

# FlyingSquid: Speeding Up Weak Supervision with Triplet Methods



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Daniel Y. Fu\*, Mayee F. Chen\*, Frederic Sala, Sarah M. Hooper, Kayvon Fatahalian, and Christopher Ré.  
Fast and Three-rious: Speeding Up Weak Supervision with Triplet Methods. *ICML 2020*.

\* Denotes Equal Contribution



# The Training Data Bottleneck in ML



**Collecting training data can be slow and expensive**

# Weak Supervision - A Response

```
def L_1(comment):  
    return SPAM if  
        "http" in comment
```

```
def L_2(comment):  
    return NOT SPAM if  
        "love" in comment
```

User-Defined Functions



Crowd Workers



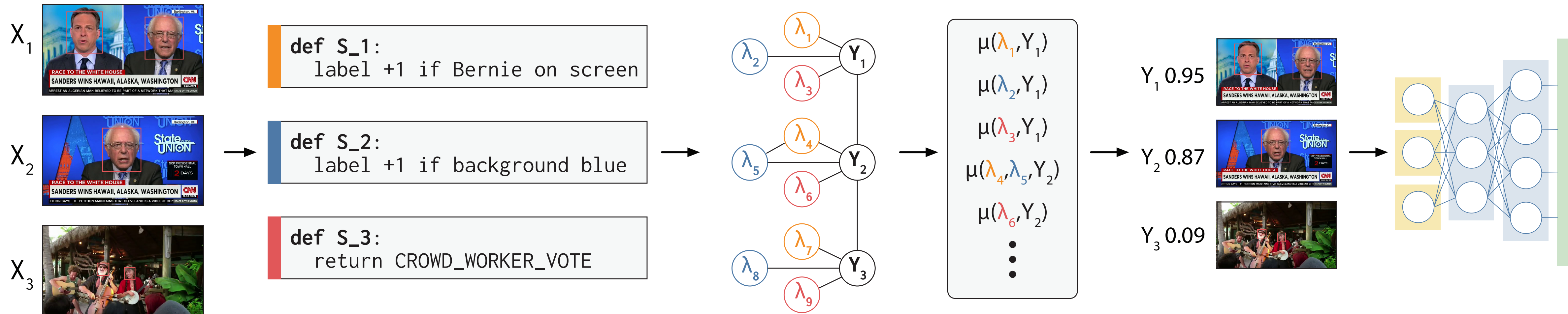
External Knowledge  
Bases

**How to best use multiple noisy sources of supervision?**

# Data Programming: Unifying Weak Supervision



snorkel<sup>[1]</sup>



Unlabeled Input

Labeling Functions

Latent Variable Model

Label Model

Probabilistic Training Labels

End Model

1 Users write *labeling functions*

2 Model labeling function behavior to de-noise them

3 Use the *probabilistic labels* to train a *downstream* model

[1] Ratner et al. Snorkel: Rapid Training Data Creation with Weak Supervision. VLDB 2018.

# Data Programming: Unifying Weak Supervision



snorkel<sup>[1]</sup>

Overtone: A Data System for Monitoring and Transcription



Christopher Apple



X<sub>3</sub>

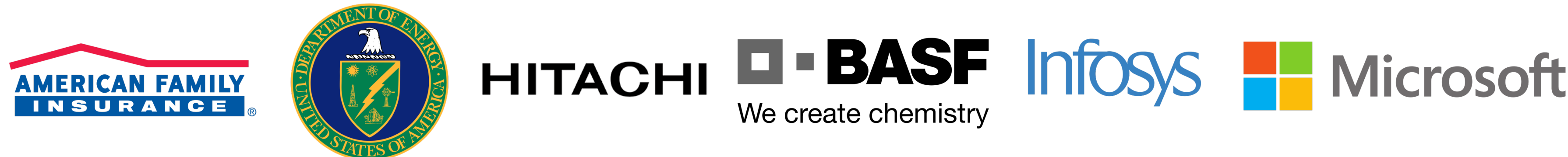
Unlabeled



1



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Khaled Saab <sup>1,5</sup>✉, Jared Dunnmon<sup>2,5</sup>, Christopher Ré<sup>2</sup>, Daniel Rubin <sup>3,5</sup> and Christopher Lee-Messer <sup>4,5</sup>✉



