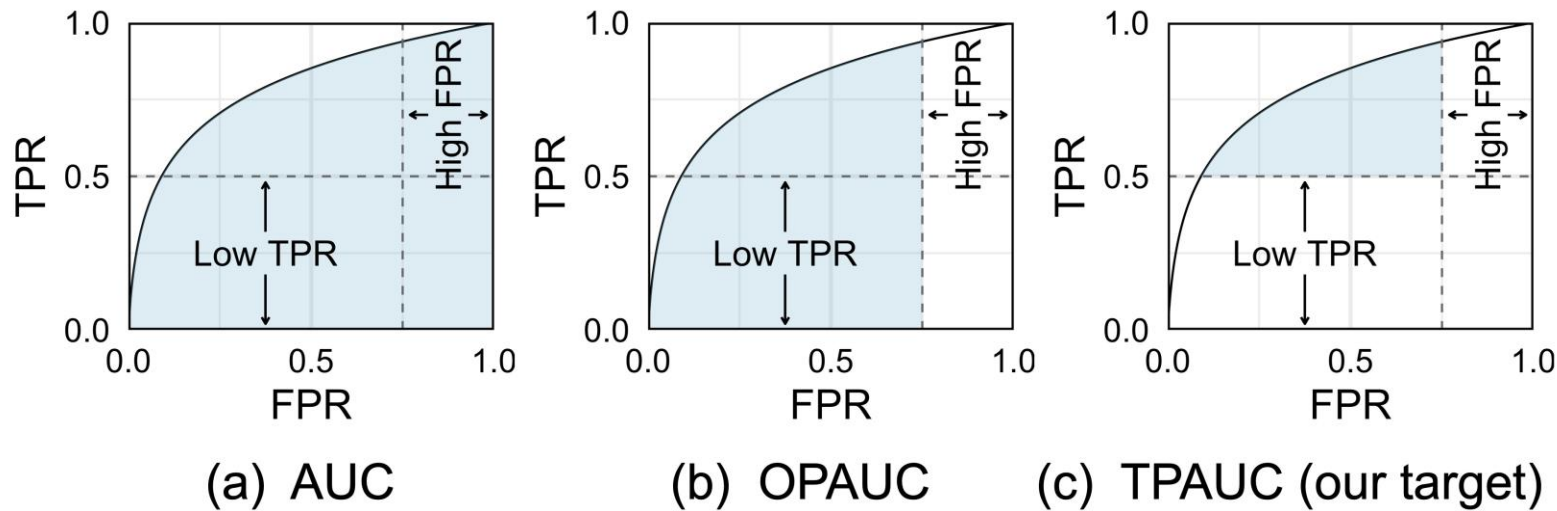
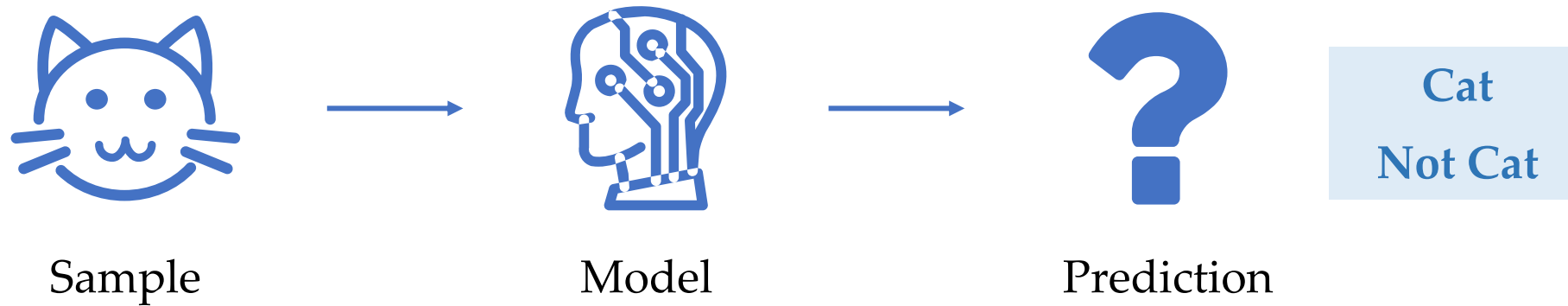


# When All We Need is a Piece of the Pie: A Generic Framework for Optimizing Two-way Partial AUC



Zhiyong Yang, Qianqian Xu, Shilong Bao, Yuan He,  
Xiaochun Cao, Qingming Huang

# Background



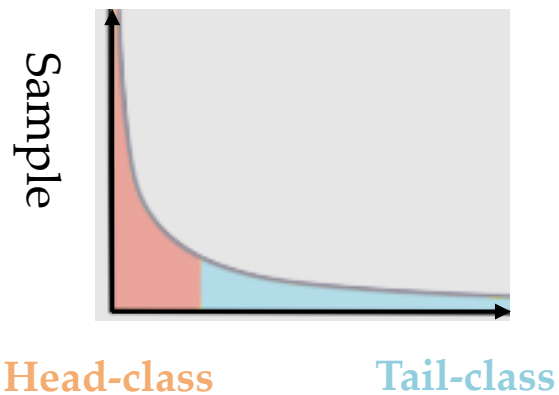
- Traditional classification methods adopt **error-rate-guided ERM**.

$$\min_{\theta} \frac{1}{n} \sum_{i=1}^n \mathbf{1} [f(\mathbf{x}_i) \neq y_i] \xrightarrow[\ell]{\text{sensitive to class distribution surrogate}} \min_{\theta} \frac{1}{n} \sum_{i=1}^n \ell (f(\mathbf{x}_i), y_i)$$

# Background

- Such ERM paradigm is problematic for imbalanced/long-tailed datasets

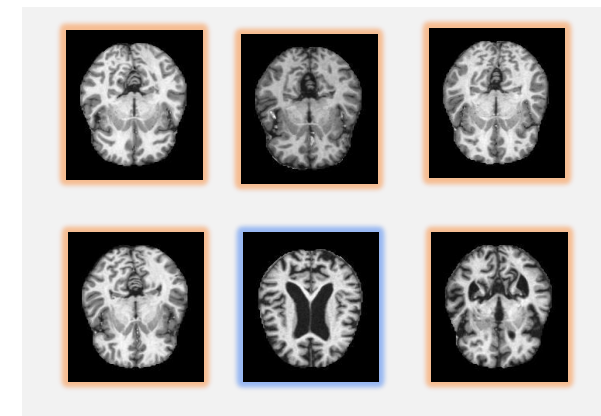
Long-tailed data



Spam Detection

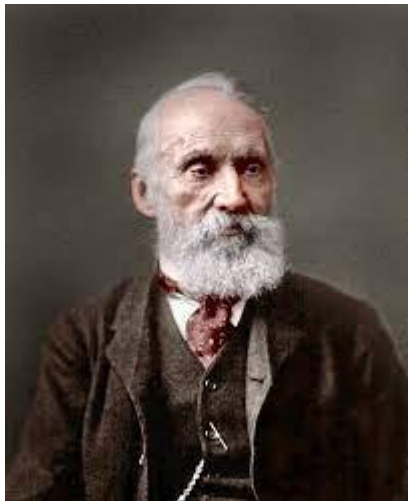


Disease Diagnosis



- It is easy to get a high accuracy score by simply predicting all the samples as the majority class!

# Background



If you can not **measure** it,  
you can not improve it

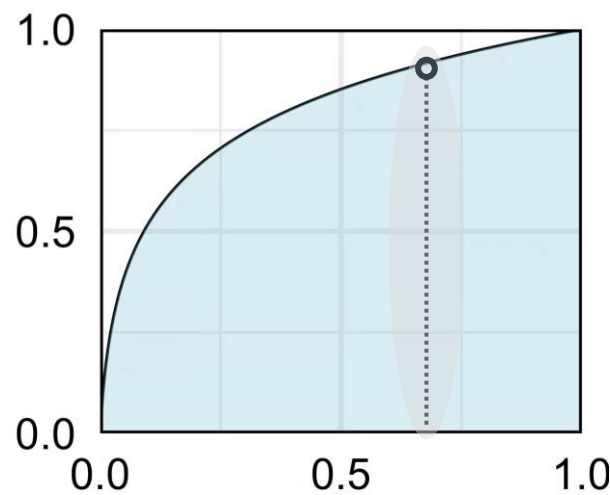
~Lord Kelvin

Seek out a suitable metric for imbalanced datasets

# Receiver Operating Characteristic Curve (ROC)

- **ROC curve:** True Positive Rate (**TPR**) vs. False Positive Rate (**FPR**).

