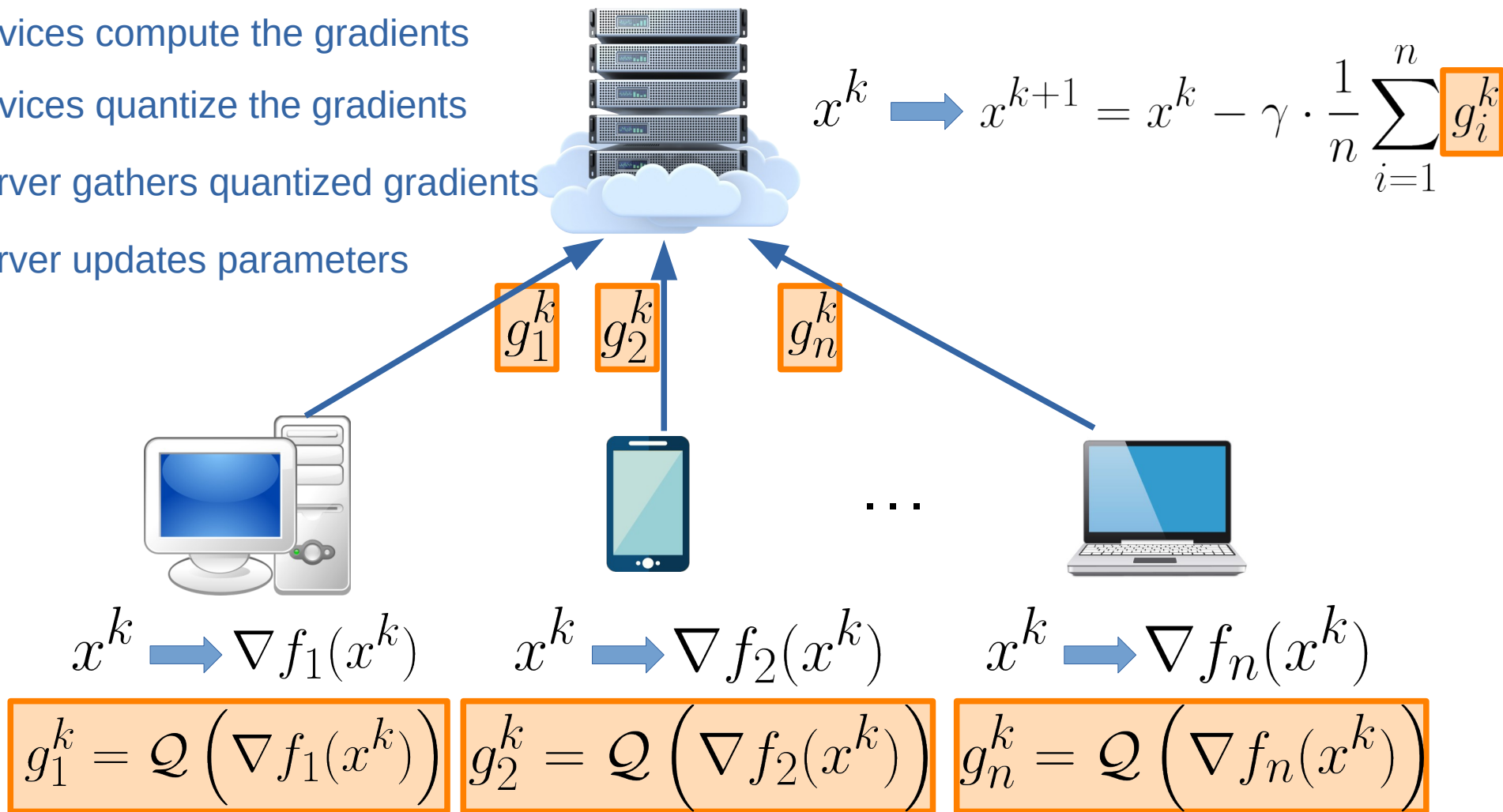
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