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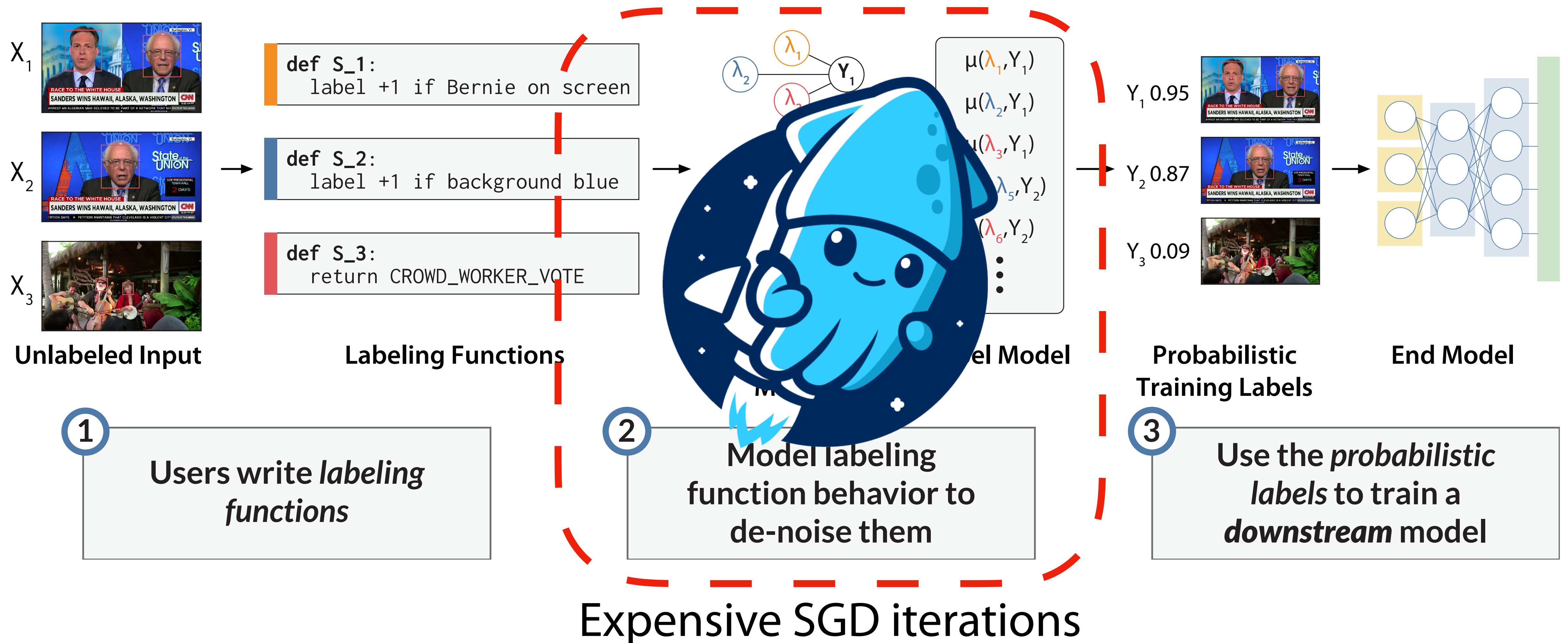
updates

Malkin<sup>‡</sup>

[1] Ratner et al. Snorkel: Rapid Training Data Creation with Weak Supervision. VLDB 2018.

# Weak Supervision: A Response

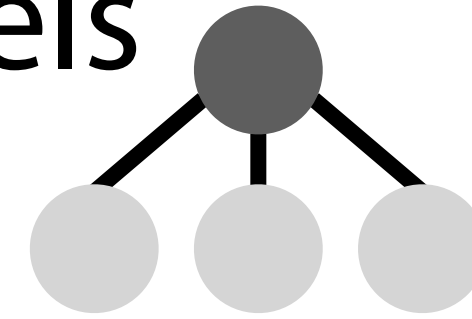
Modeling labeling functions critical, but can be slow...



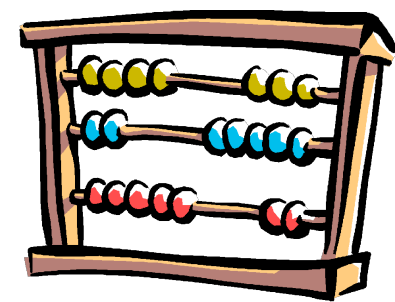
# FlyingSquid: Reduce the Turnaround Time



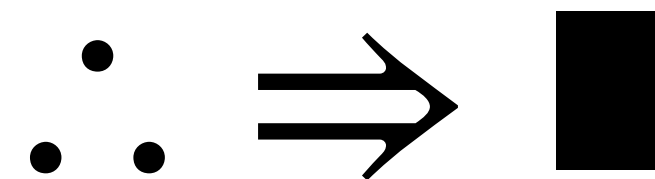
- Background: labeling functions and graphical models



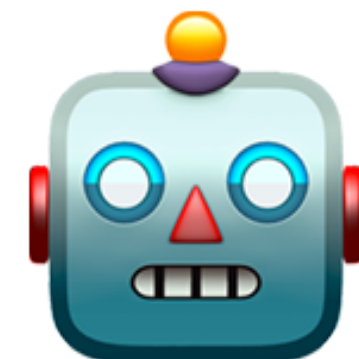
- Closed-form solution to model parameters, no SGD



- Theoretical bounds and guarantees



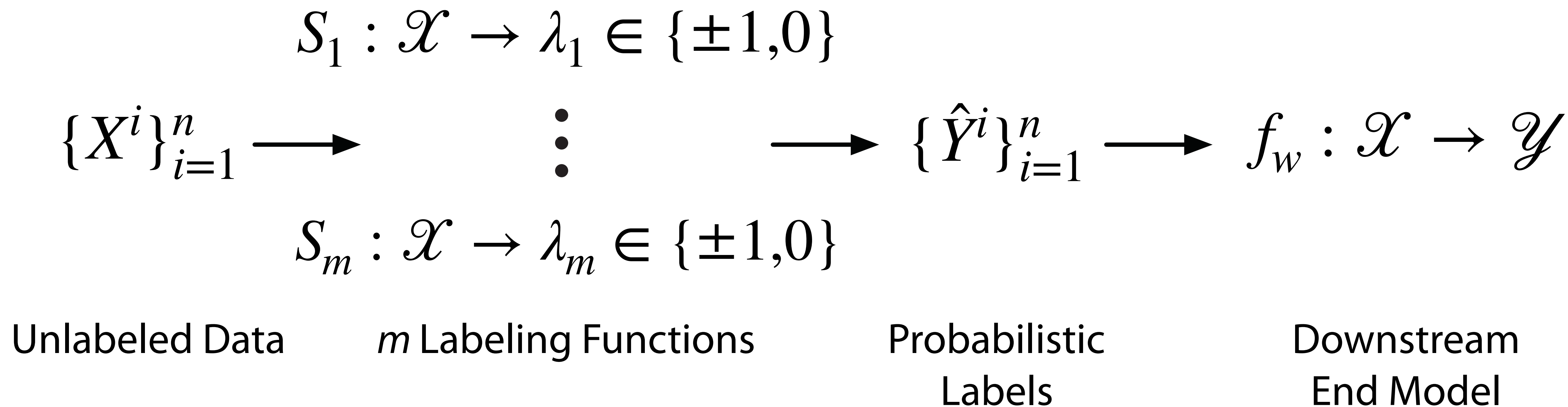
- Run orders of magnitude faster, without losing accuracy; weakly-supervised online learning