Decision with a fixed threshold  
 label:  $y \in \{0, 1\}$   
 classifier:  $f(\mathbf{x})$ , threshold:  $t$   
 prediction:  $\hat{y} = \mathbb{1}[f(\mathbf{x}) > t]$



FPR

TPR

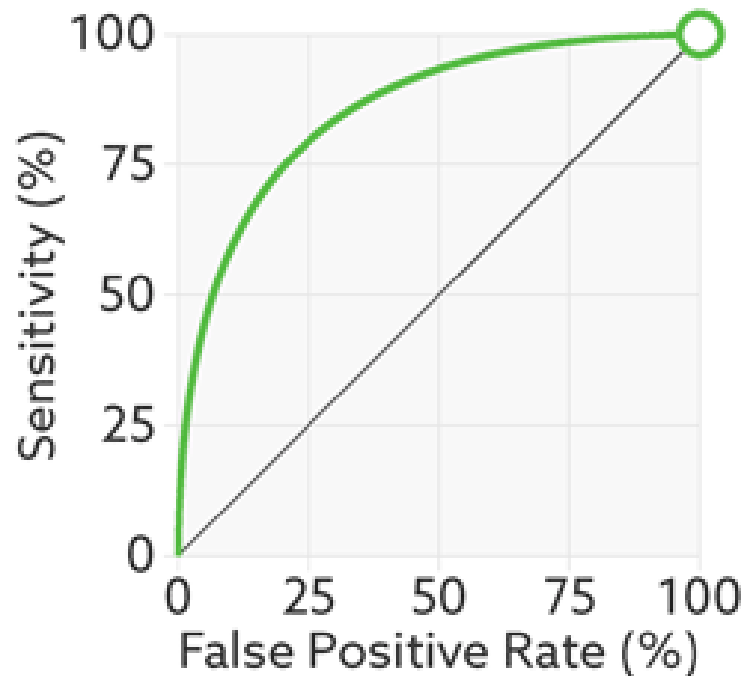


$$TPR = \mathbb{P}[f(\mathbf{x}) > t | y = 1]$$

$$FPR = \mathbb{P}[f(\mathbf{x}) > t | y = 0]$$

# Area Under the ROC Curve (AUC)

- AUC is the area under the ROC curve (over all possible thresholds)



$$\text{AUC} = \int_0^1 \text{TPR}(\text{FPR}^{-1}(\theta)) d\theta$$

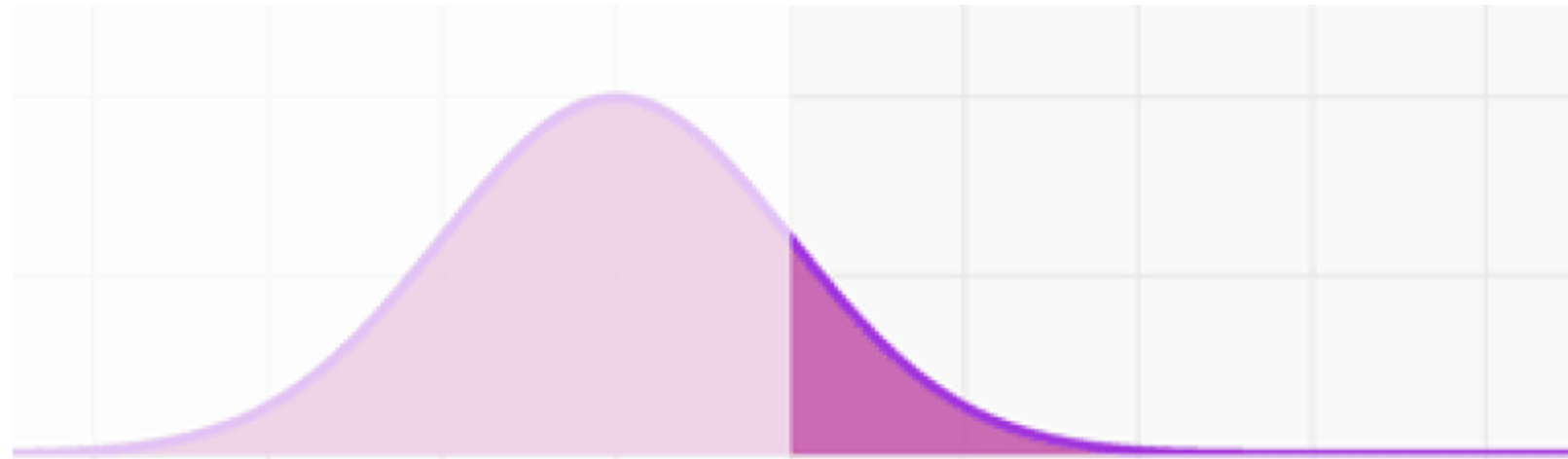
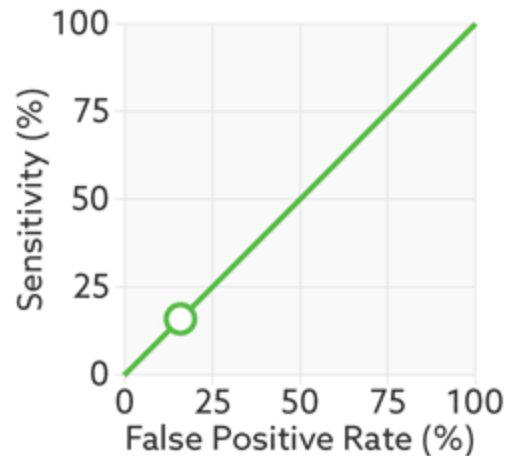
Involves a non-trivial integral

# Area Under the ROC Curve (AUC)

- A much simpler reformulation:

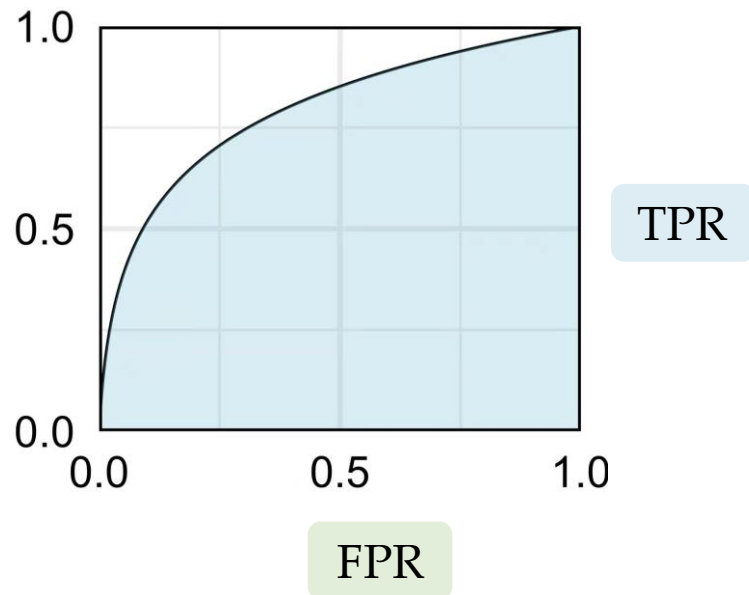
$$\text{AUC} = \mathbb{P} [f(\mathbf{x}) > f(\mathbf{x}') | y = 1, y' = -1]$$

- A measure of how well the two class conditional p.d.fs are separated



J. A. Hanley and B. J. McNeil. The meaning and use of the area under a receiver operating characteristic (roc) curve. *Radiology*, 143(1):29–36, 1982.