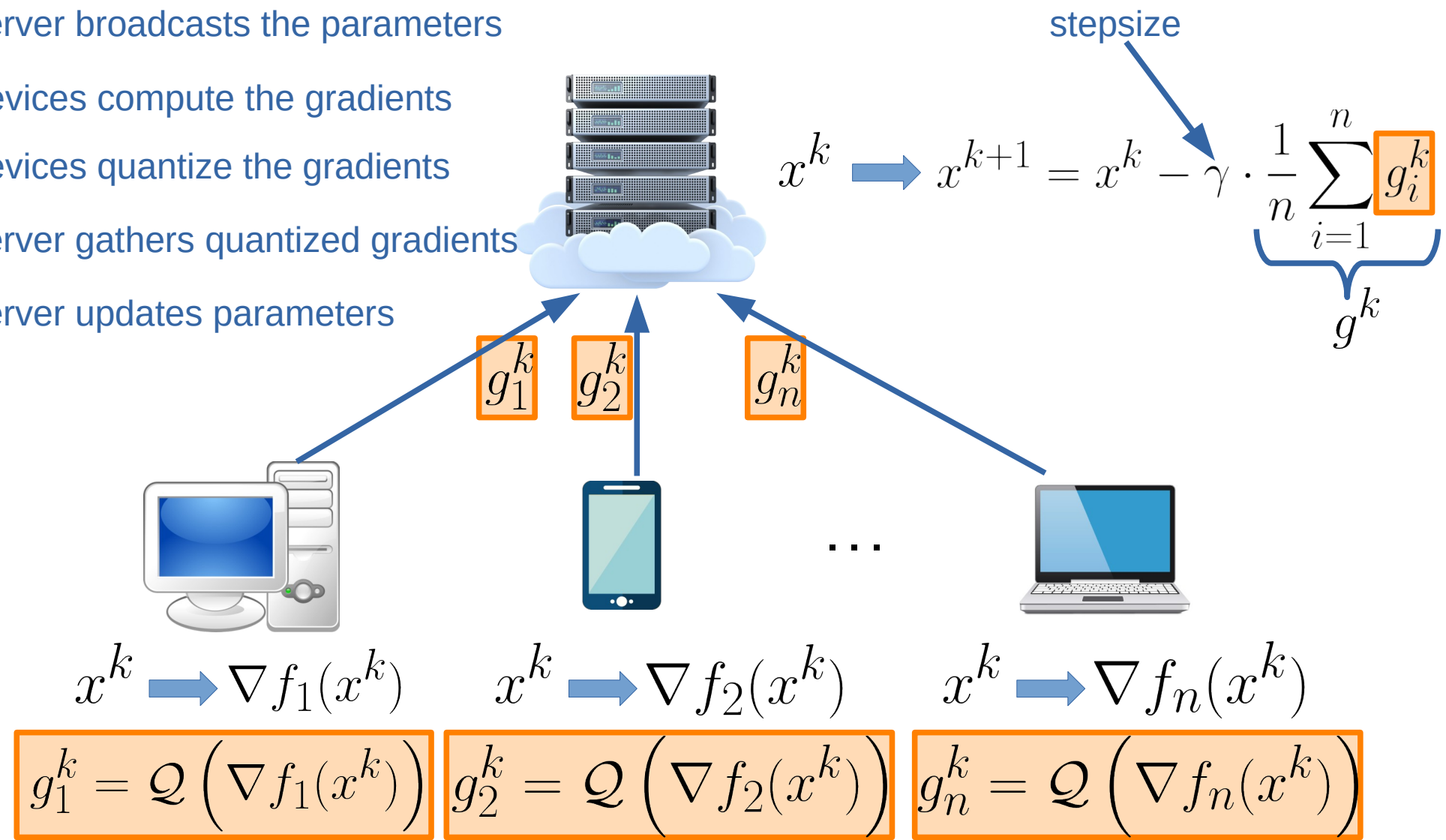
3 Devices quantize the gradients