# Background

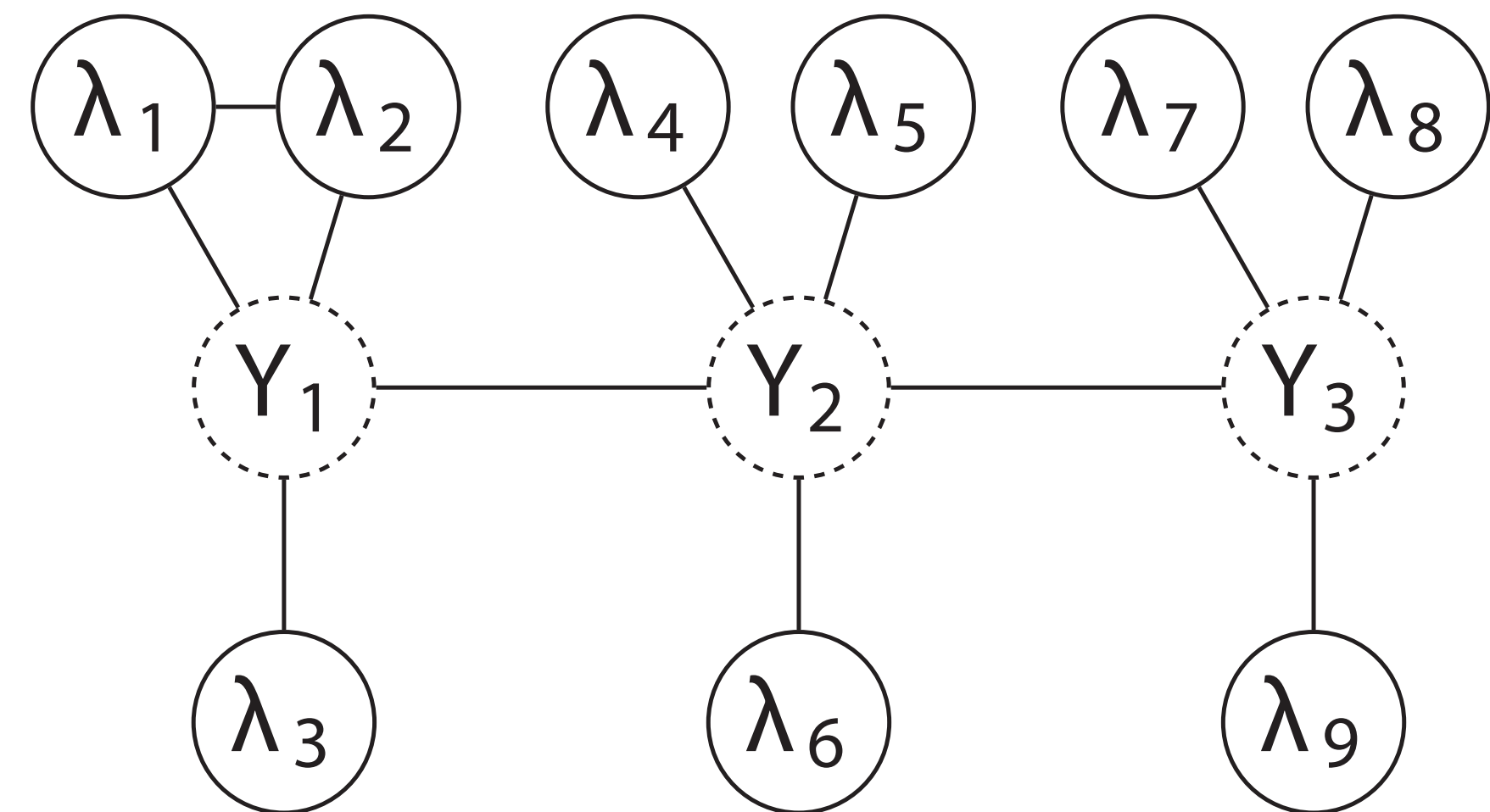
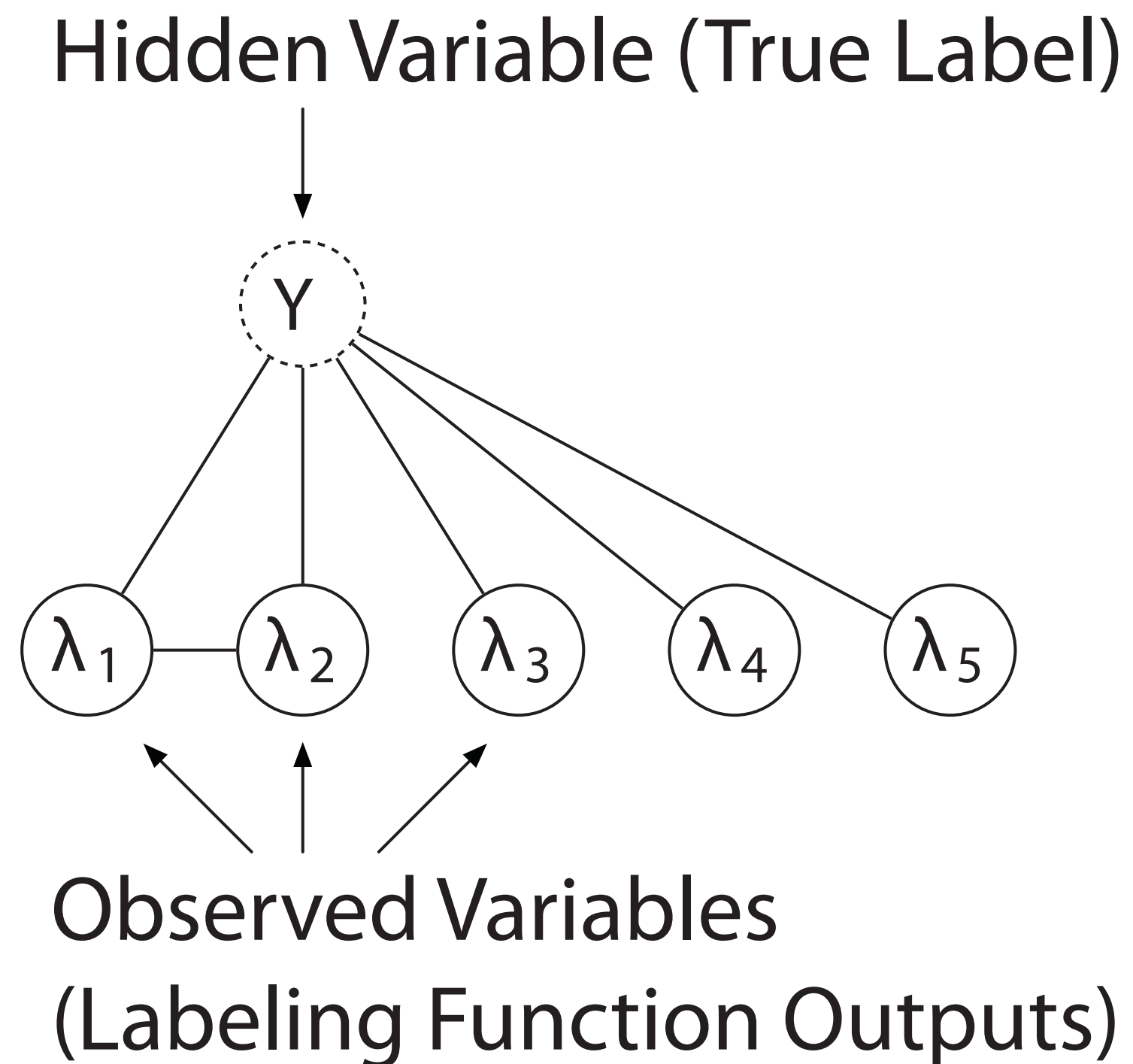