# AUC is too informative



Global integration

$$\text{AUC} = \int_0^1 \text{TPR}(\text{FPR}^{-1}(\theta)) d\theta$$

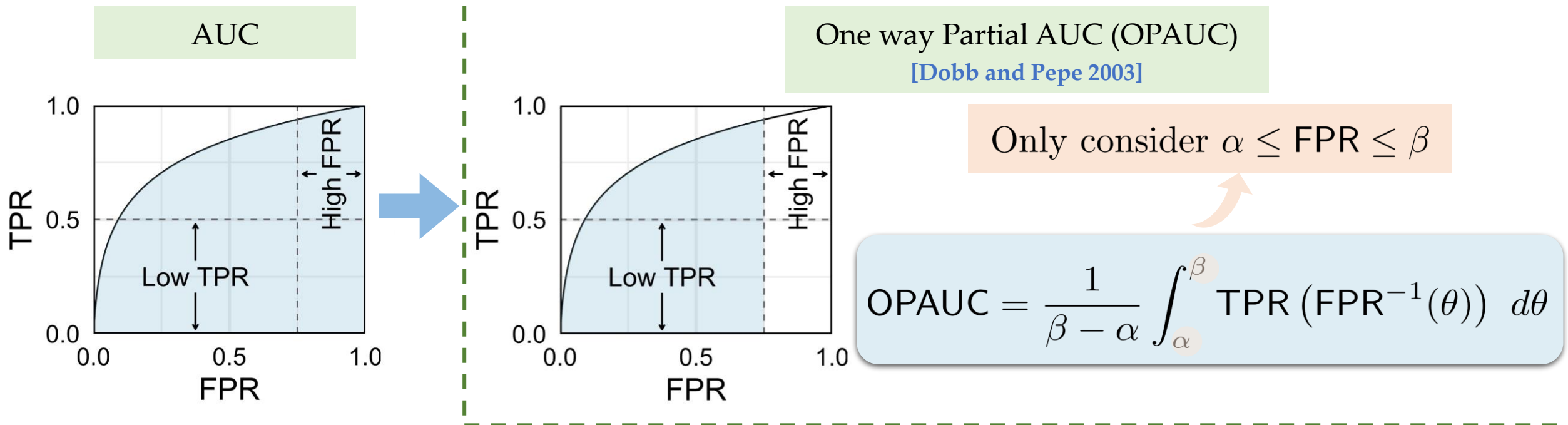
- Considers **all possible** TPR and FPR
- Real-world problems have performance **constraints** (e.g.,  $\text{TPR} > 0.5$ ,  $\text{FPR} < 0.1$ )

**Consider Local analog of AUC**



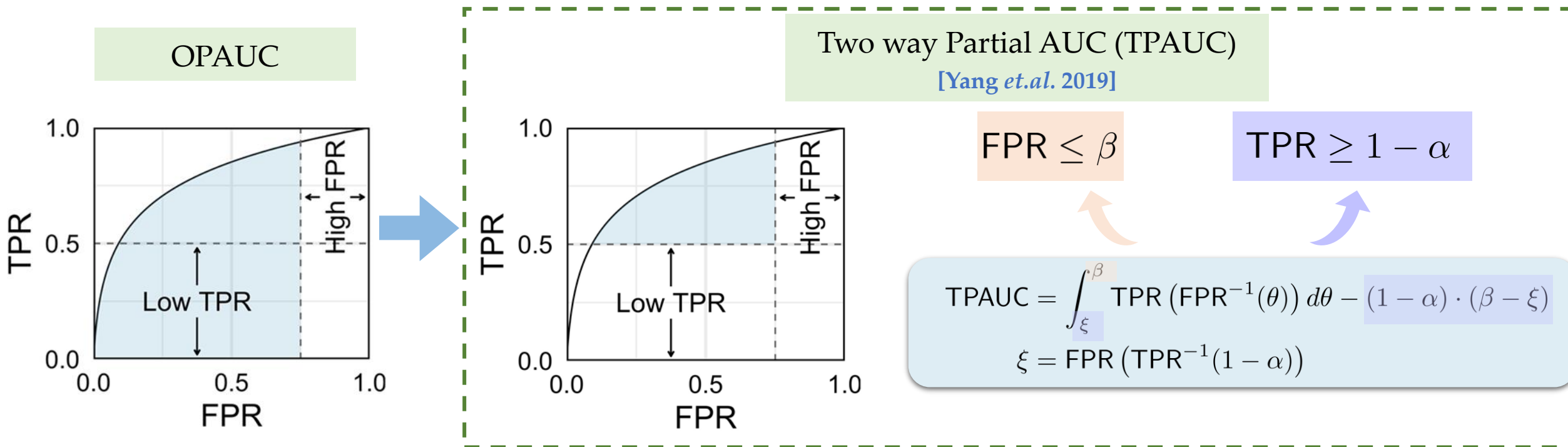
# One Way Partial AUC (OPAUC)

- AUC involves **all possible** TPRs and FPRs
- Many real-world applications have specific requirement on **FPR**
- Solution: Measure the partial area of ROC



# Two Way Partial AUC (TPAUC)

- A reasonable case should simultaneously enjoy a **low FPR** and a **high TPR**
- TPAUC measures the AUC within such a local area



# How to optimize local AUCs

- OPAUC

- Cutting Plane Solvers [Narasimhan *et.al.* 2013; Narasimhan *et.al.* 2017; Tomoharu *et.al.* 2020]
- Projected Sub-gradient Descent [Narasimhan *et.al.* 2013; Narasimhan *et.al.* 2017; Yamaguchi *et.al.* 2020]
- Evolutionary Algorithms [Fan *et.al.* 2019]
- Sampling Algorithms [Bai *et.al.* 2020a, b]

Not support the **end-to-end** training!

- TPAUC

- ?

- Requires a **sampling** process
- Do not have **theoretical guarantee**

Optimize TPAUC  
in an end-to-end fashion

# Can We estimate TPAUC from OPAUC ?

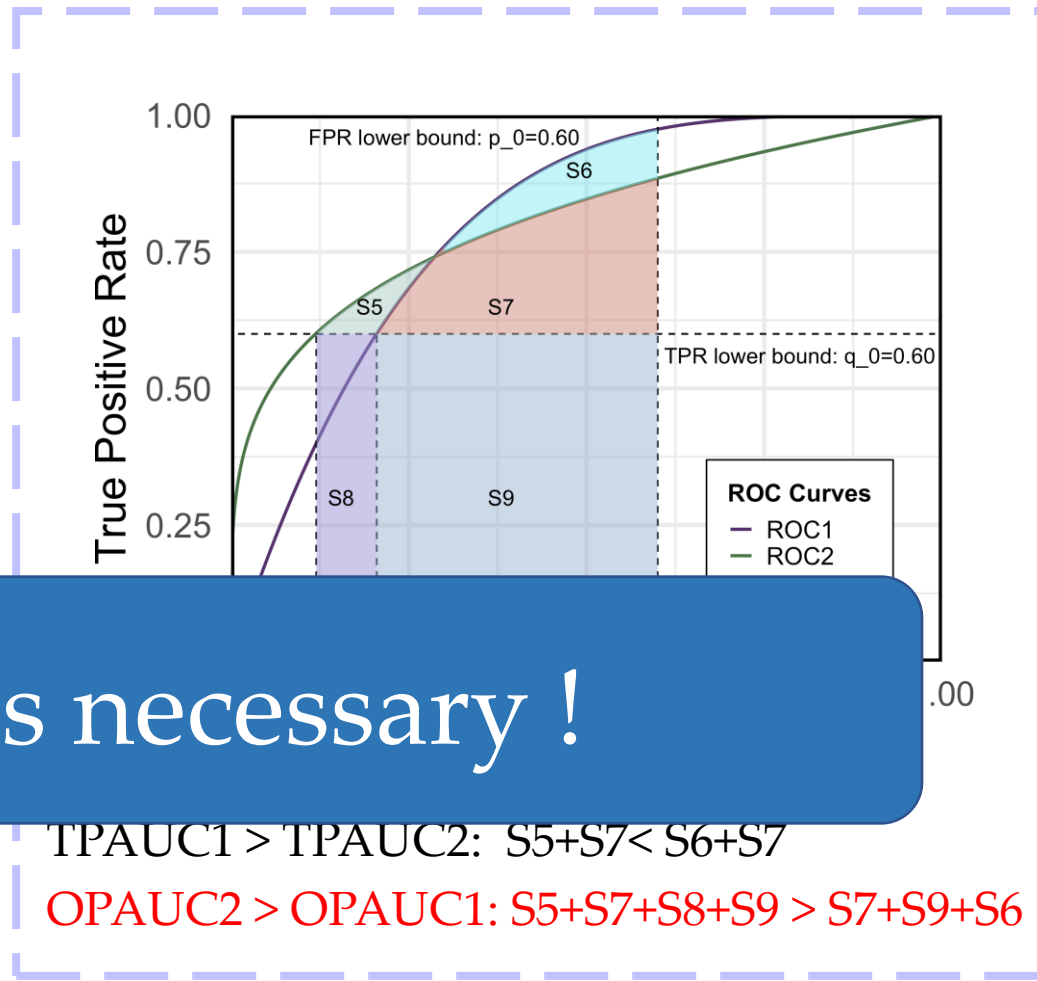
$$\text{OPAUC} = \frac{1}{\beta - \alpha} \int_{\alpha}^{\beta} \text{TPR}(\text{FPR}^{-1}(\theta)) d\theta$$

↓ approximate  $\xi$  with a fixed  $\alpha$  ?

