

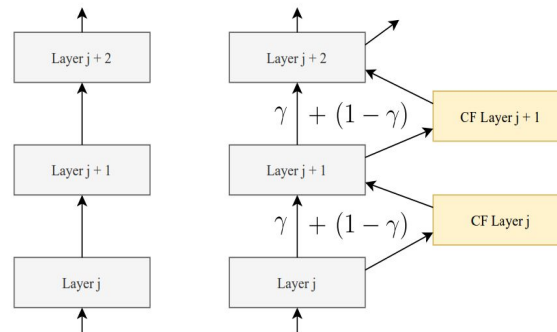
Automatic variational inference with cascading flows

Luca Ambrogioni, Gianluigi Silvestri and Marcel van Gerven

$$p(\mathbf{x}) = \prod_t \mathcal{N}(x_t; \mu(x_t), s^2(x_t))$$

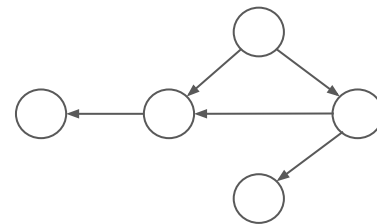


$$q_{\mathbf{w}}(\mathbf{x}) = \prod_j^N \mathcal{T}_j^{\mathbf{w}} [\rho_j(\cdot | \theta_j(\boldsymbol{\pi}_j))] (x_j)$$





Differentiable probabilistic programming



Joint Distribution

Parents of j-th variable

$$p(\mathbf{x}) = \prod_{j=1}^N \rho_j(x_j \mid \theta_j(\boldsymbol{\pi}_j))$$

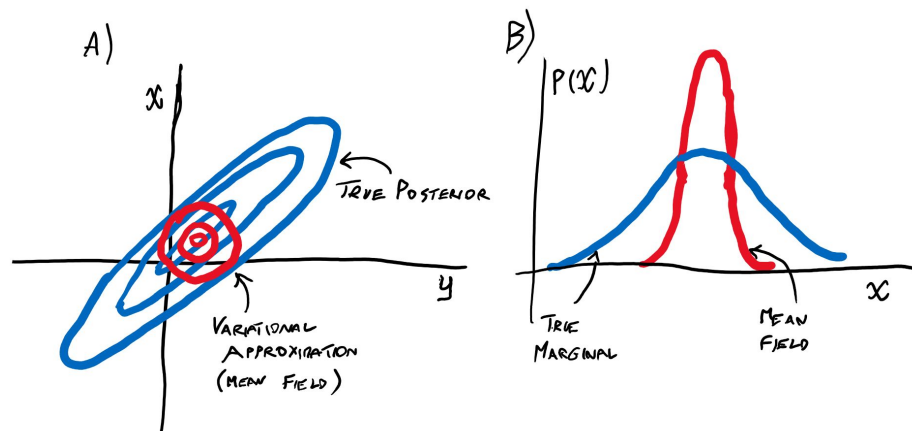
Re-parameterized
distribution of j-th variable

Link function



VI performance depends on the variational parameterization

$$q(\mathbf{x}; \boldsymbol{\psi}) = \prod_k q_k(x_k; \psi_k)$$

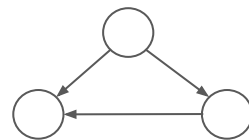
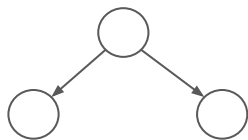


$$\nu = \sigma^2(1 - \rho^2)$$



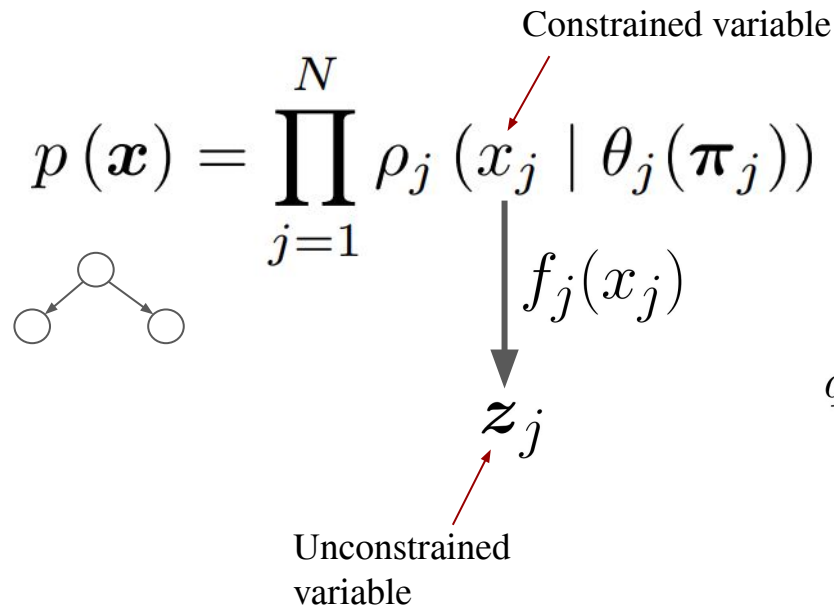
Automatic construction of structured variational families