4 Server gathers quantized gradients

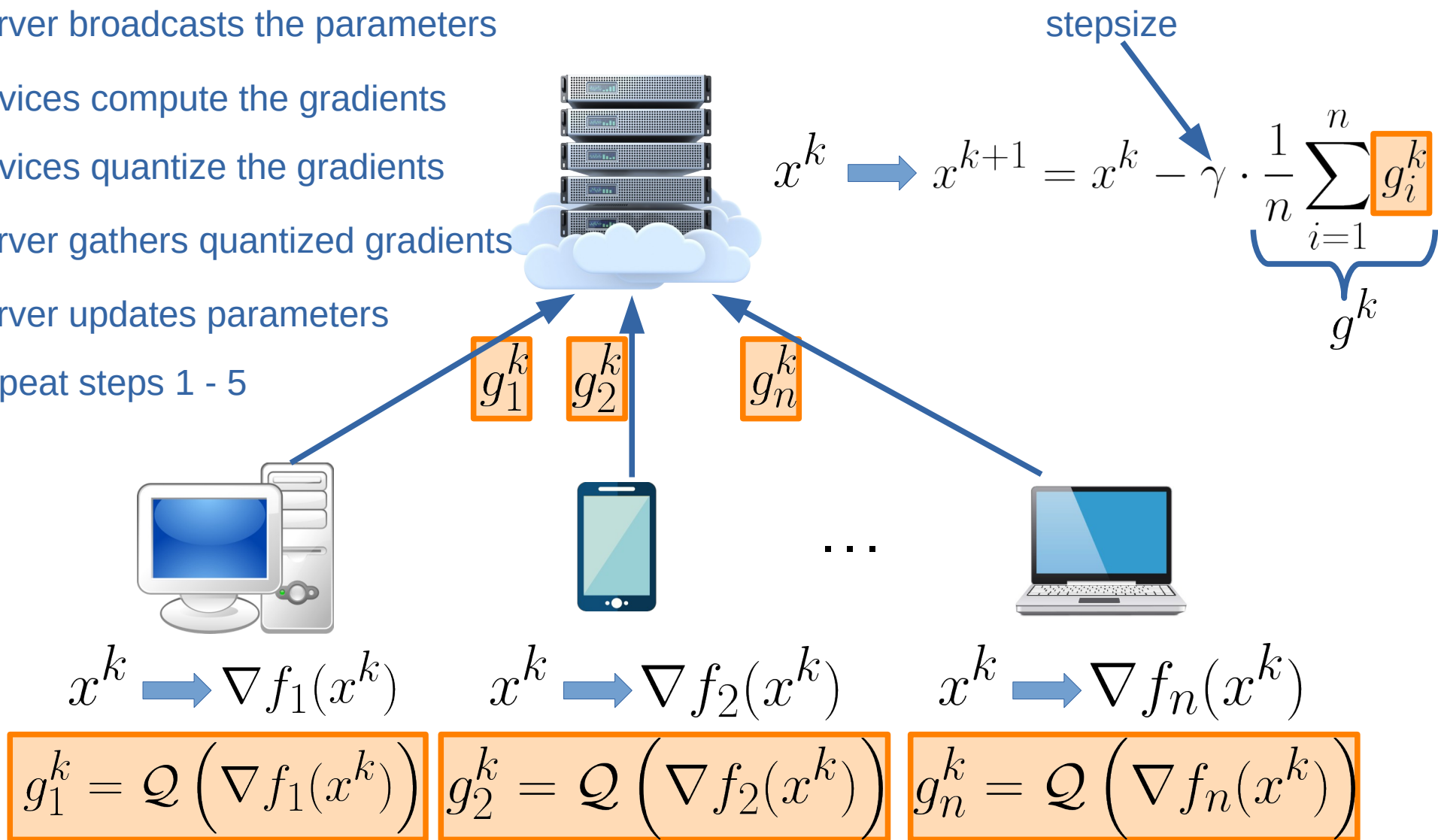
5 Server updates parameters



- 1 Server broadcasts the parameters
- 2 Devices compute the gradients
- 3 Devices quantize the gradients
- 4 Server gathers quantized gradients
- 5 Server updates parameters



- 1 Server broadcasts the parameters
- 2 Devices compute the gradients
- 3 Devices quantize the gradients
- 4 Server gathers quantized gradients
- 5 Server updates parameters
- 6 Repeat steps 1 - 5



Assumptions

1 Uniform lower bound: $\exists f_* \in \mathbb{R} : \forall x \in \mathbb{R}^d \quad f(x) \geq f_*$

2 Smoothness: $\|\nabla f_i(x) - \nabla f_i(y)\| \leq L_i \|x - y\|$

Complexity Bound for QGD



Khaled, Ahmed, and Peter Richtárik. "Better theory for SGD in the nonconvex world." arXiv preprint arXiv:2002.03329 (2020).