TPAUC  $c\beta$

**Direct optimization is necessary !**

⊗  $\xi$  is a function of the scoring function  $f$



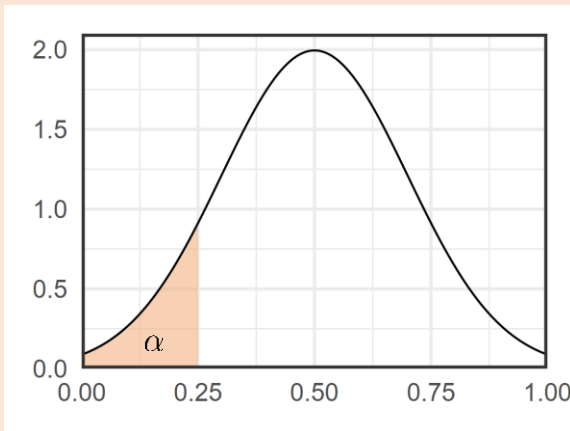
TPAUC1 > TPAUC2: S5+S7 < S6+S7

OPAUC2 > OPAUC1: S5+S7+S8+S9 > S7+S9+S6

# Reformulation of TPAUC

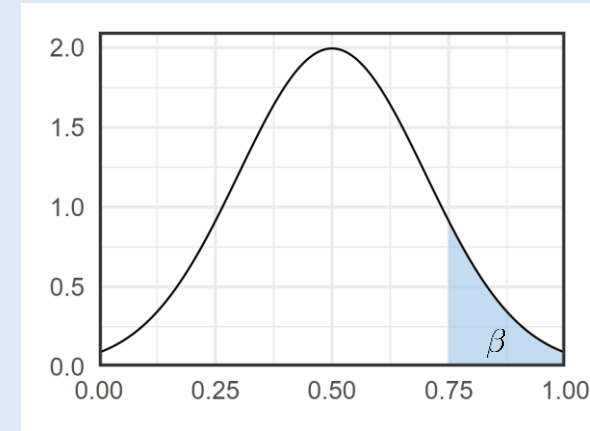
$$\text{AUC}_{\beta}^{\alpha}(f_{\theta}, \mathcal{S}) = \mathbb{E} [\mathbf{1} [f(\mathbf{x}) > f(\mathbf{x}'), f(\mathbf{x}) \leq t_{1-\alpha}, f(\mathbf{x}') \geq t_{\beta} | y = 1, y' = -1]]$$

score quantile of the positive class



$$t_{1-\alpha} = \operatorname{argmin}_{\delta \in \mathbb{R}} \left[ \delta \in \mathbb{R} : \mathbb{E} [\mathbf{1} [f(\mathbf{x}^+) \leq \delta]] = \alpha \right]$$

score quantile of the negative class



$$t_{\beta} = \operatorname{argmin}_{\delta \in \mathbb{R}} \left[ \delta \in \mathbb{R} : \mathbb{E} [\mathbf{1} [f(\mathbf{x}^-) \geq \delta]] = \beta \right]$$

- Requires empirical estimation of the **expectation**
- Requires empirical estimation of the **quantiles**

# Empirical Estimation of TPAUC

$$\hat{\text{AUC}}_{\beta}^{\alpha}(f_{\theta}, \mathcal{S}) = \frac{1}{n_{+}^{\alpha} n_{-}^{\beta}} \sum_{i=1}^{n_{+}^{\alpha}} \sum_{j=1}^{n_{-}^{\beta}} \mathbf{1}[f(\mathbf{x}) > f(\mathbf{x}')] \cdot \mathbf{1}[f(\mathbf{x}) \leq \hat{t}_{\alpha}, f(\mathbf{x}') \geq \hat{t}_{\beta} | y = 1, y' = -1]$$

empirical  
expectation

empirical  
quantile

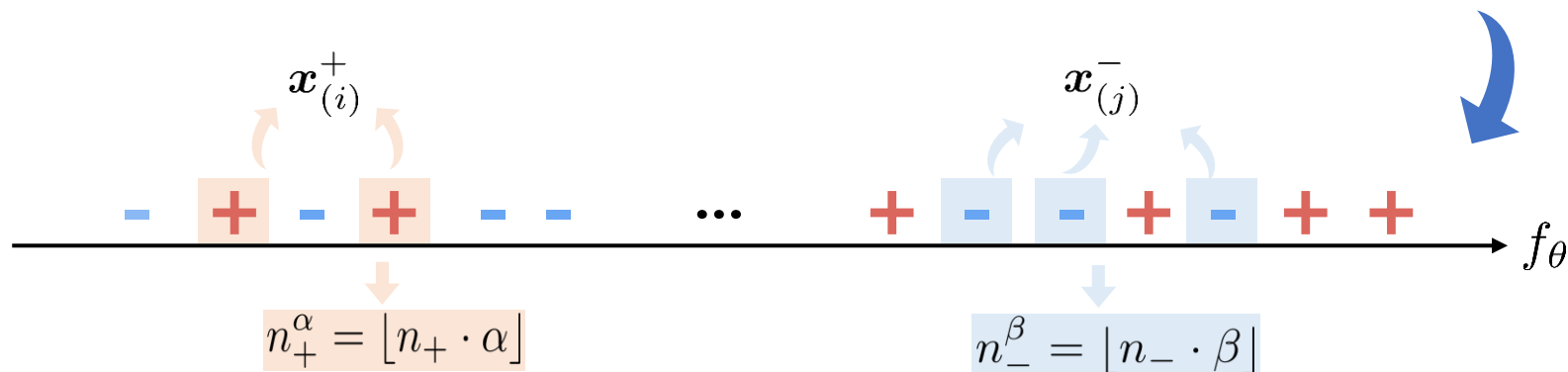
*Theorem 1 Asymptotic Normality of the Bias (Informal)* [Yang-Lu-Lyu-Hu 2019]

$$\hat{\text{AUC}}_{\alpha}^{\beta} - \text{AUC}_{\alpha}^{\beta} \xrightarrow{d} \mathcal{N}(0, \sigma^2), \quad n_{+}, n_{-} \rightarrow \infty$$

$$\sigma = \mathcal{O} \left( \sqrt{\frac{1}{n_{+}} + \frac{1}{n_{-}}} \right)$$

# Empirical Estimation of TPAUC

$$\text{AUC}_\alpha^\beta(f_\theta, \mathcal{S}) = 1 - \sum_{i=1}^{n_+^\alpha} \sum_{j=1}^{n_-^\beta} \frac{\ell_{0,1}(f_\theta(\mathbf{x}_{(i)}^+) - f_\theta(\mathbf{x}_{(j)}^-))}{n_+^\alpha n_-^\beta}$$



Optimize Empirical TPAUC approximately

all negative instances.

# Step1 Surrogate Loss Minimization

- Replace  $\ell_{0,1}$  with a continuous surrogate  $\ell$

$$(OP_0) \min_{\theta} \hat{\mathcal{R}}_{\alpha,\beta}^{\ell}(S, f_{\theta}) = \sum_{i=1}^{n_+^{\alpha}} \sum_{j=1}^{n_-^{\beta}} \frac{\ell\left(f_{\theta}\left(\mathbf{x}_{(i)}^+\right) - f\left(\mathbf{x}_{(j)}^-\right)\right)}{n_+^{\alpha} n_-^{\beta}}$$

$$\ell_{\text{exp}}(t) = \exp(-t), \ell_{\text{sq}}(t) = (1 - t)^2$$



- $\hat{\mathcal{R}}_{\alpha,\beta}^{\ell}(S, f_{\theta})$  is still not differentiable!
- Calculating  $\mathbf{x}_{(i)}^+, \mathbf{x}_{(j)}^-$  requires sorting the scores of positive and negative instances.



