#### **ICML 2020**

#### Learning to Simulate and Design for Structural Engineering

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Why is this important?

## **Problem: Structural Design for Buildings**

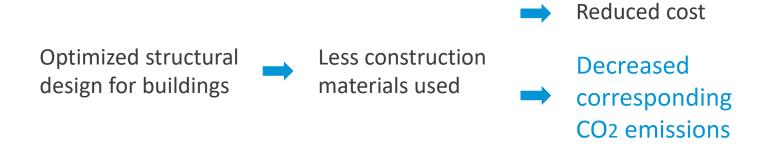
According to the International Energy Agency (IEA 2017),

# Buildings and construction caused ~ 40% of global energy-related $CO_2$ emissions.

\*Buildings: 28%; Construction 11%

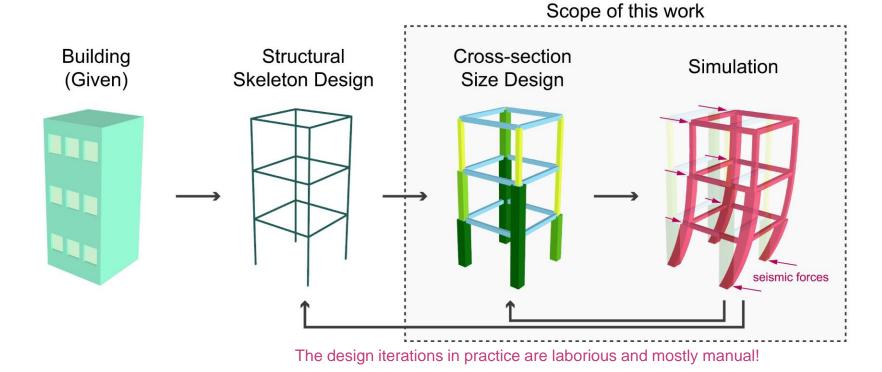
Source: derived with IEA (2017), World Energy Statistics and Balances, IEA/OECD, Paris, www.iea.org/statistics

### **Problem: Structural Design for Buildings**

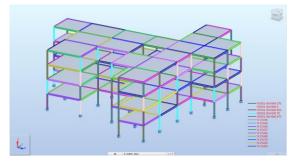


# What Is Structural Design?

A common structural design workflow:

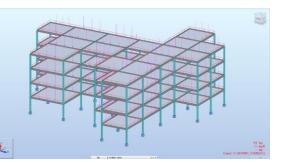


### **Components and Constraints**



#### **Cross Section Library**

Column	Beam
HSSQ 16x16x0.375	W21x44
HSSQ 16x16x0.5	W21x48
HSSQ 16x16x0.625	W21x50
HSSQ 16x16x0.75	W21x57
HSSQ 16x16x0.875	W21x62
	W21x68
	W21x73
	W21x83
	W21x93



Load Cases

#### Dead Load (L)

- Self Weight
- Super-imposed
- Roof
- Cladding Load

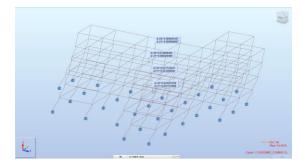
#### Live Load (Lr)

- Floor
- Roof

Seismic (E)

Combination

- 1.2D + 1.6L + 0.5Lr
- 0.9D + 1.0E (X and Y)

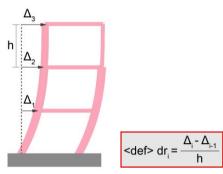


#### Simulation Results

Drift Ratio in Ex and Ey

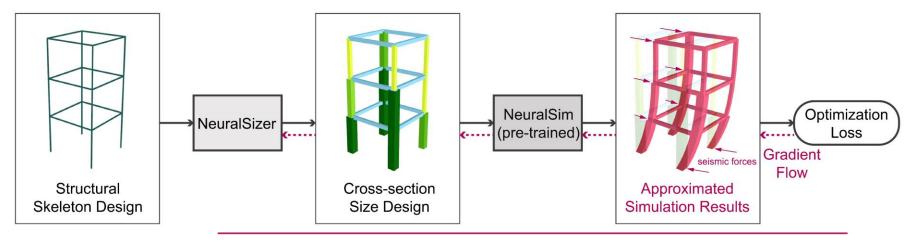
For each story

 $dr_x, dr_y$ 



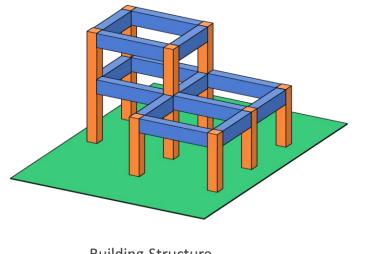
# Pipeline

Swingparadelici (Nigional Size Coan) diorad Sitin) ization



Slow, and completely relying on the engineer's knowledge, experience, and intuition

# What is the proper representation?



Building Structure

Voxel?