QGD finds such \hat{x} that $\mathbb{E} \left[\|\nabla f(\hat{x})\|^2 \right] \leq \varepsilon^2$ after

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$$\mathcal{O} \left(\frac{\Delta_0}{\varepsilon^2} + \frac{(1 + \omega)\Delta_0^2}{\varepsilon^4 n} + \frac{(1 + \omega)\Delta_0 \Delta_f^*}{\varepsilon^4 n} \right) \text{ communication rounds}$$

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Hides
numerical
factors and
smoothness
constants

$$\rightarrow \mathcal{O} \left(\frac{\Delta_0}{\varepsilon^2} + \frac{(1 + \omega)\Delta_0^2}{\varepsilon^4 n} + \frac{(1 + \omega)\Delta_0\Delta_f^*}{\varepsilon^4 n} \right)$$

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$$\mathbb{E} \| Q(x) - x \|^2 \leq \omega \| x \|^2$$

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$$\mathbb{E} \|Q(x) - x\|^2 \leq \omega \|x\|^2$$

$$\Delta_0 = f(x^0) - f_*$$

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$$\Delta_f^* = f_* - \frac{1}{n} \sum_{i=1}^n f_{i,*}$$

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Hides numerical factors and smoothness constants

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$$\mathbb{E} \|Q(x) - x\|^2 \leq \omega \|x\|^2$$

$$\Delta_0 = f(x^0) - f_*$$

Not optimal!

$$\Delta_f^* = f_* - \frac{1}{n} \sum_{i=1}^n f_{i,*}$$

3. DIANA



Mishchenko, Konstantin, Eduard Gorbunov, Martin Takáč, and Peter Richtárik. "**Distributed learning with compressed gradient differences.**" arXiv preprint arXiv:1901.09269 (2019).



Horváth, Samuel, Dmitry Kovalev, Konstantin Mishchenko, Sebastian Stich, and Peter Richtárik. "**Stochastic distributed learning with gradient quantization and variance reduction.**" arXiv preprint arXiv:1904.05115 (2019).

$$x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k$$

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QGD: $g_i^k = \mathcal{Q} \left(\nabla f_i(x^k) \right)$

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QGD: $g_i^k = \mathcal{Q} \left(\nabla f_i(x^k) \right)$

DIANA: $g_i^k = h_i^k + \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$

learnable local shifts

$$h_i^{k+1} = h_i^k + \alpha \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$$

$$x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k$$

QGD:

$$g_i^k = \mathcal{Q} \left(\nabla f_i(x^k) \right)$$

vectors that devices
have to send

DIANA:

$$g_i^k = h_i^k + \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$$

learnable local shifts

$$h_i^{k+1} = h_i^k + \alpha \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$$

Complexity Bounds for DIANA and QGD

QGD: $\mathcal{O} \left(\frac{\Delta_0}{\varepsilon^2} + \frac{(1 + \omega)\Delta_0^2}{\varepsilon^4 n} + \frac{(1 + \omega)\Delta_0\Delta_f^*}{\varepsilon^4 n} \right)$

DIANA: $\mathcal{O} \left(\frac{\Delta_0 \left(1 + (1 + \omega)\sqrt{\omega/n} \right)}{\varepsilon^2} \right)$

Complexity Bound for DIANA

$$\text{QGD: } \mathcal{O} \left(\frac{\Delta_0}{\varepsilon^2} + \frac{(1 + \omega)\Delta_0^2}{\varepsilon^4 n} + \frac{(1 + \omega)\Delta_0\Delta_f^*}{\varepsilon^4 n} \right)$$

Is it possible to get better rates?

$$\text{DIANA: } \mathcal{O} \left(\frac{\Delta_0 \left(1 + (1 + \omega)\sqrt{\omega/n} \right)}{\varepsilon^2} \right)$$