# Step2 Bi-level optimization

The original optimization problem is equivalent to the following problem:

$$\begin{aligned}
 & \min_{\theta} \frac{1}{n_+ n_-} \sum_{i=1}^{n_+} \sum_{j=1}^{n_-} v_i^+ \cdot v_j^- \cdot \ell(f_{\theta}, \mathbf{x}_i^+, \mathbf{x}_j^-) \\
 \text{s.t. } & v_+ = \underset{v_i^+ \in [0,1], \sum_{i=1}^{n_+} v_i^+ \leq n_+^{\alpha}}{\operatorname{argmax}} \sum_{i=1}^{n_+} (v_i^+ \cdot (1 - f_{\theta}(\mathbf{x}_i^+))) \\
 & v_- = \underset{v_j^- \in [0,1], \sum_{j=1}^{n_-} v_j^- \leq n_-^{\beta}}{\operatorname{argmax}} \sum_{j=1}^{n_-} (v_j^- \cdot f_{\theta}(\mathbf{x}_j^-))
 \end{aligned}$$

where

$$\ell(f_{\theta}, \mathbf{x}_i^+, \mathbf{x}_j^-) = \ell(f_{\theta}(\mathbf{x}_i^+) - f_{\theta}(\mathbf{x}_j^-))$$

**Outer-level problem**  
 optimization based on  
 the chosen instances

The ball constraints  
 makes the optimization  
 intractable

**Inner-level problem**  
 a sparse sample selection  
 process

# Step2 Bi-level optimization

- Transform the  $\ell_1$  ball constraints to  $\ell_1$  penalty terms (note that  $v_+$ ,  $v_-$  are non-negative):

$$v_+ = \operatorname{argmax}_{v_i^+ \in [0,1], \sum_{i=1}^{n_+} v_i^+ \leq n_+^\alpha} \sum_{i=1}^{n_+} (v_i^+ \cdot (1 - f_{\theta}(\mathbf{x}_i^+)))$$

$$v_- = \operatorname{argmax}_{v_j^- \in [0,1], \sum_{j=1}^{n_-} v_j^- \leq n_-^\beta} \sum_{j=1}^{n_-} (v_j^- \cdot f_{\theta}(\mathbf{x}_j^-))$$



$$v_+ = \operatorname{argmax}_{v_i^+ \in [0,1]} \sum_{i=1}^{n_+} (v_i^+ \cdot (1 - f_{\theta}(\mathbf{x}_i^+)) - \lambda^+ \cdot v_i^+)$$

$$v_- = \operatorname{argmax}_{v_j^- \in [0,1]} \sum_{j=1}^{n_-} (v_j^- \cdot f_{\theta}(\mathbf{x}_j^-) - \lambda^- \cdot v_j^-)$$

# Step2 Bi-level optimization

- Replace the sparsity-inducing  $\ell_1$  penalty with a smooth surrogate  $\varphi_\gamma$

$$(OP_1) \min_{\theta} \frac{1}{n_+^\alpha n_-^\beta} \sum_{i=1}^{n_+} \sum_{j=1}^{n_-} v_i^+ \cdot v_j^- \cdot \ell(f_\theta, \mathbf{x}_i^+, \mathbf{x}_j^-)$$

$$\text{s.t } v_+ = \operatorname{argmax}_{v_i^+ \in [0,1]} \sum_{i=1}^{n_+} (v_i^+ \cdot (1 - f_\theta(\mathbf{x}_i^+)) - \varphi_\gamma(v_i^+))$$

$$v_- = \operatorname{argmax}_{v_j^- \in [0,1]} \sum_{j=1}^{n_-} (v_j^- \cdot f_\theta(\mathbf{x}_j^-) - \varphi_\gamma(v_j^-))$$

## Sample Weights

Choose what to learn in the outer level problem

## Penalty Function

Choose the weighting strategy



The connection between weight and the penalty is the key

# Step3 Dual Correspondence

$$v_+ = \operatorname{argmax}_{v_i^+ \in [0,1]} \sum_{i=1}^{n^+} (v_i^+ \cdot (1 - f_{\theta}(\mathbf{x}_i^+)) - \varphi_{\gamma}(v_i^+))$$

$$v_- = \operatorname{argmax}_{v_j^- \in [0,1]} \sum_{j=1}^{n_-} (v_j^- \cdot f_{\theta}(\mathbf{x}_j^-) - \varphi_{\gamma}(v_j^-))$$

**With a Closed-form Solution**

$$v_i^+ = \psi_{\gamma}(1 - f_{\theta}(\mathbf{x}_i^+)) \quad v_j^- = \psi_{\gamma}(f_{\theta}(\mathbf{x}_j^-))$$

**weighting function**

Under what condition can we realize such a simplification ?

# Step 3 Dual Correspondence

## Definition 1 Calibrated Smooth Penalty Function

A penalty function  $\varphi_\gamma(x) : \mathbb{R}_+ \rightarrow \mathbb{R}$  satisfies the following regularities:

- (A)  $\varphi_\gamma$  has continuous third-order derivatives.
- (B)  $\varphi_\gamma$  is strictly increasing in the sense that  $\varphi'_\gamma(x) > 0$ .
- (C)  $\varphi_\gamma$  is strictly convex in the sense that  $\varphi''_\gamma(x) > 0$ .
- (D)  $\varphi_\gamma$  has positive third-order derivatives in the sense that  $\varphi'''_\gamma(x) > 0$ .

## Definition 2 Calibrated Weighting Function

A weighting function  $\psi_\gamma(x) : [0, 1] \rightarrow \text{Rng}$ , where  $\text{Rng} \subseteq [0, 1]$ , satisfies the following regularities:

- (A)  $\psi_\gamma$  has continuous second-order derivatives.
- (B)  $\psi_\gamma$  is strictly increasing in the sense that  $\psi'_\gamma(x) > 0$ .
- (C)  $\psi_\gamma$  is strictly concave in the sense that  $\psi''_\gamma(x) < 0$ .

# Step 3 Dual Correspondence

## Proposition 1

Given a strictly convex function  $\varphi_\gamma$ , and define  $\psi_\gamma(t)$  as

$$\psi_\gamma(t) = \operatorname{argmax}_{v \in [0,1]} v \cdot t - \varphi_\gamma(v)$$

Then we can draw the following conclusions:

- (a) If  $\varphi_\gamma$  is a calibrated smooth penalty function, we have  $\psi_\gamma(t) = \varphi_\gamma'^{-1}(t)$ .
- (b) If  $\psi_\gamma$  is a calibrated weighting function such that  $v = \psi_\gamma(t)$ , we have

$$\varphi_\gamma(v) = \int \psi_\gamma^{-1}(v) dv + \text{const.}$$

penalty to weight

weight to penalty



This provides a simple way to establish a surrogate optimization problem of TPAUC

# Step 3 Dual Correspondence

- Given the penalty functions  $\varphi_\gamma$ ,

$$v_i^+ = \psi_\gamma(1 - f_\theta(\mathbf{x}_i^+)), v_j^- = \psi_\gamma(f_\theta(\mathbf{x}_j^-)), v_i^+, v_j^- \in [0, 1]$$

If  $\psi_\gamma$  has a closed-form expression

Cancel the inner optimization problem

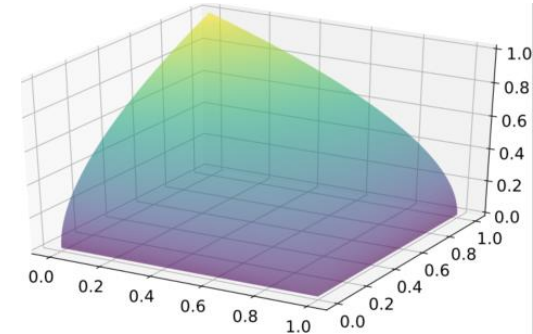
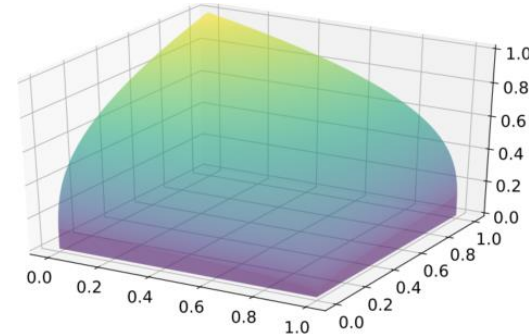
- Weighted empirical risk:

$$\hat{\mathcal{R}}_\psi^\ell(\mathcal{S}, f_\theta) = \frac{1}{n_+ n_-} \sum_{i=1}^{n_+} \sum_{j=1}^{n_-} \psi_\gamma(1 - f_\theta(\mathbf{x}_i^+)) \psi_\gamma(f_\theta(\mathbf{x}_j^-)) \cdot \ell(f_\theta, \mathbf{x}_i^+, \mathbf{x}_j^-)$$