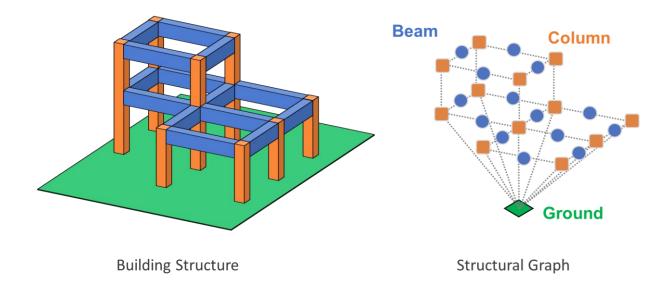
Point clouds?

Meshes?

Images with multi-views?

It contains discrete components, is usually large at scale, and has strong connectivity relations.

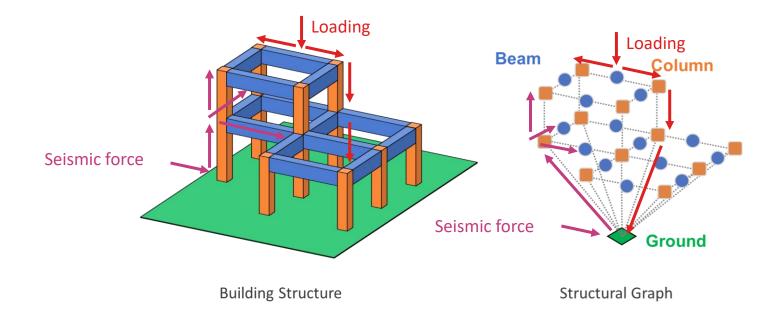
### Intuition: Representing Structures as Graphs



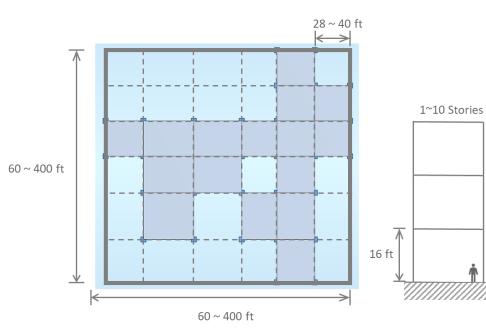
Node feature

Posi	tions	0: column	One hot vector of			
x <sub>1</sub> , y <sub>1</sub> , z <sub>1</sub>	x <sub>2</sub> , y <sub>2</sub> , z <sub>2</sub>	1: beam	cross section type	if roof	Metal deck area	if boundary

#### Force Transmissions vs. Message Passing

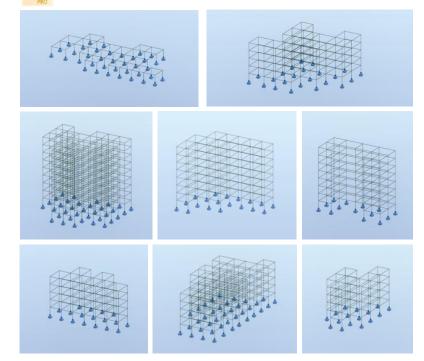


#### **Data Generation**



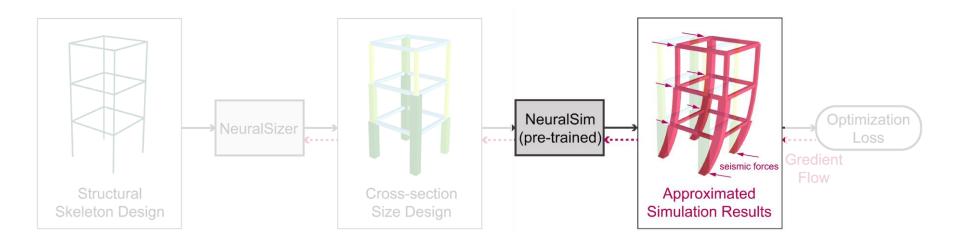


Using Autodesk<sup>®</sup> Robot<sup>TM</sup> Structural Analysis (free for educational use)