# Problem Setup



**We want to learn the joint distribution  $P(\lambda, Y)$ , without observing  $Y$ !**

# Model Labeling Functions with Latent Graphical Models



**Technical problem: learning parameters of these graphical models**  
**Main challenge: recover *accuracies*  $\mu$  of labeling functions**

[2] Varma et al. Learning Dependency Structures for Weak Supervision Models. *ICML 2019*.

# Parameter Recovery

# Existing Iterative Approaches Can Be Slow

SGD over loss function



**snorkel**

Ratner et al. 2016

Sala et al. 2019

Safranchik et al. 2020

Ratner et al. 2018

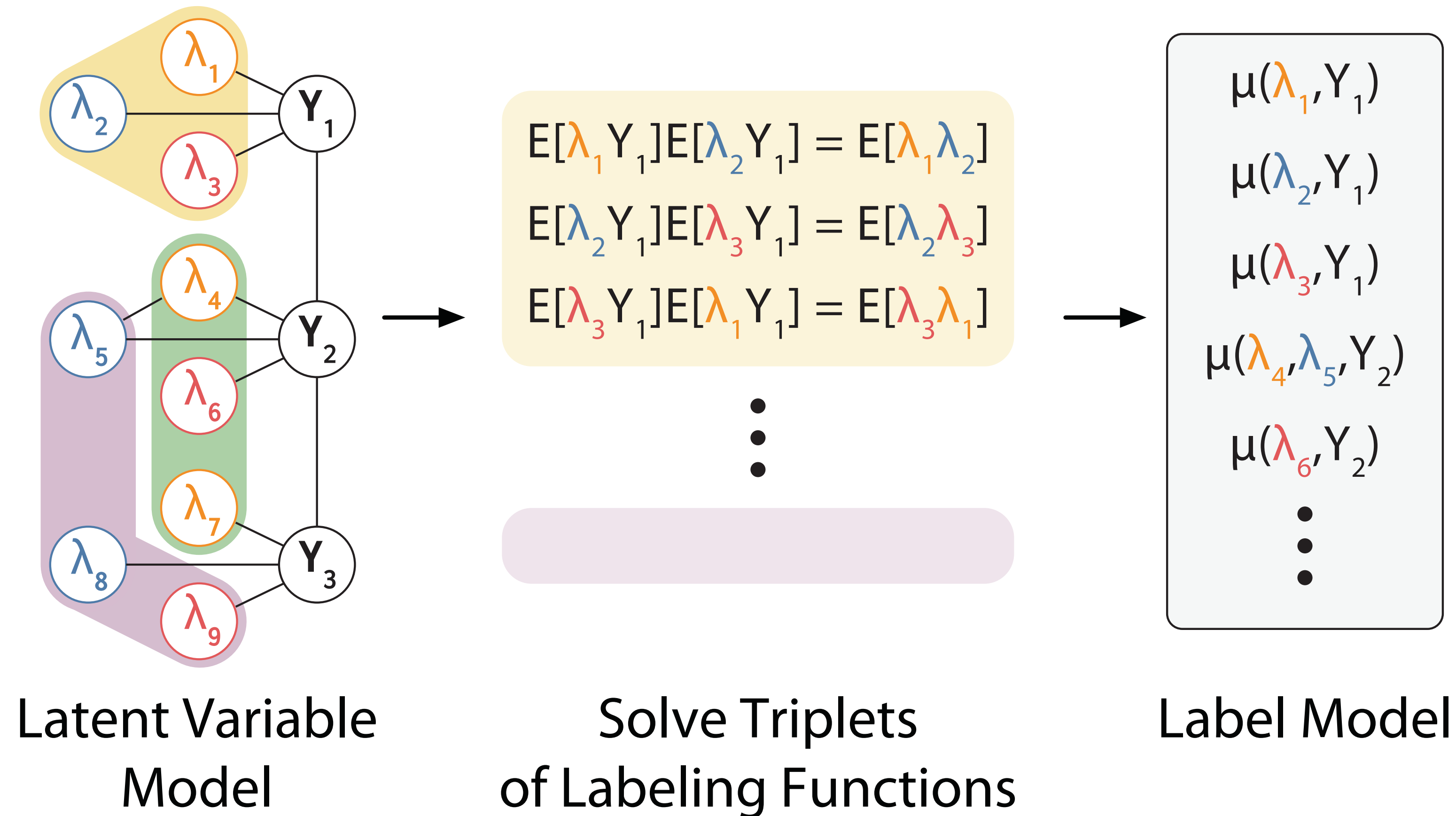
Zhan et al. 2019

Bach et al. 2019 (Gibbs)

Ratner et al. 2019

**Disadvantages: SGD can take a long time,  
many hyperparameters (learning rate, momentum, etc) to tune**

# Solve Triplets of Labeling Function Parameters at a Time



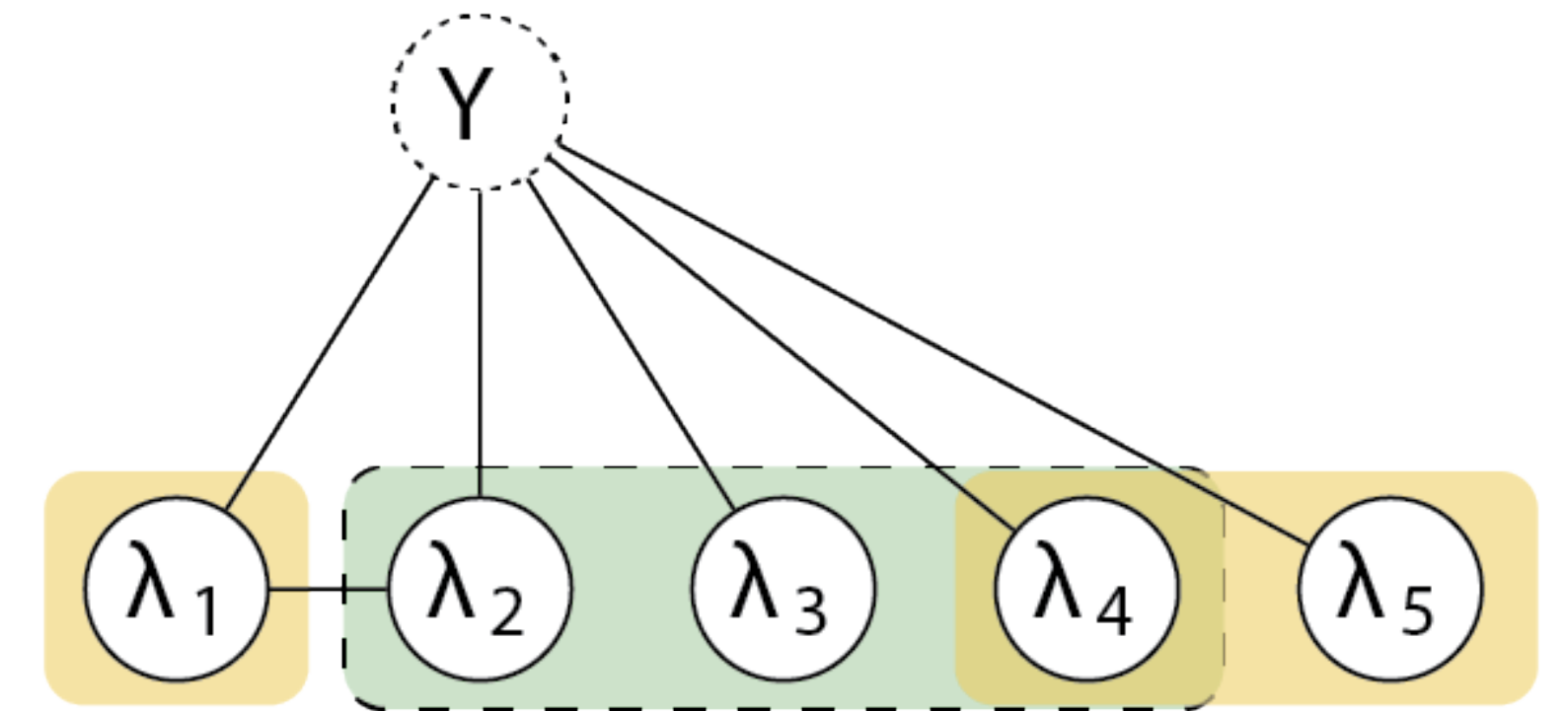
**Method of moments: break problem up into pieces, get *closed-form solutions***