# Instantiations of the Generic Framework

## Example 1 (Polynomial Surrogate Model).

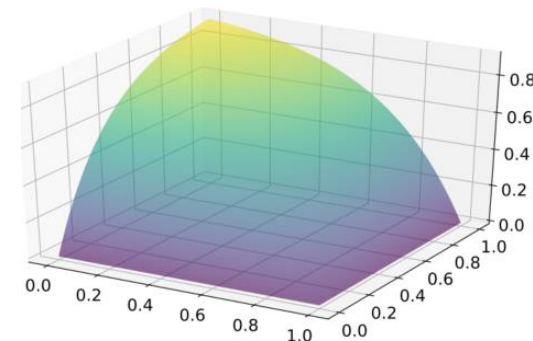
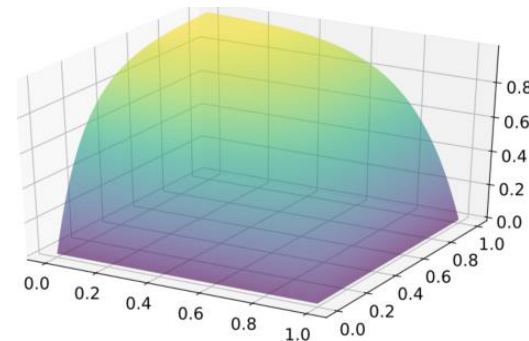
$$\varphi_{\gamma}^{\text{poly}}(t) = \frac{1}{\gamma} \cdot t^{\gamma}, \psi_{\gamma}^{\text{poly}}(t) = t^{\frac{1}{\gamma-1}}, \gamma > 2$$



## Example 2 (Exponential Surrogate Model).

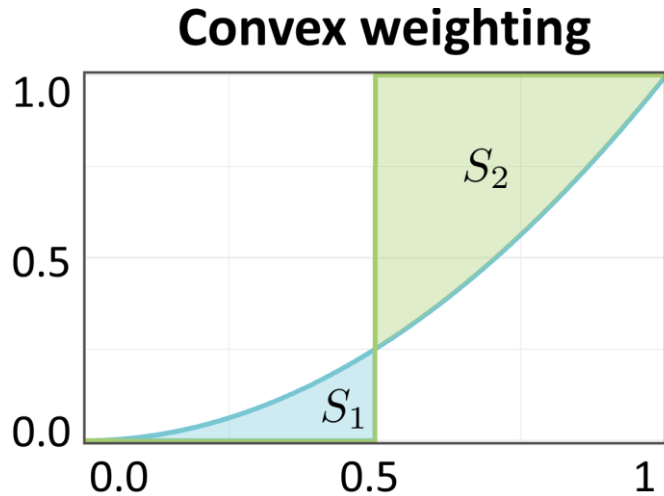
$$\varphi_{\gamma}^{\text{exp}}(t) = \frac{(1-t)(\log(1-t) - 1) + 1}{\gamma}$$

$$\psi_{\gamma}^{\text{exp}}(t) = 1 - e^{-\gamma t}$$

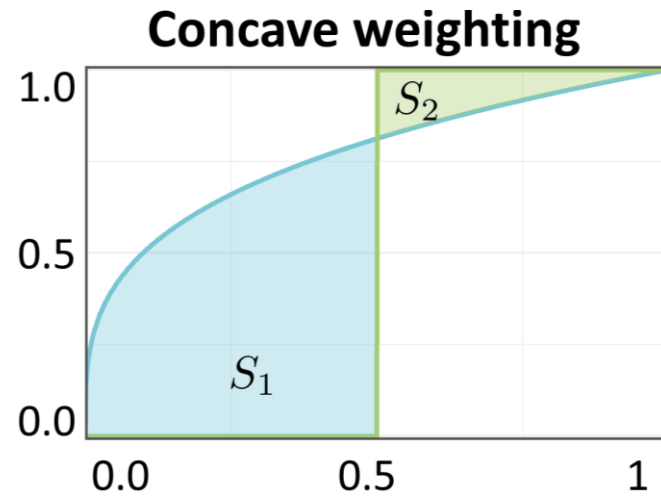




# Theoretical Analysis: concave vs. convex weighting function



$S_1/S_2$   
should  
be **large**



## Proposition 2 (Informal).

- **Concave** functions  $\psi$  are always **easier** to induces an upper bound of the original objective function

surrogate  
risk

$$\hat{\mathcal{R}}_{\psi}^{\ell}(S, f_{\theta}) > \hat{\mathcal{R}}_{\alpha, \beta}^{\ell}(S, f_{\theta})$$

true  
risk

- A **sufficient** condition for achieving the **upper** bound:

$$\sup_{p \in (0,1), q = -\frac{p}{1-p}} [\rho_p - \xi_q] \geq 0,$$

$$\rho_p = \frac{(\bar{\mathbb{E}}_{x^+, x^- \in \mathcal{I}_2} [v_+^p \cdot v_-^p])^{1/p}}{\left(\bar{\mathbb{E}}_{x^+ \in \mathcal{I}_1^+, x^- \in \mathcal{I}_1^-} [(1 - v_+ v_-)^2]\right)^{1/2}},$$

$$\xi_q = \frac{\alpha\beta}{1 - \alpha\beta} \cdot \frac{(\bar{\mathbb{E}}_{x^+, x^- \in \mathcal{I}_2} (\ell_{i,j}^2))^{1/2}}{\left(\bar{\mathbb{E}}_{x^+ \in \mathcal{I}_1^+, x^- \in \mathcal{I}_1^-} (\ell_{i,j}^q)\right)^{1/q}}.$$

The empirical  
distribution  
has **significant** mass  
over instances with  
**moderate difficulty**

# Theoretical Analysis: concave vs. convex weighting function

## Validation on simulated Dataset

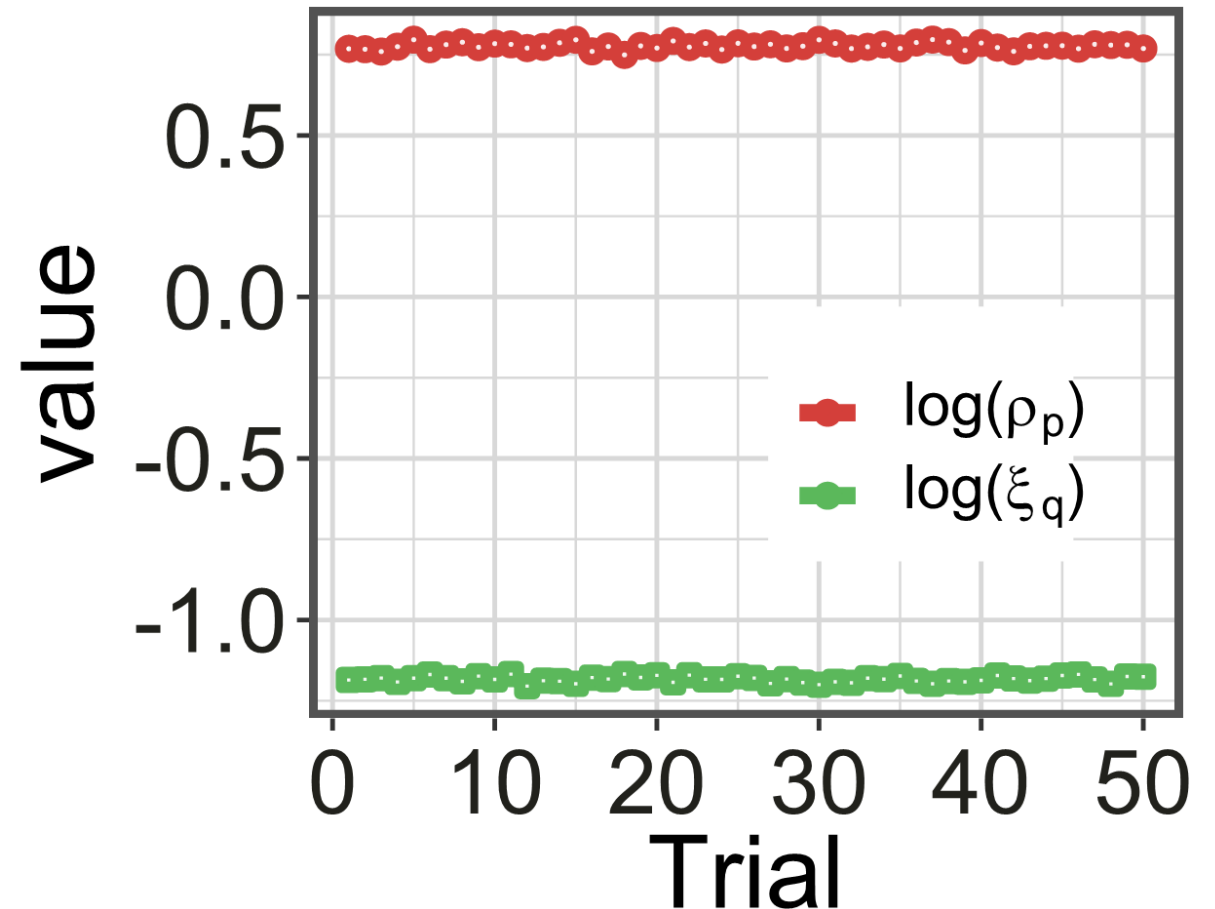
$$f(x^+) \sim \mathcal{N}(0.5, 0.08)$$

$$f(x^-) \sim \mathcal{N}(0.3, 0.08)$$

Generate 100 points for each class

plot for 50 such trails

$$\rho_p > \xi_q$$



# Theoretical Analysis: Excess risk bound

## *Theorem 2 (Informal).*

*The following inequality holds with high probability:*

$$\mathcal{R}_{AUC}^{\alpha, \beta}(f_{\theta}, \mathcal{S}) \leq \hat{\mathcal{R}}_{\psi}^{\ell}(f_{\theta}, \mathcal{S}) + \tilde{O} \left( \left( \frac{\text{VC}}{n_{+}} \right)^{1/2} + \left( \frac{\text{VC}}{n_{-}} \right)^{1/2} \right)$$