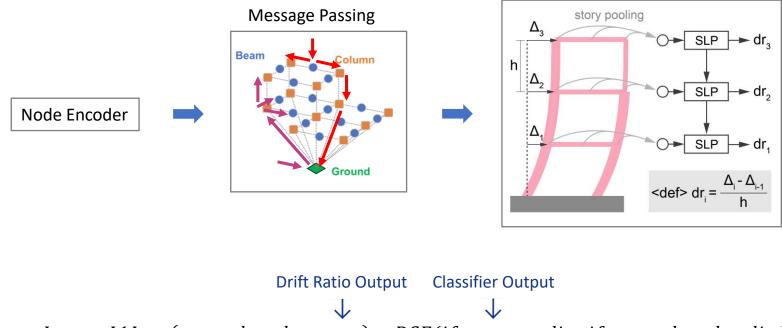
# NeuralSim

#### A Graph-Based Neural Approximator for Structural Simulation



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#### A Graph-Based Neural Approximator for Structural Simulation



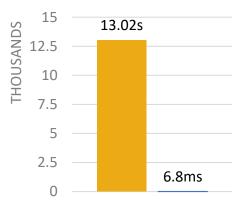
#### Structured Decoder

Loss = L1Loss(groundtruth, output) + BCE(if output > lim, if groundtruth > lim)

# NeuralSim: Performance

Table 1. NeuralSim Performance Compared To Other Models				
Model	L1 Loss $\times 1e-4$	Relative Accuracy	Classification Accuracy	
GCN	16.01	94.86	89.22	
GIN	33.85	89.62	84.27	
GAT	10.87	96.41	93.35	
PGNN	9.39	96.72	94.83	
NeuralSim	7.57	97.36	95.64	
NeuralSim + PGNN	5.01	98.22	96.43	
NeuralSim(no SD)	10.24	96.65	92.71	
NeuralSim(only L1 loss)	16.47	95.24	n/a	

#### Speed: ~ 1900x faster

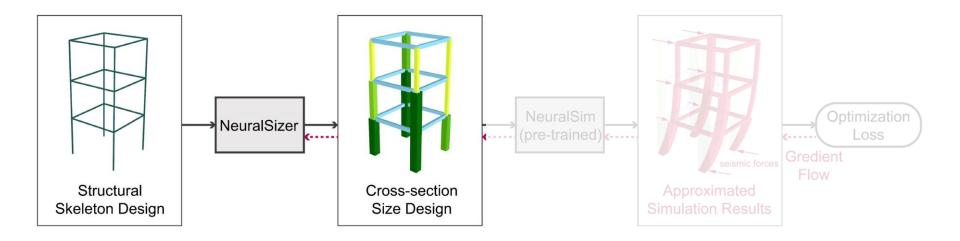


Robot Structural Analysis

NeuralSim

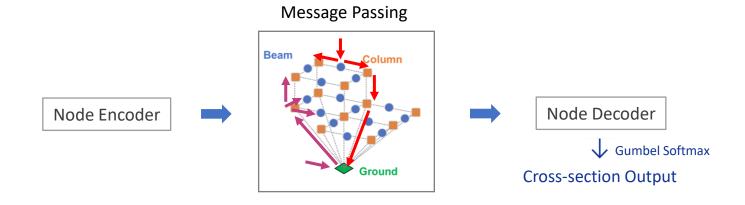
# NeuralSizer

#### A Graph Neural Network for Proposing Optimal Size Design



# NeuralSizer

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# NeuralSizer + NeuralSim:

Optimization Setup min objective s.t. constraints

Mass Objective

 $obj = \sum_{bar} length \times area \times density$ 

Drift Ratio Constraints

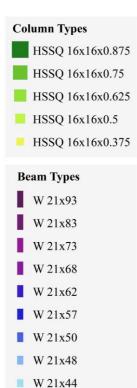
 $l_{dr} = Mean\{LeakyReLU(|dr_k| - lim)\} \le 0$ 

Variety Constraints

 $l_{var} = 1 - SumTop6(usage_{percentage}) = 0$ 

Entropy Constraints

$$l_H = Mean\{H_i\}/H_{max} - \alpha = 0$$



## NeuralSizer + NeuralSim:

Table 3. NeuralSizer Results Under Different Scenarios					
Scenario	Objective Weight	Objective	Constraints		
Scenario	Objective weight	Mass Objective	Drift Ratio Constraint	Variety Constraint	
High Safety Factor	1	0.870	$6.00 \times 1e - 7$	$0.01 \times 1e - 8$	
	10	0.735	$1.34 \times 1e - 7$	$1.04 \times 1e - 8$	
Low Safaty Factor	1	0.592	$6.42 \times 1e - 5$	$1.67 \times 1e - 8$	
Low Safety Factor	10	0.596	$3.32 \times 1e - 5$	$1.78 \times 1e - 8$	