# Triples of Conditionally-Independent Labeling Functions

$$\boxed{\mu_i \mu_j} = \boxed{N_{i,j}} = \boxed{E[\lambda_i \lambda_j]} \text{ Moment}$$

Unobservable  
accuracy parameters

Observable  
agreements



Form triplets of these equations:

$$\begin{aligned} \boxed{\mu_1 \mu_4} &= \boxed{N_{1,4}} \\ \boxed{\mu_1 \mu_5} &= \boxed{N_{1,5}} \\ \boxed{\mu_4 \mu_5} &= \boxed{N_{4,5}} \end{aligned}$$

$\Rightarrow$

Get closed-form solutions:

$$\begin{aligned} \boxed{|\mu_1|} &= \sqrt{N_{1,4} N_{1,5} / N_{4,5}} \\ \boxed{|\mu_4|} &= \sqrt{N_{1,4} N_{4,5} / N_{1,5}} \\ \boxed{|\mu_5|} &= \sqrt{N_{4,5} N_{1,5} / N_{1,4}} \end{aligned}$$

**All we need to do is count how often the labeling functions agree - no SGD!**

# Theoretical Analysis

# Bounding Sampling Error (Informal)

## Theorem 1: How Sampling Error Scales in $n$

Error in parameter estimate

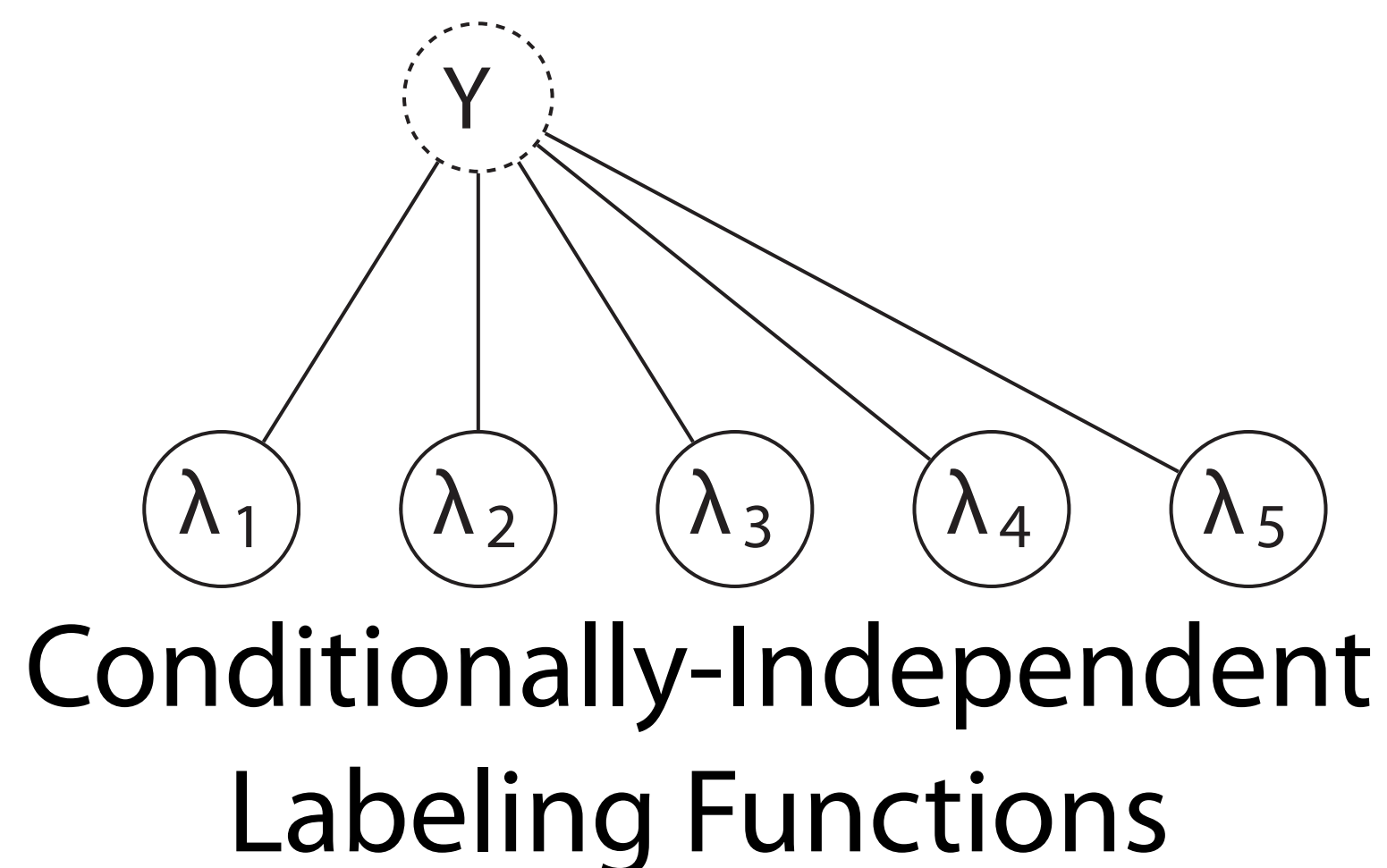
$$E[\|\hat{\mu} - \mu\|_2] \leq O(n^{-1/2})$$

