

# Think Global and Act Local: Bayesian Optimisation over High-dimensional Categorical and Mixed Search Spaces

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  - Useful for applications where evaluations are difficult, e.g., AutoML
- However, BO in **high dimensions** and heterogenous search spaces (i.e., some variables are not continuous) is still challenging
  - Search space grows exponentially with dimension, making GP surrogate difficult to cover
  - Categorical variables do not have natural ordering; one-hot transform makes problems even higher-dimensional
  - Some examples: combinatorial optimisation problems such as maximum satisfiability, Neural network tuning with both continuous (e.g., learning rate) and categorical (e.g., choice of optimiser) hyperparameters

# Contributions

- **Our method: CASMOPOLITAN**
  - Use *local trust regions* and *tailored kernels* to effectively handle high dimensions and categorical/mixed search spaces.
  - Derive guarantee under some assumptions that the method converges.
  - Empirically show that our method achieves better performance, better sample efficiency or both.
  - Code implementation is open-sourced.

# CASMOPOLITAN in Categorical Space

- Tailored kernel: GP with Exponentiated overlap kernel.

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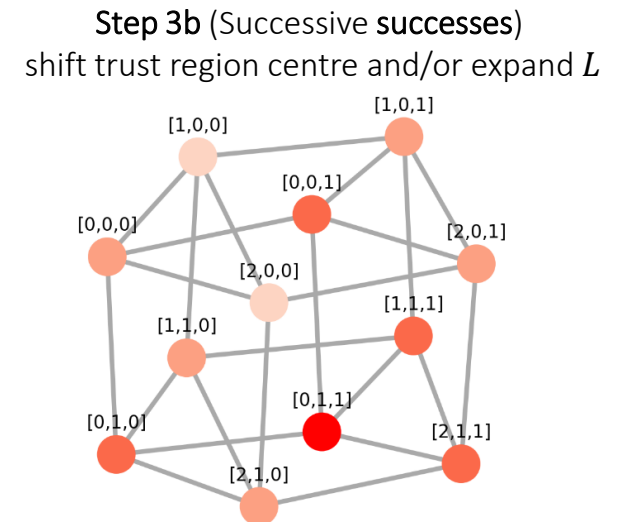
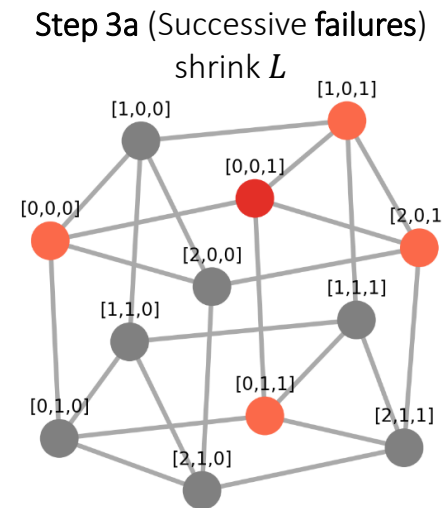
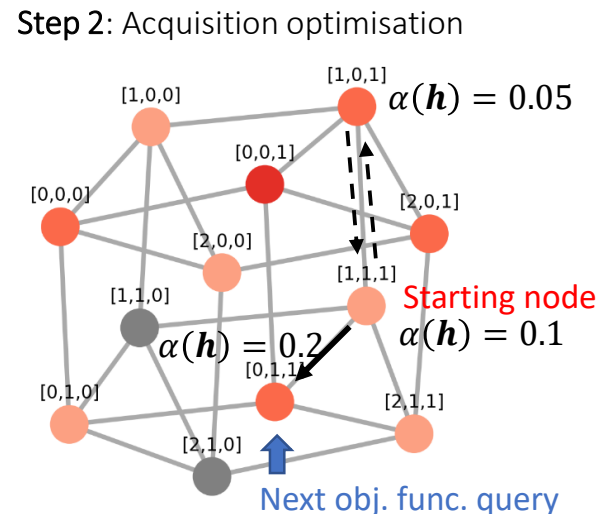
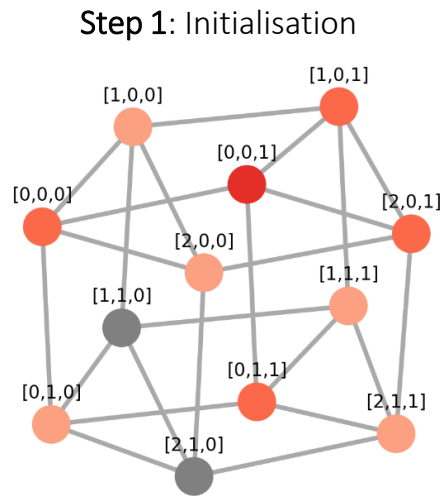
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- Tailored kernel: GP with Exponentiated overlap kernel.
- Use of **Trust Regions** defined in terms of Hamming distance from the best location seen so far:
- Trust regions are restarted using the UCB principle to ensure guarantee in terms of trust region restarts.

