

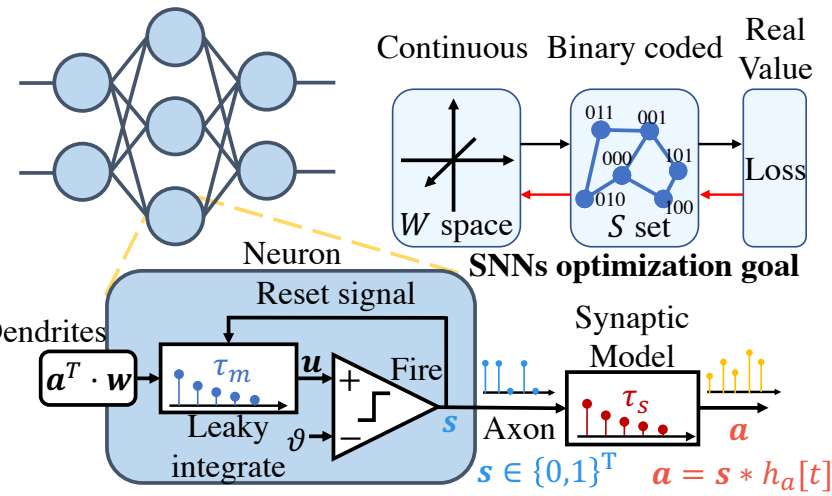


Backpropagated Neighborhood Aggregation for Accurate Training of Spiking Neural Networks

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Take home info:
A New Algorithm to Train SNN with Higher Accuracy!

Forward



(a) Forward path of Leaky Integrate-and-Fire SNNs and the generic optimization framework

$$u_i^{(l)}[t+1] = \left(1 - \frac{1}{\tau_m}\right) u_i^{(l)}[t] \left(1 - s_i^{(l)}[t]\right) + \sum_{j=1}^{N^{(l-1)}} w_{ij}^{(l)} a_j^{(l-1)}[t+1]$$

$$a_i^{(l)} = s_i^{(l)} * \sigma, \quad \sigma[t] = \frac{1}{\tau_s} \left(1 - \frac{1}{\tau_s}\right)^t$$

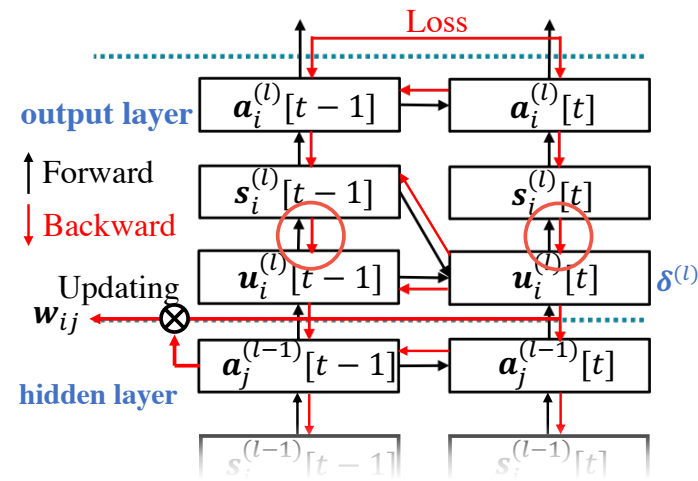
$$a_i^{(l)}[t+1] = \left(1 - \frac{1}{\tau_s}\right) a_i^{(l)}[t] + \left(\frac{1}{\tau_s}\right) s_i^{(l)}[t+1]$$

$$s_i^{(l)}[t] = H(u_i^{(l)}[t] - \vartheta)$$

$$L = \sum_{t=0}^{N_t} E[t] = \sum_{t=0}^{N_t} \frac{1}{2} \left((\sigma * d)[t] - (\sigma * s)[t] \right)^2$$