Number of unlabeled data points

## Theorem 2: Optimal Scaling Rate

$$E[\|\hat{\mu} - \mu\|_2] \geq \Omega(n^{-1/2})$$

Best Possible Scaling Rate  
with Unlabeled Data



$\Rightarrow$  Bound is Tight



# End Model Generalization Error (Informal)

## Theorem 3: End Model Generalization Error

If you use parameters  $\hat{\mu}$  to generate labels  $\hat{Y}$  and train an end model  $f_{\hat{w}}$ ,

End model generalization error

$$E[L(\hat{w}, X, Y) - L(w^*, X, Y)] = O(n^{-1/2})$$

**This is the same asymptotic rate as with supervised data!**

More theory nuggets (check out our paper for details):

- We can achieve these rates even with model misspecification (graph is incorrect)
- Bounds for distributional drift over time in the online setting

# Evaluation & Implications

# We run faster, and get high quality

Label model training times (s):

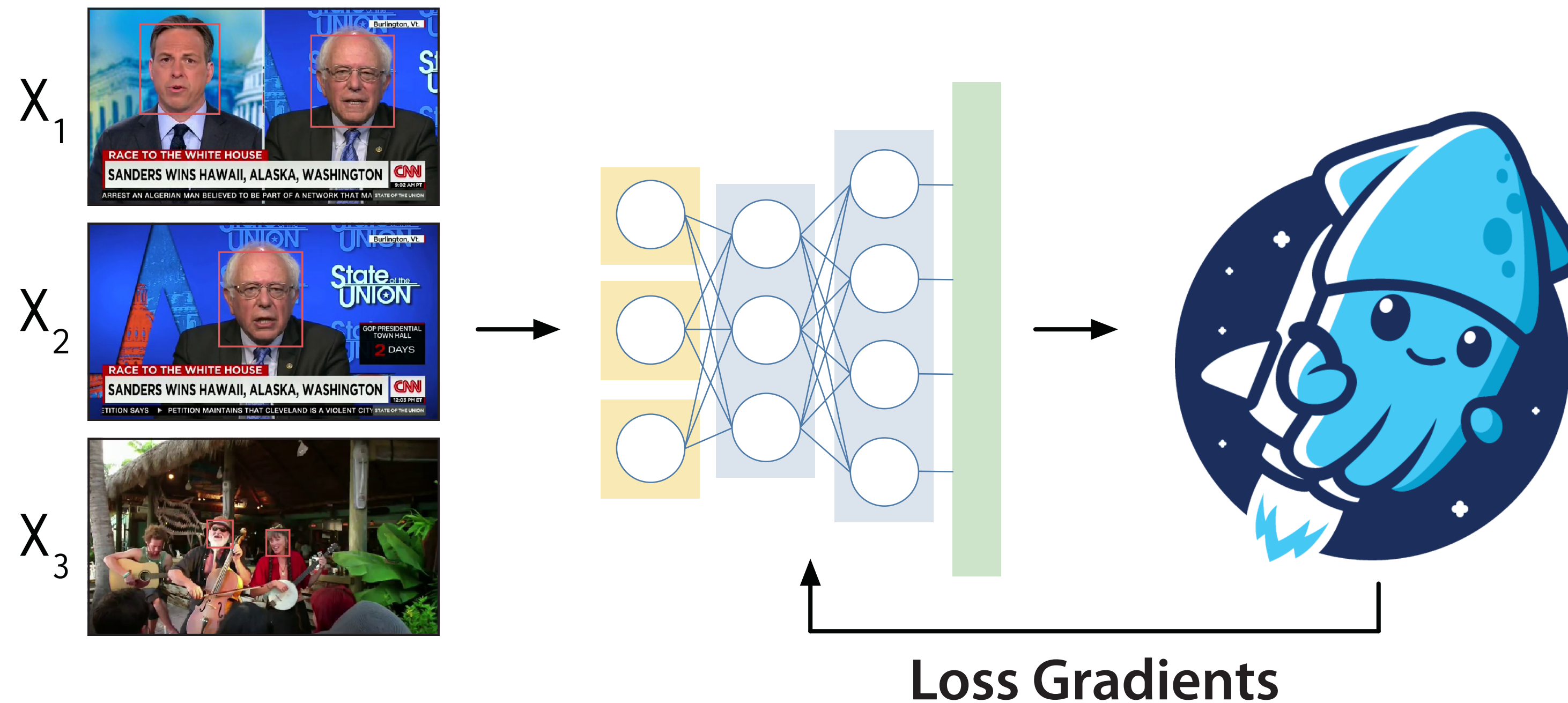
	<b>Snorkel</b>	<b>Temporal Snorkel</b>	<b>FlyingSquid</b>
<b>Benchmarks</b>	3.0	--	<b>0.06</b>
<b>Video Tasks</b>	41.5	<b>292.3</b>	<b>0.20</b>

End model accuracies (F1):