$$p(\mathbf{x}) \mapsto q(\mathbf{x}; \psi)$$





Automatic differentiation variational inference



Mean-field ADVI

$$q(\mathbf{x}) = \prod_j \left(\frac{df_j(x_j)}{dx_j} \right)^{-1} \mathcal{N}(f_j^{-1}(x_j); \mu_k, s_k^2)$$

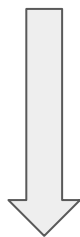
Multivariate normal ADVI

$$q(\mathbf{x}) = \mathcal{N}(\mathbf{f}^{-1}(\mathbf{x}); \boldsymbol{\mu}, HH^T) \prod_j \left(\frac{df_j(x_j)}{dx_j} \right)^{-1}$$



ASVI preserves the forward pass of the model

$$p(\mathbf{x}) = \prod_t \mathcal{N}(x_t; \mu(x_t), s^2(x_t))$$



$$q(\mathbf{x}) = \prod_t \mathcal{N}(x_t; \lambda_t^\mu \mu(x_t) + (1 - \lambda_t^\mu) \alpha_t^\mu, \lambda_t^s s^2(x_t) + (1 - \lambda_t^s) \alpha_t^s)$$

Gate parameters

Perturbation parameters



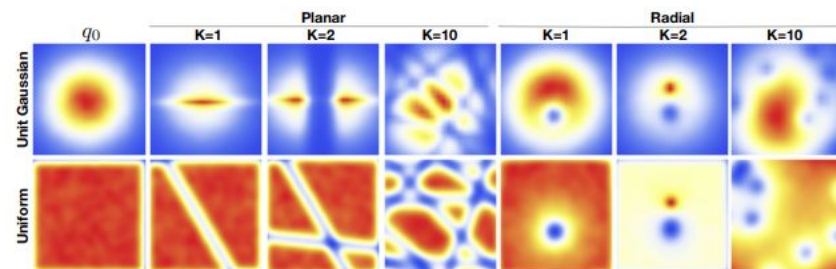
Variational inference with normalizing flows

Normal distribution

Non-linear transformation

$$p_X(x) = |\det J(\Psi^{-1}(x))| p_0(\Psi^{-1}(x))$$

Volume distortion factor





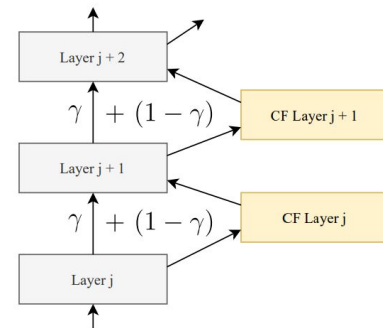
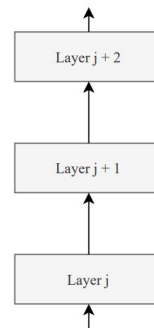
ASVI with cascading flows

$$p(\mathbf{x}) = \prod_t \mathcal{N}(x_t; \mu(x_t), s^2(x_t))$$



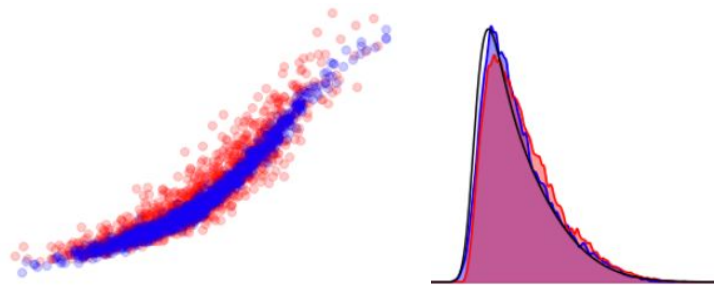
$$q_{\mathbf{w}}(\mathbf{x}) = \prod_j^N \mathcal{T}_j^{\mathbf{w}} [\rho_j(\cdot | \theta_j(\boldsymbol{\pi}_j))] (x_j)$$

Push-forward of non-linear transformation (normalizing flow)