$$= \sum_{t=0}^{N_t} \frac{1}{2} \left((\sigma * d)[t] - a[t] \right)^2$$

BPTT's Difficulty

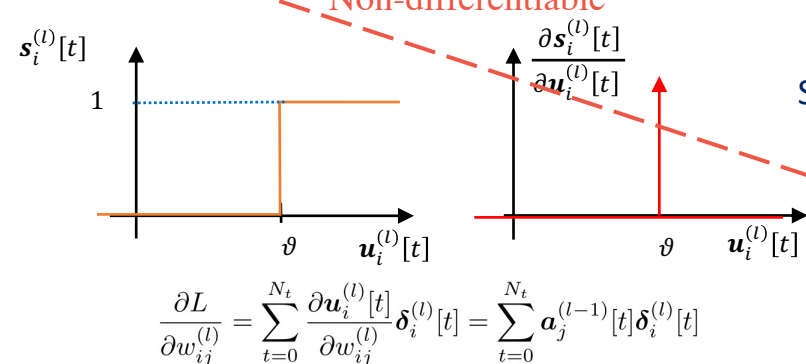


(b) Typical backpropagation through time dataflow

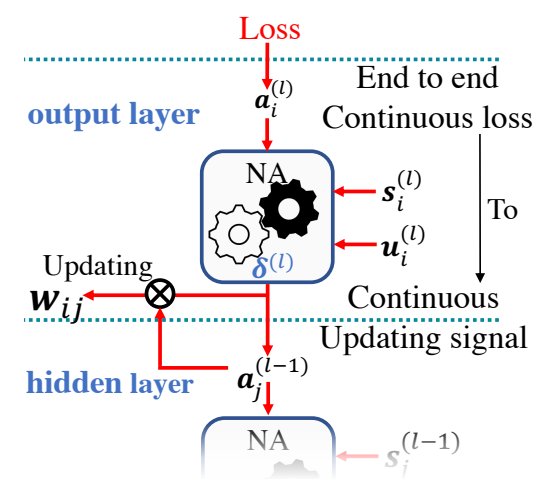
$$g_i^{(l)} = \begin{cases} a_i^{(l)} - (\sigma * d_i), & \text{output layer} \\ \sum_{p=1}^{N^{(l+1)}} w_{ji}^{(l+1)} \delta_p^{(l+1)}, & \text{hidden layer} \end{cases}$$

$$e_i^{(l)}[t] = \begin{cases} g_i^{(l)}[t], & t = N_t \\ g_i^{(l)}[t] + \frac{\partial a_i^{(l)}[t+1]}{\partial u_i^{(l)}[t]} e_i^{(l)}[t+1], & t < N_t \end{cases}$$

$$\delta_i^{(l)}[t] = \begin{cases} e_i^{(l)}[t] \frac{\partial a_i^{(l)}[t]}{\partial u_i^{(l)}[t]}, & t = N_t \\ e_i^{(l)}[t] \frac{\partial a_i^{(l)}[t]}{\partial u_i^{(l)}[t]} + \delta_i^{(l)}[t+1] \frac{\partial u_i^{(l)}[t+1]}{\partial u_i^{(l)}[t]}, & t < N_t \end{cases}$$



Our NA Algorithm



(c) Neighborhood aggregation (NA) algorithm

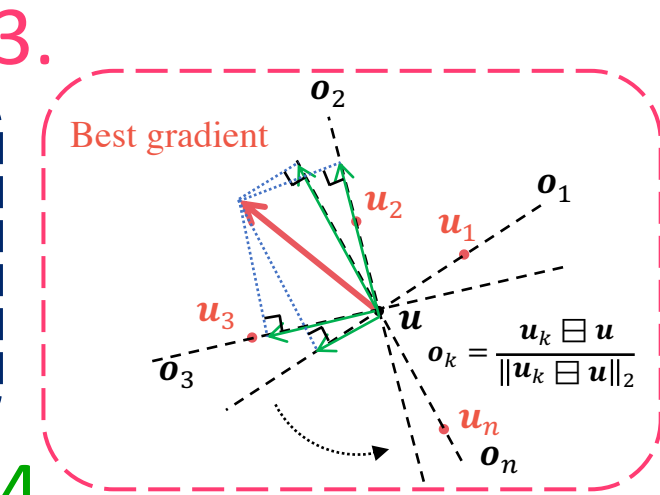
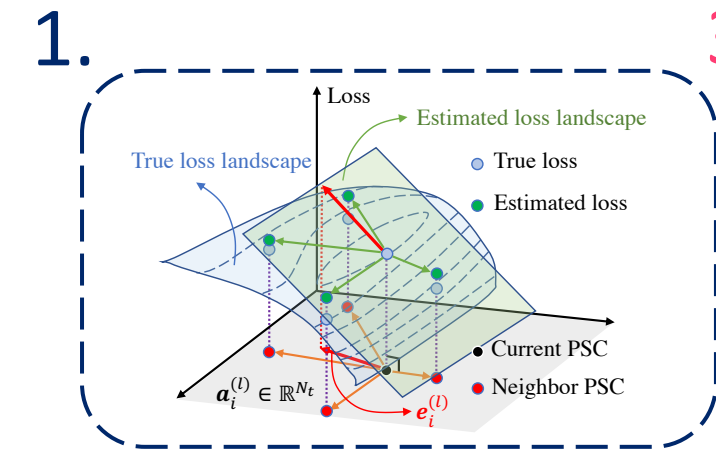
$$1. \quad f_{d(u, u_p)} L = \frac{L(u_p) - L(u)}{d_{MP}(u, u_p)} \approx \frac{e \cdot (a_p - a)}{d_{MP}(u, u_p)}$$

$$L(u_p) - L(u) = L(a_p) - L(a) \approx \nabla_a L(a_p - a) = e \cdot (a_p - a)$$