	<b>Snorkel</b>	<b>Temporal Snorkel</b>	<b>FlyingSquid</b>
<b>Benchmarks</b>	74.6	--	<b>77.0</b>
<b>Video Tasks</b>	47.4	<b>75.2</b>	<b>76.2</b>

# Re-training in the End Model Training Loop

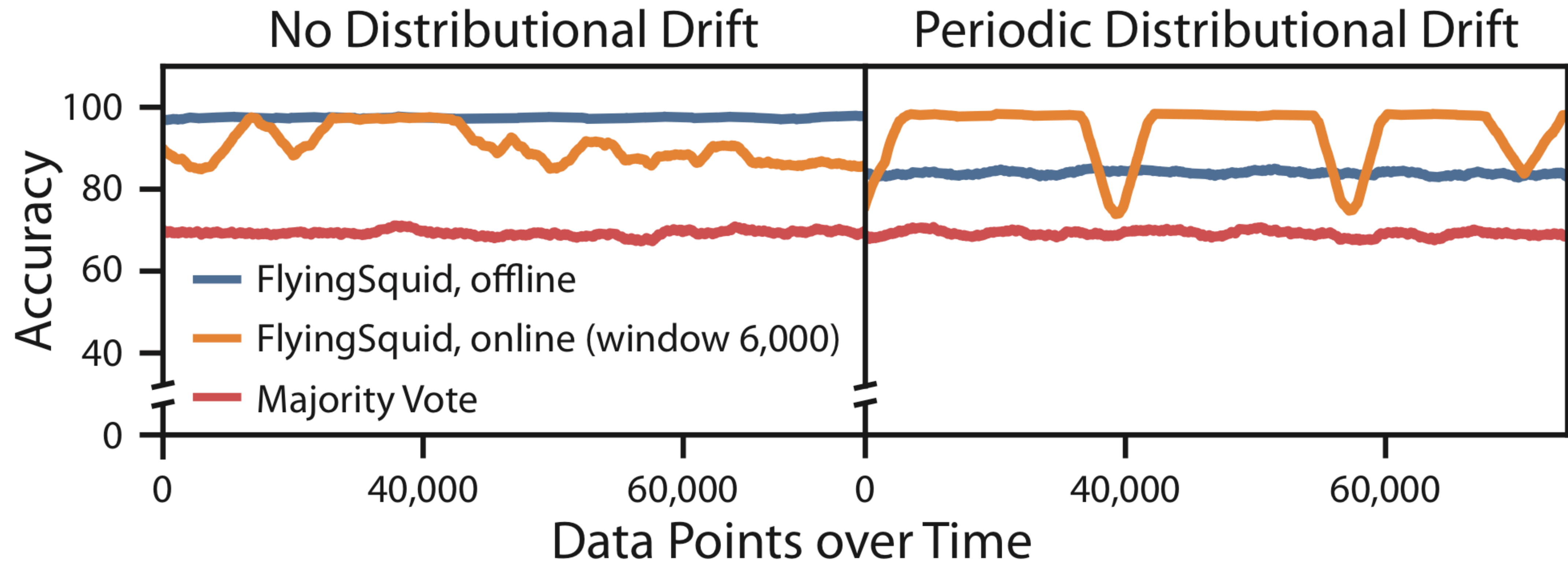
**No SGD -> re-train the label model *in the training loop* of an end model**



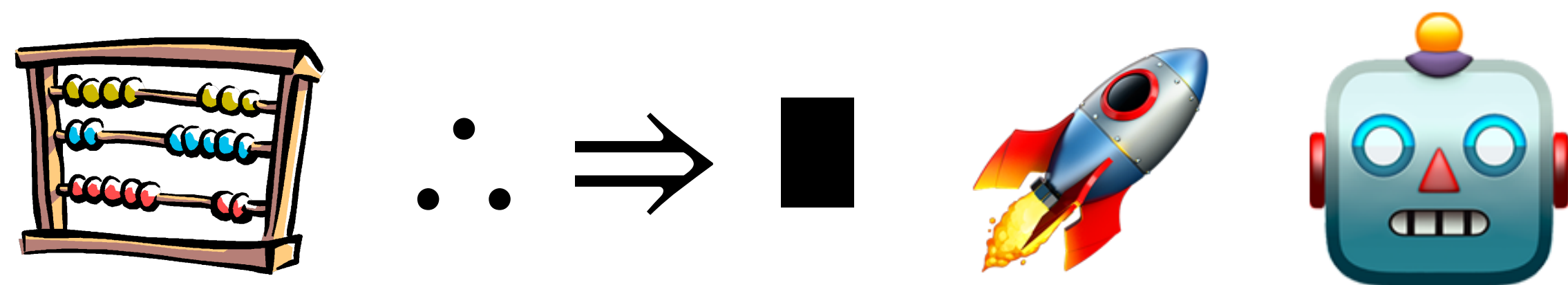
**PyTorch integration: FlyingSquid loss layer**

# Speedups enable online learning

**Online learning: re-train on a *rolling window***  
**Adapt to distributional drift over time**



# Thank you!



Contact: Dan Fu ([danfu@cs.stanford.edu](mailto:danfu@cs.stanford.edu), [@realDanFu](https://twitter.com/realDanFu))

Code: <https://github.com/HazyResearch/flyingsquid>

Blog Post (Towards Interactive Weak Supervision with FlyingSquid):  
<http://hazyresearch.stanford.edu/flyingsquid>

Fast and Three-rious: Speeding Up Weak Supervision with Triplet Methods:  
<https://arxiv.org/abs/2002.11955>



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