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# CASMOPOLITAN in Mixed Space

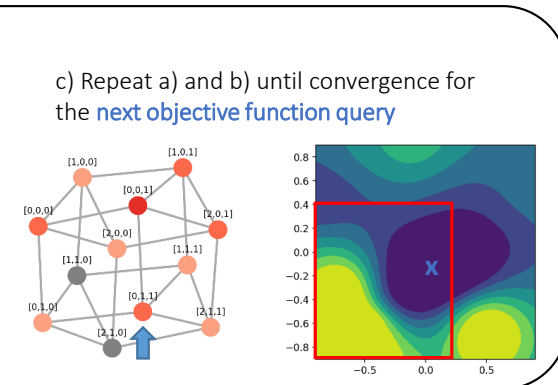
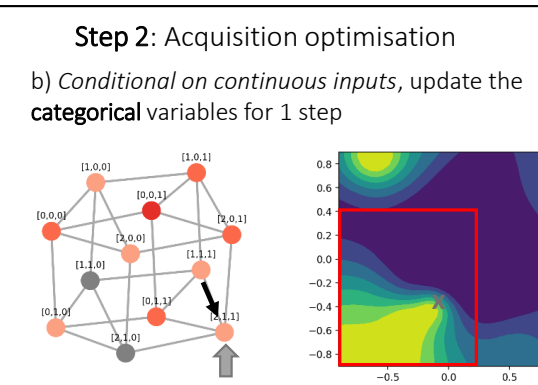
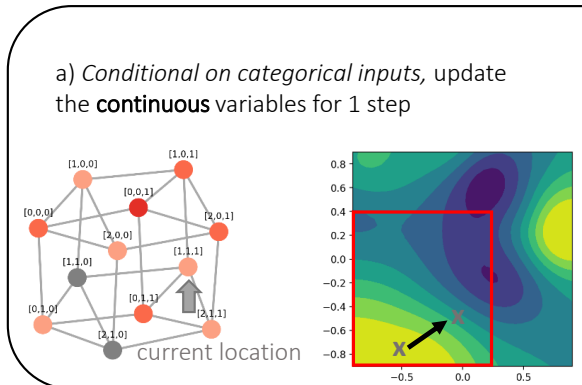
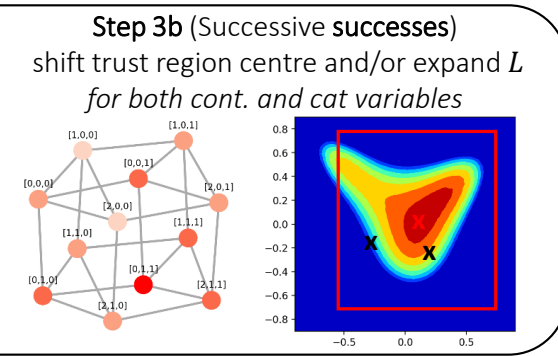
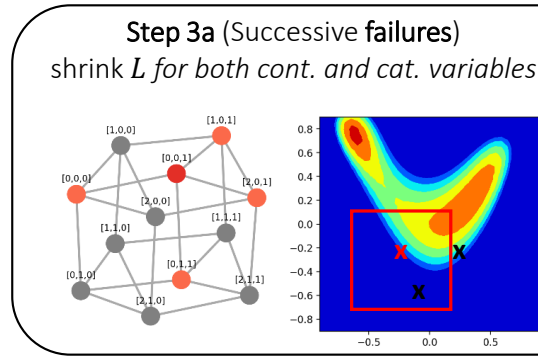
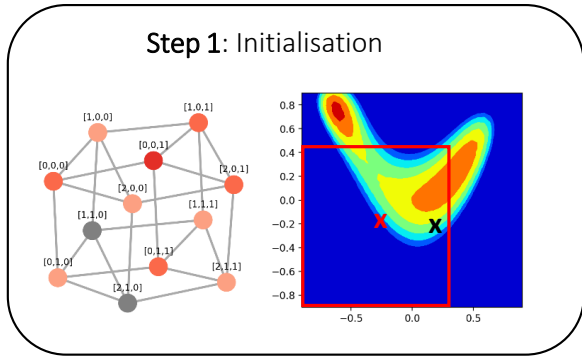
- Tailored kernel: GP now handles both categorical variables  $\mathbf{h}$  and continuous variables  $\mathbf{x}$ .