Highway flow architecture



1. Upper triangular highway layer:

$$l_U(z; U, \lambda) = \lambda z + (1 - \lambda)(Uz + b_U) \quad (9)$$

$$\log \det J_U = \sum_k \log(\lambda + (1 - \lambda)U_{kk}) \quad (10)$$

2. Lower triangular layer:

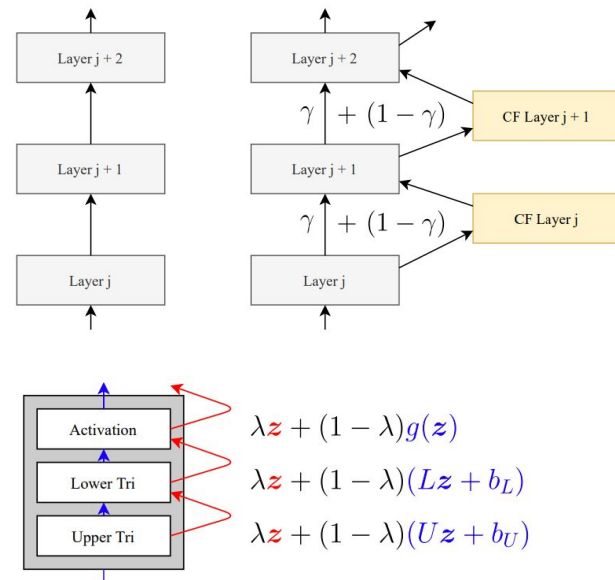
$$l_L(z; L, \lambda) = \lambda z + (1 - \lambda)(Lz + b_L) \quad (11)$$

$$\log \det J_L = \sum_k \log(\lambda + (1 - \lambda)L_{kk}) \quad (12)$$

3. Highway activation functions:

$$f(z; \lambda) = \lambda z + (1 - \lambda)g(z) \quad (13)$$

$$\log \det \frac{df(x_k)}{dx} = \sum_k \log \left(\lambda + (1 - \lambda) \frac{dg(x_k)}{dx} \right) \quad (14)$$





Hierarchical variational inference and auxiliary variables

$$q(x_j, \epsilon_j | \pi_j) = \hat{\mathcal{T}}_j^w [\rho_j(\cdot | \theta_j(\pi_j)) p_j(\cdot)](x_j, \epsilon_j)$$

$$q(x_j | \pi_j) = \int q(x_j, \epsilon_j | \pi_j) d\epsilon_j$$

Ranganath, Rajesh, Dustin Tran, and David Blei. "Hierarchical variational models." *International Conference on Machine Learning*. PMLR, 2016.

Caterini, Anthony, et al. "Variational Inference with Continuously-Indexed Normalizing Flows." *arXiv preprint arXiv:2007.05426* (2020).

Ambrogioni, Luca, Gianluigi Silvestri, and Marcel van Gerven. "Automatic variational inference with cascading flows." *arXiv preprint arXiv:2102.04801* (2021).



Hierarchical variational inference and auxiliary variables

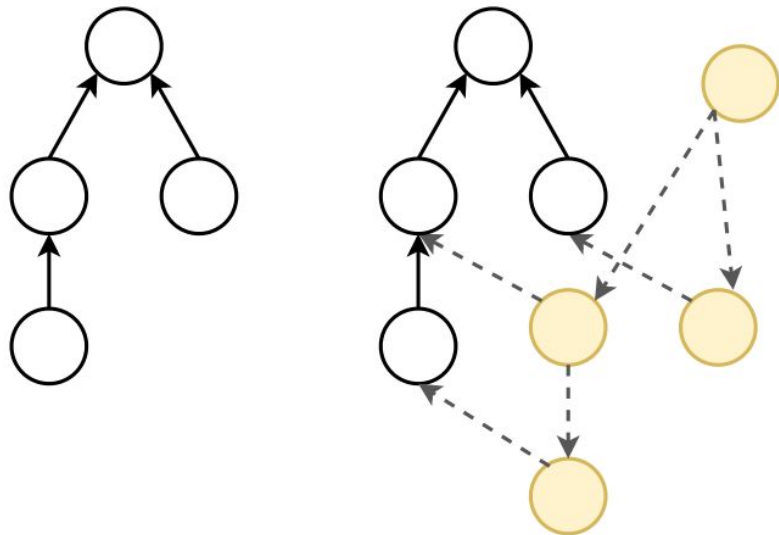
$$q(x_j | \pi_j) = \int q(x_j, \epsilon_j | \pi_j) d\epsilon_j$$

$$\mathbb{E}_{\mathbf{x}} \left[\log \frac{p(\mathbf{x}, \mathbf{y})}{\int q(\mathbf{x}, \epsilon) d\epsilon} \right] \geq \underbrace{\mathbb{E}_{\mathbf{x}, \epsilon} \left[\log \frac{p(\mathbf{x}, \mathbf{y}) r(\epsilon)}{q(\mathbf{x}, \epsilon)} \right]}_{\text{Augmented ELBO}}$$