**The empirical risk  
is biased**

*where  $\tilde{O}$  is the big-O complexity notation hiding the logarithm factors,*

$$\mathcal{R}_{AUC}^{\alpha, \beta}(f_{\theta}, \mathcal{S}) = 1 - \text{AUC}_{\alpha}^{\beta}(f_{\theta}, \mathcal{S}),$$

*and VC is the VC dimension of the hypothesis class:*

$$\mathcal{T}(\mathcal{F}) \triangleq \{ \text{sign}(f_{\theta}(\cdot) - \delta) : f_{\theta} \in \mathcal{F}, \delta \in \mathbb{R} \}$$

# Empirical Results

Table 2. Details on the datasets.

Dataset	Pos. Class ID	Pos. Class Name	# Pos. Examples	# Neg. Examples
CIFAR-10-LT-1	2	birds	1,508	8,907
CIFAR-10-LT-2	1	automobiles	2,517	7,898
CIFAR-10-LT-3	3	cats	904	9,511
CIFAR-100-LT-1	6, 7, 14, 18, 24	insects	1,928	13,218
CIFAR-100-LT-2	0, 51, 53, 57, 83	fruits and vegetables	885	14,261
CIFAR-100-LT-3	15, 19, 21, 32, 38	large omnivores and herbivores	1,172	13,974
Tiny-ImageNet-200-LT-1	24, 25, 26, 27, 28, 29	dogs	2,100	67,900
Tiny-ImageNet-200-LT-2	11, 20, 21, 22	birds	1,400	68,600
Tiny-ImageNet-200-LT-3	70, 81, 94, 107, 111, 116, 121, 133, 145, 153, 164, 166	vehicles	4,200	65,800

- We construct long-tail binary datasets with different subsets:

- ✓ Binary CIFAR-10-LT Dataset
- ✓ Binary CIFAR-100-LT Dataset
- ✓ Binary Tiny-ImageNet-200-LT Dataset

- We adopt the following variant of the TPAUC metric:

$$\text{TPAUC}(\alpha, \beta) = 1 - \sum_{i=1}^{n_+^\alpha} \sum_{j=1}^{n_-^\beta} \frac{\ell_{0,1} \left( f_\theta \left( \mathbf{x}_{(i)}^+ \right) - f \left( \mathbf{x}_{(j)}^- \right) \right)}{n_+^\alpha n_-^\beta}$$

# Empirical Results

- We consider TPAUC with

$$\alpha = 0.3, \beta = 0.3$$

$$\alpha = 0.4, \beta = 0.4$$

$$\alpha = 0.5, \beta = 0.5$$

- Table 1 shows the performance comparison against other methods dealing with imbalanced data.

- The empirical results demonstrate the superiority of our proposed TPAUC algorithm.

Table 1. Performance Comparisons over different metrics and datasets, where  $(x, y)$  stands for TPAUC( $x, y$ ) in short.

dataset	type	methods	Subset1			Subset2			Subset3			
			(0.3,0.3)	(0.4,0.4)	(0.5,0.5)	(0.3,0.3)	(0.4,0.4)	(0.5,0.5)	(0.3,0.3)	(0.4,0.4)	(0.5,0.5)	
CIFAR-10-LT	Competitors	CE-RW	9.09	30.86	47.99	72.83	83.33	88.71	23.47	44.44	59.69	
		Focal	9.84	30.89	50.83	75.72	85.10	90.06	21.47	45.88	59.09	
		CBCE	3.29	27.30	43.95	69.48	80.80	86.87	12.94	34.06	51.09	
		CBFocal	9.04	31.73	48.13	77.99	86.75	91.13	21.32	43.03	59.11	
		SqAUC	18.05	40.74	57.94	80.09	87.78	91.87	31.52	50.00	64.42	
	Ours	Poly	<b>21.43</b>	<b>44.41</b>	<b>59.10</b>	80.66	<b>88.07</b>	<b>92.15</b>	<b>36.54</b>	<b>54.48</b>	<u>67.19</u>	
		Exp	<u>20.86</u>	<u>41.78</u>	<u>58.38</u>	<b>81.22</b>	<u>87.88</u>	<u>91.93</u>	<u>32.47</u>	<u>53.86</u>	<b>67.32</b>	
	CIFAR-100-LT	Competitors	CE-RW	31.43	52.60	66.21	79.70	88.06	92.64	3.09	21.32	40.75
			Focal	36.51	61.71	73.25	83.08	90.35	93.76	8.09	28.88	49.89
			CBCE	17.53	38.79	55.19	67.91	79.32	85.82	1.84	18.46	37.04
CBFocal			41.85	62.41	73.13	82.75	89.57	92.89	7.10	29.12	44.84	
SqAUC			<u>63.24</u>	76.62	84.68	<u>91.02</u>	93.69	94.73	41.60	60.36	70.86	
Ours-TPAUC		Poly	<b>68.02</b>	<b>79.11</b>	<b>85.17</b>	<b>91.13</b>	<b>93.78</b>	<b>95.69</b>	<b>47.07</b>	<b>65.89</b>	<b>75.08</b>	
		Exp	<u>63.24</u>	<u>77.94</u>	<u>84.62</u>	90.69	<u>93.74</u>	<u>95.41</u>	<u>44.54</u>	<u>64.58</u>	<u>73.02</u>	
Tiny-ImageNet-200-LT		Competitors	CE-RW	80.90	87.76	91.54	93.30	96.15	97.53	90.37	94.34	96.75
			Focal	<u>81.18</u>	88.06	91.72	93.23	96.08	97.59	91.35	94.87	96.63
			CBCE	80.64	87.58	91.17	<u>93.77</u>	<b>96.52</b>	<b>97.77</b>	91.66	95.19	96.79
	CBFocal		80.44	87.95	91.91	93.46	<u>96.43</u>	<u>97.64</u>	91.06	94.82	96.62	
	SqAUC		80.16	87.99	91.67	93.10	96.07	97.32	<b>92.15</b>	<u>95.16</u>	<u>96.75</u>	
	Ours-TPAUC	Poly	80.44	88.21	91.98	93.00	95.61	97.47	<u>92.02</u>	<b>95.25</b>	<b>96.84</b>	
		Exp	<b>82.61</b>	<b>89.13</b>	<b>92.62</b>	<b>93.82</b>	96.12	97.38	91.25	94.78	96.57	