$$k(\mathbf{z}, \mathbf{z}') = \lambda \left( k_x(\mathbf{x}, \mathbf{x}') k_h(\mathbf{h}, \mathbf{h}') \right) + (1 - \lambda) \left( k_h(\mathbf{h}, \mathbf{h}') + k_x(\mathbf{x}, \mathbf{x}') \right),$$



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- Use of **separate trust regions** for both categorical and continuous variables



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- Use of **separate trust regions** for both categorical and continuous variables
- May be extended to handle other discrete inputs such as integer-valued and ordinal variables.

# Proof sketch of guarantee derivation

- We first prove that both kernels have bounded maximum information gain.
- We make assumptions on the properties of the trust region.
  - Objective function  $f$  is bounded
  - Given a small enough region, the surrogate model may approximate  $f$
- Using the UCB restarting of the trust region, we may derive sub-linear regret in terms of **number of restarts**.

# Experiments

- Categorical problems
  - Contamination control (Hu et al, 2010): 25 binary variables and  $>3.35 \times 10^7$  configurations
  - Pest control (Oh et al, 2019): 25 variables, 5 choices each and  $> 2.98 \times 10^{17}$  configurations
  - Weighted maximum satisfiability: 60 binary variables and  $> 1.15 \times 10^{18}$  configurations
- Mixed problems
  - Func2C (2 categorical and 2 continuous) and Func3C (3 categorical and 3 continuous) (Ru et al, 2020a)
  - Hyperparameter tuning of the XGBoost model
  - 53-dimensional Ackley with 50 binary and 3 continuous dimensions
  - 200-dimensional Rosenbrock with 100 binary and 100 continuous dimensions
  - Black-box adversarial attack on CIFAR-10 on a sparse attack setup:
    - Need to choose the pixel location (categorical dimension) and the amount of noise to inject (continuous dimension)
    - 43 categorical dimension with 15 choices each, and 43 continuous dimensions.