$$2. \quad d_{MP}(u, u') = \|u' \boxminus u\|_2$$

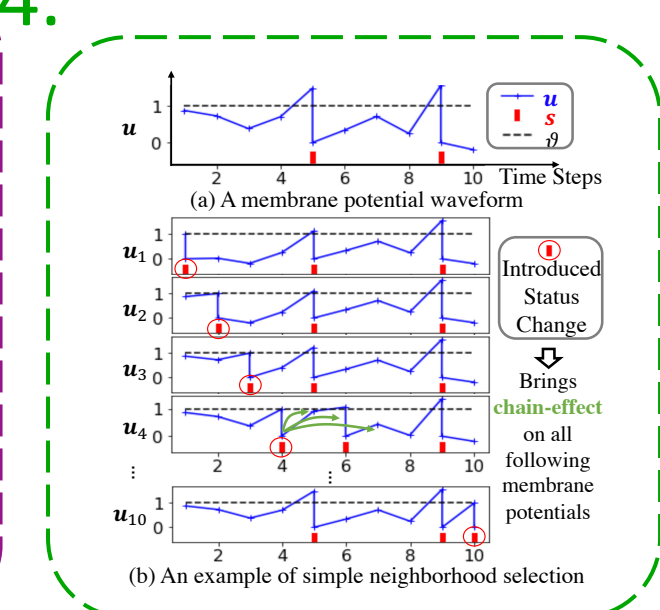
$$3. \quad \begin{bmatrix} o_1^T \\ o_2^T \\ \vdots \\ o_M^T \end{bmatrix} \cdot \tilde{\nabla}_u L = \begin{bmatrix} f_d(u, u_1) L \\ f_d(u, u_2) L \\ \vdots \\ f_d(u, u_M) L \end{bmatrix}, \quad \tilde{\nabla}_u L = \begin{bmatrix} o_1^T \\ o_2^T \\ \vdots \\ o_M^T \end{bmatrix}^+ \begin{bmatrix} f_d(u, u_1) L \\ f_d(u, u_2) L \\ \vdots \\ f_d(u, u_M) L \end{bmatrix}$$

$$4. \quad \delta \approx \tilde{\nabla}_u L = \begin{bmatrix} f_d(u, u_1) L \\ f_d(u, u_2) L \\ \vdots \\ f_d(u, u_M) L \end{bmatrix}$$

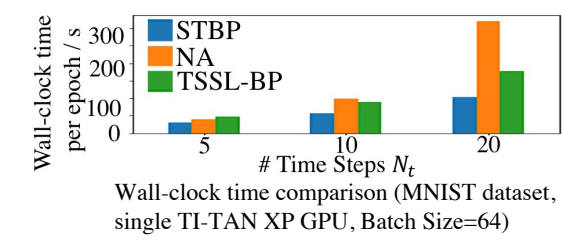


Algorithm 1 Membrane potential addition: $u' = u \boxplus \epsilon$
Inputs: u, ϵ ; **Output:** u' ; ϑ : firing threshold;
Initialization: $u = 0$;
 $c = f^{-1}(u)$;
for t in $\text{range}(1, N_t)$:
 $u'[t] = u \left(1 - \frac{1}{\tau_m}\right) + \epsilon[t] + c[t]$;
 $u = u'[t] (1 - H(u'[t] - \vartheta))$;
return u'

Algorithm 2 Membrane potential subtraction: $\epsilon = u' \boxminus u$
Inputs: u, u' ; **Output:** ϵ ; ϑ : firing threshold;
initialization: $u = 0$;
 $c = f^{-1}(u)$;
for t in $\text{range}(1, N_t)$:
 $u[t] = u \left(1 - \frac{1}{\tau_m}\right) + c[t]$;
 $\epsilon[t] = u'[t] - u[t]$;
 $u = u'[t] (1 - H(u'[t] - \vartheta))$;
return ϵ



Experimental Results



MNIST			
Method	#Steps	BestAcc	
HM2BP (Jin et al., 2018)	400	99.49%	
ST-RSBP (Zhang & Li, 2019)	400	99.62%	
SLAYER (Shrestha & Orchard, 2018)	300	99.41%	
STBP (Wu et al., 2018)	30	99.42%	
TSSL-BP (Zhang & Li, 2020)	5	99.53%	
This work	5	99.69%	

CIFAR10			
Methods	Structure	#Time steps	Best accuracy
STBP	AlexNet	12	85.24%
STBP	CifarNet	12	90.53%
TSSL-BP	AlexNet	5	89.22%
This work	AlexNet	5	91.76%

AlexNet structure: 96C3-256C3-P2-384C3-P2-384C3-256C3-1024-1024
 CifarNet structure: 128C3-256C3-P2-512C3-P2-1024C3-512C3-1024-512

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