

Autoregressive Denoising Diffusion Models for Multivariate Probabilistic Time Series Forecasting

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Neural Probabilistic Forecasts

- Probabilistic forecasts account for uncertainty
- Individual time series can be statistically dependant
- Model needs to account for this via **multivariate forecasts**
 - e.g. in traffic flow a disruption will ripple to nearby streets etc.
 - can resort to low-rank approximation or diagonal distribution
 - can use normalizing flows or GANs

This work proposes a denoising diffusion based model for probabilistic multivariate time series forecasting.

Diffusion Models (Sohl-Dickstein et al. 2015)

- A class of latent variable models for $\mathbf{x}^0 \in \mathbb{R}^D$ with $\mathbf{x}^0 \sim q(\mathbf{x}^0)$:

$$p_\theta(\mathbf{x}^0) := \int p_\theta(\mathbf{x}^{0:N}) d\mathbf{x}^{1:N}$$

- N latents: $\mathbf{x}^1, \dots, \mathbf{x}^N \in \mathbb{R}^D$
- **Fixed** diffusion (forward) process is a Markov chain that adds noise via given β_1, \dots, β_N , with $\beta_n \in [0, 1]$:

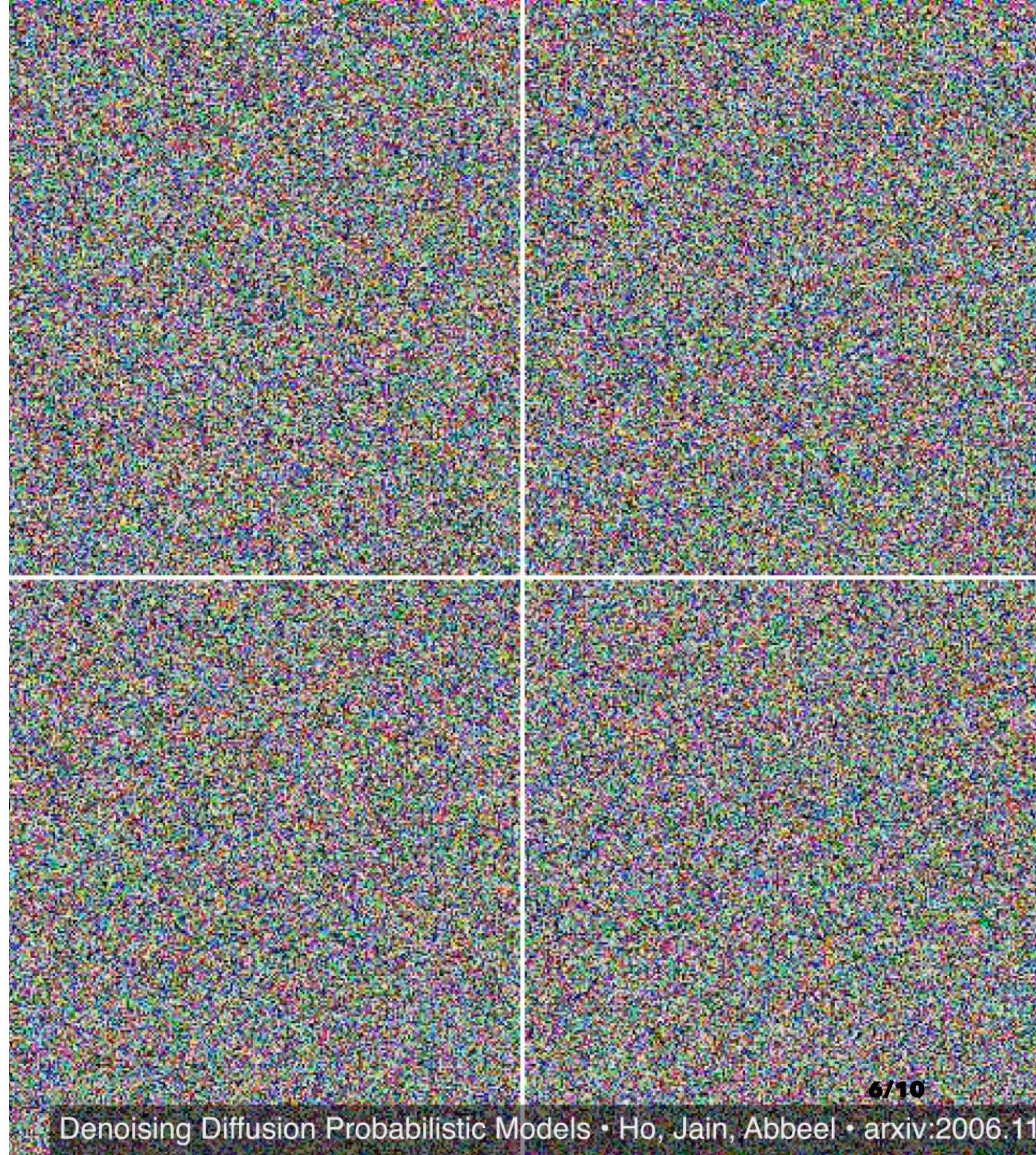
$$q(\mathbf{x}^n | \mathbf{x}^{n-1}) := \mathcal{N}(\mathbf{x}^n; \sqrt{1 - \beta_n} \mathbf{x}^{n-1}, \beta_n \mathbf{I})$$