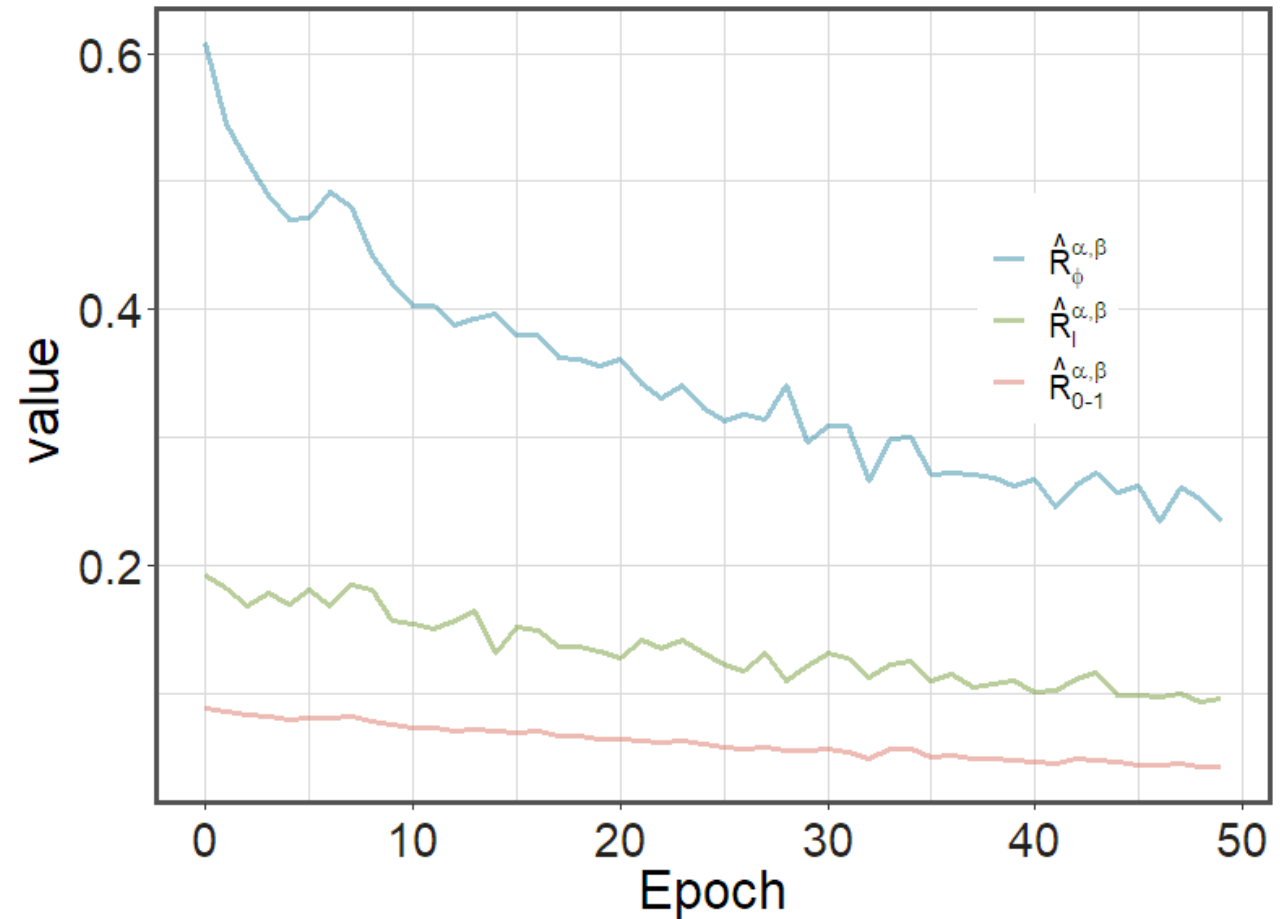
# Validation of the upper bound

- We show the training curve of different losses, where we consistently observe that :

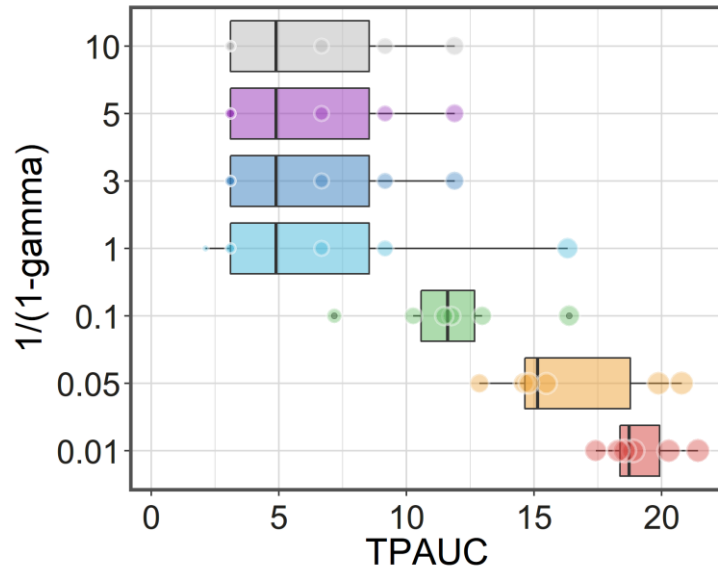
$$\hat{\mathcal{R}}_{\psi}^{\ell}(\mathcal{S}, f_{\theta}) > \hat{\mathcal{R}}_{\alpha, \beta}^{\ell}(\mathcal{S}, f_{\theta}) > \hat{\mathcal{R}}_{\alpha, \beta}^{0-1}(\mathcal{S}, f_{\theta})$$

App. Surr. Loss > Surr. Loss > emp. TPAUC

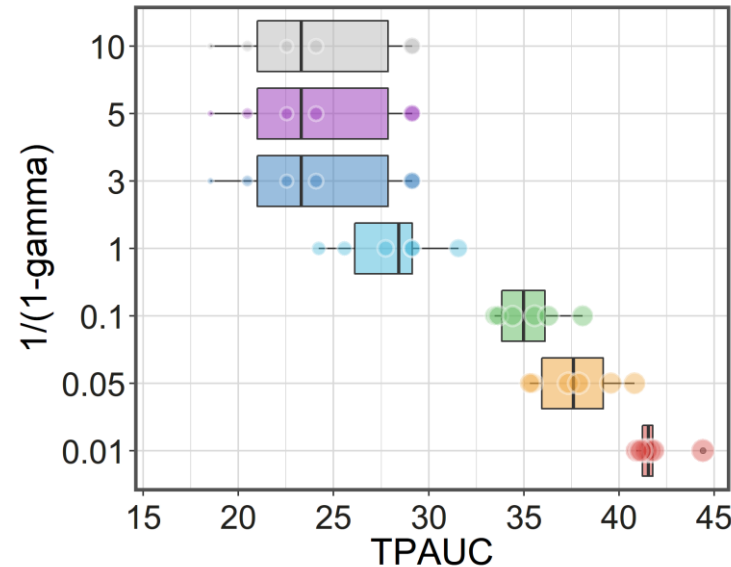
- This validate the proposed proposition about concave weights.



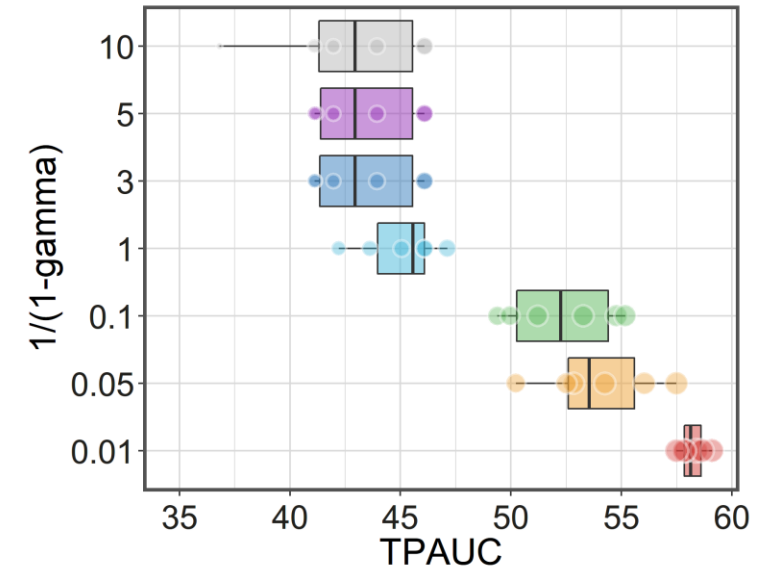
# Convex vs. Concave Weighting



$$\alpha = 0.3, \beta = 0.3.$$



$$\alpha = 0.4, \beta = 0.4.$$



$$\alpha = 0.5, \beta = 0.5.$$

- We analyze the effect of  $\gamma$  on CIFAR-10-Subset-1 with poly model
- The results shows that the concave function ( $(1 - \gamma)^{-1} < 1$ ) significantly outperforms convex functions ( $(1 - \gamma)^{-1} \geq 1$ )

# Conclusion

## Problem

How to optimize TPAUC (AUC with FPR upper bound and a TPR lower bound) in an **end-to-end** manner?

## Method

A Bi-level reformulation of ERM framework for TPAUC  
A relaxation scheme for sample selection of the inner-level problem  
A generic surrogate objective function based on the dual correspondence

## Theory

A sufficient condition for achieving the upper bound of the objective  
Concave weighting functions are easier to achieve the upper bound  
An  $\mathcal{O}((VC/n_+ + VC/n_-)^{1/2})$  excess risk bound for the approximated ERM



# Q&A