# Results

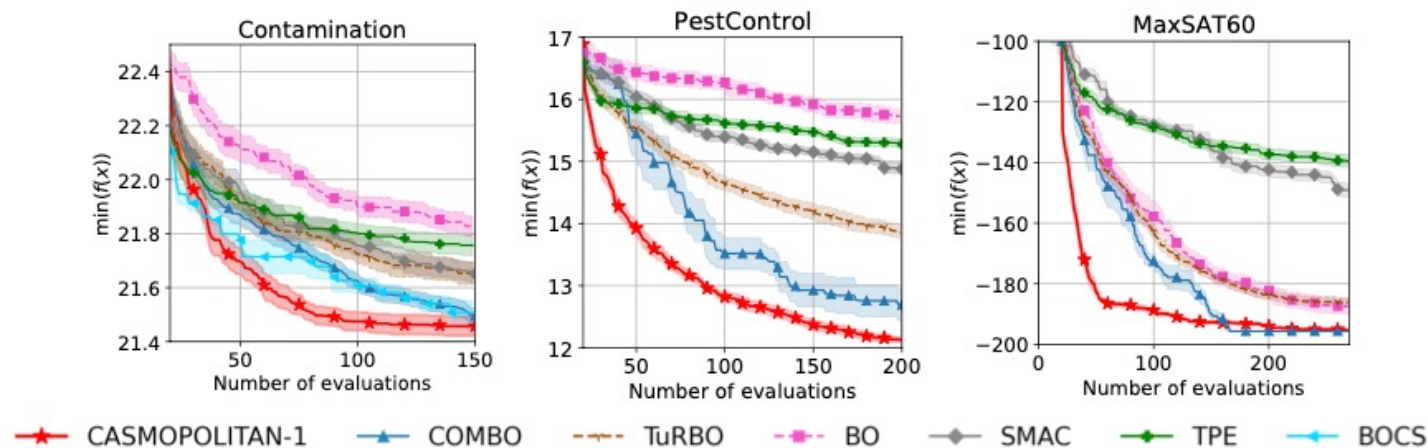


Figure 3. Results on various categorical optimisation problems. Lines and shaded area denote mean  $\pm 1$  standard error.

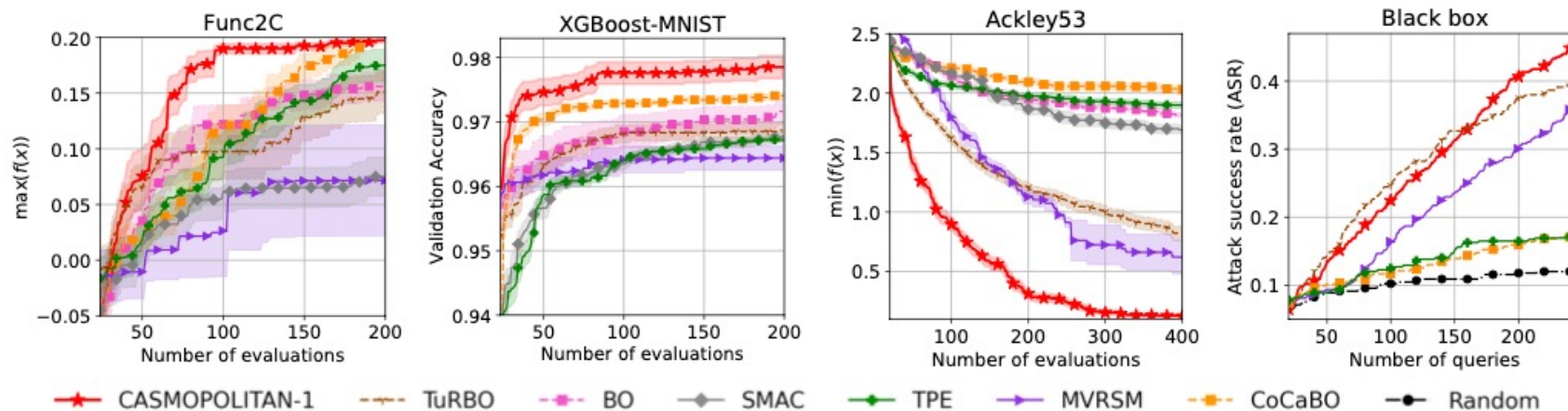


Figure 4. Results on various mixed optimisation problems. Lines and shaded area denote mean  $\pm 1$  standard error (except for Black-box where we show the ASR against number of queries). Additional experiment results in App. B.

# Summary

- **CASMOPOLITAN**

- Effective BO method applicable for high-dimensional problems that are categorical or mixed in nature
- Use a combination of trust-region-based local optimization and tailored kernel to adapt to the setup
- Features theoretical guarantee and state-of-the-art empirical performance

- **Future Directions**

- Other types of structured search space: e.g., graphs, trees, conditional search spaces
- Improvements on theories, e.g., simplifying assumptions in the certain combinatorial problems leading to better bounds

- **Paper Link:** <https://arxiv.org/pdf/2102.07188.pdf>
- **Code:** <https://github.com/xingchenwan/Casmopolitan>.
- **Email:** [xwan@robots.ox.ac.uk](mailto:xwan@robots.ox.ac.uk)