Reverse Process

- Joint $p_{\theta}(\mathbf{x}^{0:N}) := p(\mathbf{x}^N) \prod_{n=N}^1 p_{\theta}(\mathbf{x}^{n-1} | \mathbf{x}^n)$ is a **learned** Markov chain
- Start from $p(\mathbf{x}^N) \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- Each transition is given by Gaussian with shared parameters:
 $p_{\theta}(\mathbf{x}^{n-1} | \mathbf{x}^n) := \mathcal{N}(\mathbf{x}^{n-1}; \mu_{\theta}(\mathbf{x}^n, n), \sigma_{\theta}(\mathbf{x}^n, n)\mathbf{I})$
 - Where $\mu_{\theta}: \mathbb{R}^D \times \mathbb{N} \rightarrow \mathbb{R}^D$ and $\sigma_{\theta}: \mathbb{R}^D \times \mathbb{N} \rightarrow \mathbb{R}^+$ are neural networks

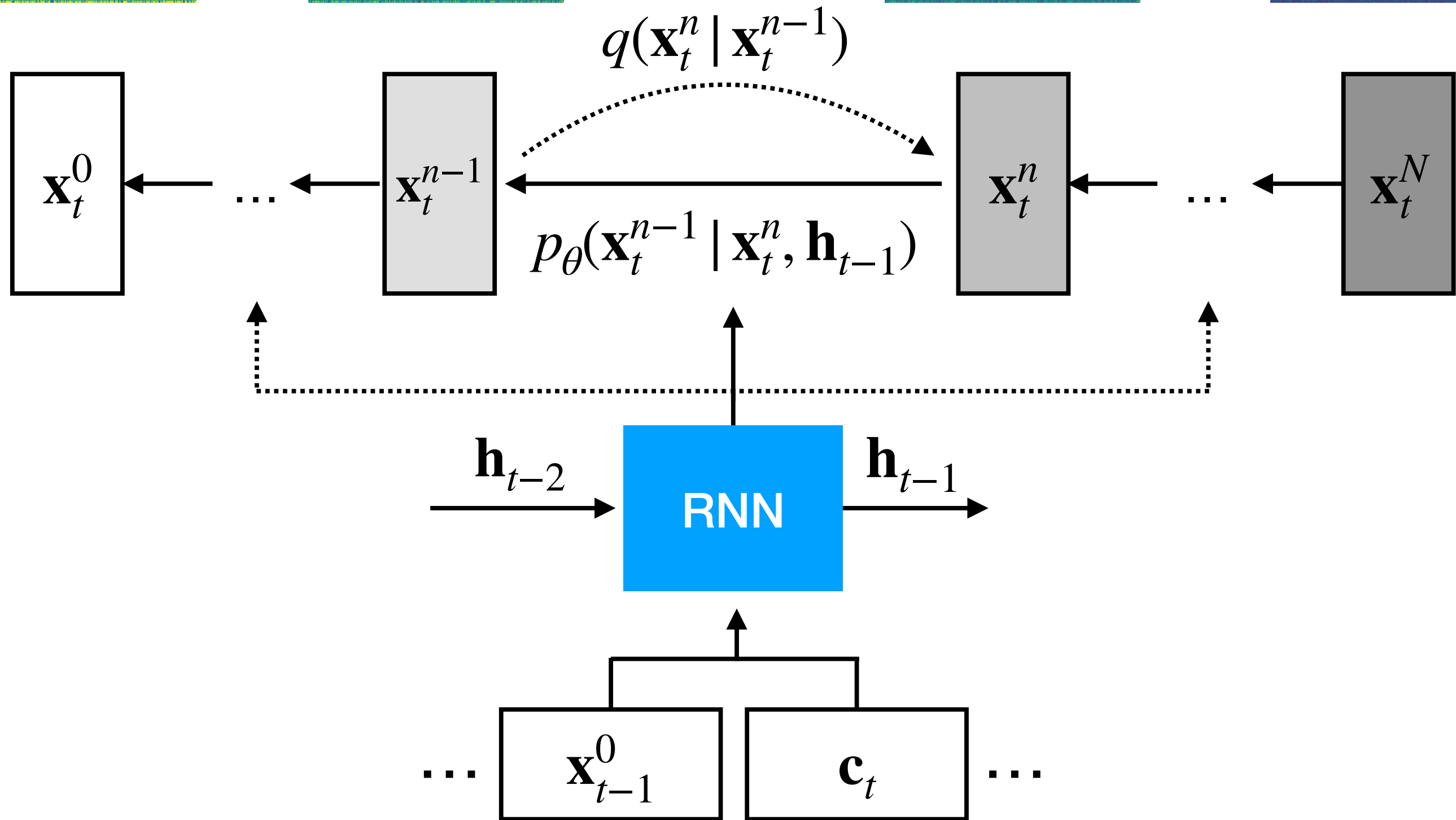
High level intuition

- Sample from distribution by gradual reversal of noising process
- Starting with white noise the learned model produces slightly less noisy signal
- Repeating this N times gives us a data sample
- **Training** can be expressed as a regression problem!
- Can learn complex distributions (Ho et al. 2020)



TimeGrad

- We could learn $p_{\theta}(\mathbf{x}_t^0 | \mathbf{h}_{t-1})$ using a conditional Denoising Diffusion Model for each t
- \mathbf{h}_t state of an RNN from the history of the time series and covariate