Backward coupling and amortization

$$\epsilon_k \mid \mathbf{v}_k = \mathcal{B}^{(k)}[y_k] + \sum_{j=1}^K a_j \odot \mathbf{v}_j + a_0 \odot \xi_k$$





Experimental results

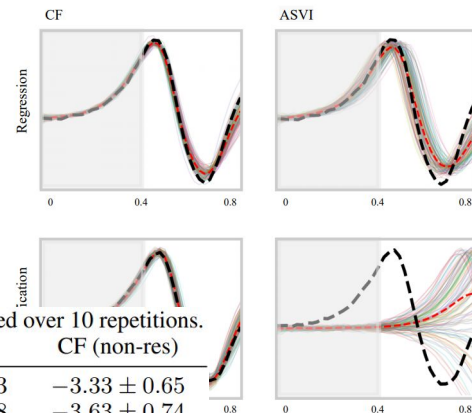


Table 1. Predictive and latent log-likelihood (forward KL) of variational timeseries models. Error are SEM estimated over 10 repetitions.

		CF	ASVI	MF	GF	MVN	CF (non-res)
BR-r	Pred	-2.27 ± 0.26	-2.23 ± 0.21	-3.79 ± 0.82	-2.81 ± 0.56	-2.88 ± 0.53	-3.33 ± 0.65
	Latent	-1.48 ± 0.19	-1.45 ± 0.14	-4.02 ± 0.63	-2.41 ± 0.52	-2.02 ± 0.48	-3.63 ± 0.74
BR-c	Pred	1.61 ± 0.18	1.45 ± 0.14	1.04 ± 0.03	2.00 ± 0.29	1.02 ± 0.03	1.31 ± 0.18
	Latent	-1.53 ± 0.21	-1.55 ± 0.19	-5.78 ± 0.89	-2.06 ± 0.53	-2.82 ± 0.77	-5.07 ± 0.85
LZ-r	Pred	-2.89 ± 0.17	-4.48 ± 0.60	-8.26 ± 0.28	-8.03 ± 0.37	-8.24 ± 0.29	-8.25 ± 0.27
	Latent	-2.39 ± 0.45	-4.38 ± 0.67	-10.28 ± 0.18	-9.44 ± 0.20	-9.45 ± 0.22	-10.00 ± 0.18
LZ-c	Pred	5.10 ± 0.52	0.92 ± 0.03	0.90 ± 0.003	0.86 ± 0.15	0.89 ± 0.001	0.88 ± 0.04
	Latent	-4.19 ± 0.66	-7.47 ± 0.30	-9.89 ± 0.19	-8.71 ± 0.32	-8.58 ± 0.34	-9.59 ± 0.29
PD-r	Pred	-3.19 ± 0.22	-3.25 ± 0.11	-4.42 ± 0.22	-3.84 ± 0.28	-4.30 ± 0.22	-4.29 ± 0.25
	Latent	-2.32 ± 0.19	-3.14 ± 0.12	-9.12 ± 0.29	-4.16 ± 0.33	-7.72 ± 0.30	-8.27 ± 0.36
PD-c	Pred	1.97 ± 0.07	1.65 ± 0.06	0.86 ± 0.003	01.07 ± 0.02	1.09 ± 0.02	0.96 ± 0.01
	Latent	-2.77 ± 0.18	-3.09 ± 0.15	-8.40 ± 0.43	-6.20 ± 0.40	-7.45 ± 0.42	-8.41 ± 0.43
RNN-r	Pred	-1.68 ± 0.05	-2.30 ± 0.18	-5.20 ± 0.94	-1.60 ± 0.09	-4.47 ± 0.92	-1.97 ± 0.21
	Latent	-1.34 ± 0.33	-1.95 ± 0.35	-10.30 ± 0.20	-6.39 ± 1.27	-6.61 ± 0.50	-10.47 ± 0.22
RNN-c	Pred	5.77 ± 1.40	1.05 ± 0.06	0.81 ± 0.03	2.81 ± 0.36	0.86 ± 0.02	1.39 ± 0.04
	Latent	-2.30 ± 0.61	-2.05 ± 0.32	-10.22 ± 0.29	-10.75 ± 0.15	-10.22 ± 0.29	-11.22 ± 0.04

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