High / Low Safety Factor : Drift Ratio Limit 0.015 / 0.025

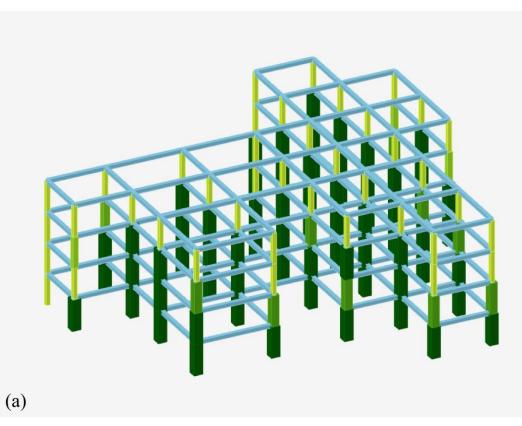
Train Data Test Data		Objective	Constraints	
ITalli Dala	Test Data	Mass Objective	Drift Ratio Constraint	Variety Constraint
$1 \sim 10$ story	$1 \sim 3$ story	0.738	$1.62 \times 1e - 7$	$0.80 \times 1e - 8$
(Baseline)	$4{\sim}7$ story	0.725	$1.28 \times 1e - 7$	$0.97 \times 1e - 8$
(Dasenne)	$8 \sim 10$ story	0.711	$1.69 \times 1e - 7$	$1.06 \times 1e - 8$
	$1 \sim 3$ story	0.773	$2.96 \times 1e - 7$	1.30×1e-8
$4 \sim 7$ story	$4{\sim}7$ story	0.746	$3.50 \times 1e - 7$	$1.25 \times 1e - 8$
	$8 \sim 10$ story	0.728	$3.68 \times 1e - 7$	$1.01 \times 1e - 8$

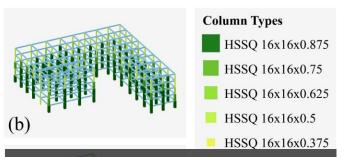
*Table 4.* NeuralSizer Generalizability (High Safety Factor, Objective Weight = 10)

#### Inference Time: 5.41ms

# NeuralSizer + NeuralSim:

#### **Result Visualization**





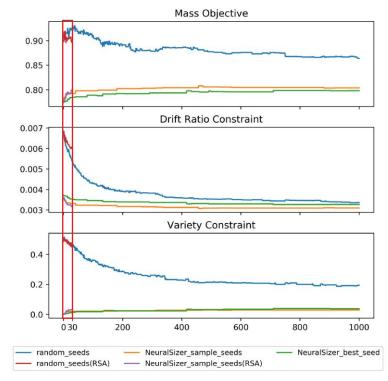
### Structural Engineers' Insights

- 1. Columns are generally<sub>21x83</sub> thicker on lower floors<sub>1x73</sub>
- 2. Prioritize using stronger columns over beams<sup>v 21x62</sup> w 21x57
- 3. Similar patterns/strategies across different buildings

## Speed Comparison with Genetic Algorithm (G.A.)

Table 5. Time Comparison of GA under Different Setups				
Setup	Time	Total	Time /	
		Iterations	Iteration	
NeuroSizer	10.07 ms	-	-	
GA + RSA	24 hr	30	-	
$\rightarrow (estimated)$	2 weeks	1000	20.16 mins	
GA + NeuralSim	30 mins	1000	0.03 mins	

Figure 3. Performance Curves of GA Using Different Seeding Approaches.



## G.A. with Random vs. NeuralSizer Seed

Tabl	le 6. NeuralSizer	· Seeding Perfor	mance	
Metric	Mass Objective	Drift Ratio Constraint	Variety Constraint	
High Safe	ty Factor			This is just an illustrati
1 2 3	232.60% 7.43% 0	115.30% 25.70% 25.6	186.20% 95.82% 0	1 Random seed
Low Safet	y Factor			2
1	83.15%	95.35%	156.22%	NeuralSizer sampled seed
2	4.16%	49.22%	32.53%	<b>3</b> ↔
3	128	0	0	

### Conclusion

- We propose an end-to-end pipeline for cross-section size design optimization problem in structural engineering
  - NeuralSim Fast, accurate
  - NeuralSizer Qualified design comparable GA results

 Research on improving building and construction performance can bring positive impact, especially on energy consumptions and CO<sub>2</sub> emissions

Open-source data is public at <u>https://github.com/AutodeskAILab/LSDSE-Dataset</u>