4. MARINA

$$x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k$$

DIANA: $g_i^k = h_i^k + \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$

$$h_i^{k+1} = h_i^k + \alpha \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$$

$$x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k$$

DIANA: $g_i^k = h_i^k + \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$

$$h_i^{k+1} = h_i^k + \alpha \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$$

MARINA: $g_i^k = \begin{cases} \nabla f_i(x^k) \\ g^{k-1} + \mathcal{Q} \left(\nabla f_i(x^k) - \nabla f_i(x^{k-1}) \right) \end{cases}$

w.p. p

w.p. $1 - p$

typically small



$$x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k$$

DIANA: $g_i^k = h_i^k + \mathcal{Q} \left(\nabla f_i(x^k) - \boxed{h_i^k} \right)$ ← vectors that devices have to send

$$h_i^{k+1} = h_i^k + \alpha \mathcal{Q} \left(\nabla f_i(x^k) - h_i^k \right)$$

MARINA: $g_i^k = \begin{cases} \boxed{\nabla f_i(x^k)} & \text{w.p. } p \\ g^{k-1} + \mathcal{Q} \left(\nabla f_i(x^k) - \boxed{\nabla f_i(x^{k-1})} \right) & \text{w.p. } 1 - p \end{cases}$

← typically small

$$x^{k+1} = x^k - \gamma \cdot \frac{1}{n} \sum_{i=1}^n g_i^k = x^k - \gamma g^k$$

DIANA: $g_i^k = h_i^k + \mathcal{Q}(\nabla f_i(x^k) - h_i^k)$ ← vectors that devices have to send

$$h_i^{k+1} = h_i^k + \alpha \mathcal{Q}(\nabla f_i(x^k) - h_i^k) \mathbb{E}[g^k | x^k] = \nabla f(x^k)$$

typically small

MARINA: $g_i^k = \begin{cases} \nabla f_i(x^k) & \text{w.p. } p \\ g^{k-1} + \mathcal{Q}(\nabla f_i(x^k) - \nabla f_i(x^{k-1})) & \text{w.p. } 1-p \end{cases}$

$$\mathbb{E}[g^k | x^k] \neq \nabla f(x^k)$$

Complexity Bound for MARINA

MARINA finds such \hat{x} that $\mathbb{E} \left[\|\nabla f(\hat{x})\|^2 \right] \leq \boxed{\varepsilon^2}$ after

Hides numerical factors and smoothness constants

$$\mathcal{O} \left(\frac{\boxed{\Delta_0} \left(1 + \boxed{\omega} / \sqrt{n} \right)}{\boxed{\varepsilon^2}} \right)$$

communication rounds

$$\mathbb{E} \| \mathcal{Q}(x) - x \|^2 \leq \omega \|x\|^2$$

$$\Delta_0 = f(x^0) - f_*$$

$$p = \frac{1}{\omega + 1} = \Theta \left(\frac{\boxed{\zeta_{\mathcal{Q}}}}{d} \right)$$

$$\boxed{\zeta_{\mathcal{Q}}} = \sup_{x \in \mathbb{R}^d} \mathbb{E} [\| \mathcal{Q}(x) \|_0]$$

assumption (holds for RandK, I2-quantization)

expected density

Complexity Bounds for MARINA and DIANA

DIANA: $\mathcal{O} \left(\frac{\Delta_0 \left(1 + (1 + \omega) \sqrt{\omega/n} \right)}{\varepsilon^2} \right)$

MARINA: $\mathcal{O} \left(\frac{\Delta_0 \left(1 + \omega / \sqrt{n} \right)}{\varepsilon^2} \right)$

5. Extra Results

In the paper, we also have:

- Variance Reduced MARINA (uses stochastic gradients instead of full gradients)
- MARINA with partial participation of clients
- Rates under Polyak- Lojasiewicz Condition
- Explicit dependencies on smoothness constants, non-uniform sampling
- Simple proofs
- Numerical experiments with generalized linear models and neural networks

If you have any questions, feel free to write me on my email eduard.gorbunov@phystech.edu
...or just find me at the poster session :-)