- Again: minimizing $-\log p_{\theta}(\mathbf{x}_t^0 | \mathbf{h}_{t-1})$ corresponds to a regression problem for each time step!



Method	Exchange	Solar	Electricity	Traffic	Taxi	Wikipedia
VES	0.005 ± 0.000	0.9 ± 0.003	0.88 ± 0.0035	0.35 ± 0.0023	-	-
VAR	0.005 ± 0.000	0.83 ± 0.006	0.039 ± 0.0005	0.29 ± 0.005	0.292 ± 0.000	3.4 ± 0.003
VAR-Lasso	0.012 ± 0.0002	0.51 ± 0.006	0.025 ± 0.0002	0.15 ± 0.002	-	3.1 ± 0.004
GARCH	0.023 ± 0.000	0.88 ± 0.002	0.19 ± 0.001	0.37 ± 0.0016	-	-
KVAE	0.014 ± 0.002	0.34 ± 0.025	0.051 ± 0.019	0.1 ± 0.005	-	0.095 ± 0.012
Vec-LSTM ind-scaling	0.008 ± 0.001	0.391 ± 0.017	0.025 ± 0.001	0.087 ± 0.041	0.506 ± 0.005	0.133 ± 0.002
Vec-LSTM lowrank-Copula	0.007 ± 0.000	0.319 ± 0.011	0.064 ± 0.008	0.103 ± 0.006	0.326 ± 0.007	0.241 ± 0.033
GP scaling	0.009 ± 0.000	0.368 ± 0.012	0.022 ± 0.000	0.079 ± 0.000	0.183 ± 0.395	1.483 ± 1.034
GP Copula	0.007 ± 0.000	0.337 ± 0.024	0.0245 ± 0.002	0.078 ± 0.002	0.208 ± 0.183	0.086 ± 0.004
Transformer MAF	0.005 ± 0.003	0.301 ± 0.014	0.0207 ± 0.000	0.056 ± 0.001	0.179 ± 0.002	0.063 ± 0.003
TimeGrad	0.006 ± 0.001	0.287 ± 0.02	0.0206 ± 0.001	0.044 ± 0.006	0.114 ± 0.02	0.0485 ± 0.002

**Thank you
&**

See you at the poster!

Github: [zalando-research/pytorch-ts](https://github.com/zalando-research/pytorch-ts)