

Individual Fairness for k -Clustering

Sepideh Mahabadi
TTIC

Ali Vakilian
University of Wisconsin-Madison

Fairness

Classic Objective in Algorithms

- Accuracy
- Runtime
- Space



Fairness

Classic Objective in Algorithms

- Accuracy
- Runtime
- Space



But, user interactions with algorithms have other implications

- Loans Approval
- Candidate for Job Interviews
- Candidate for Medical Treatments



Bias in Algorithms?

Notions of Fairness

Notions of Fairness

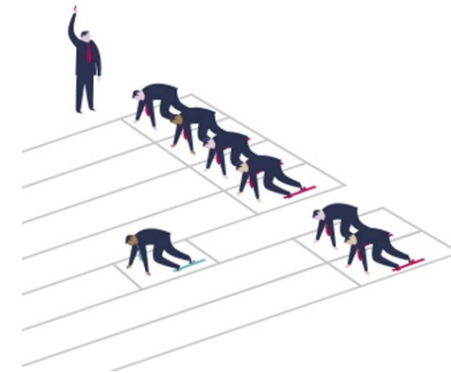


Group Fairness

Notions of Fairness



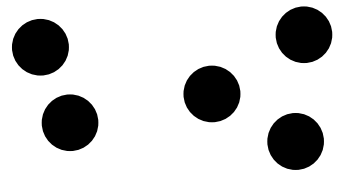
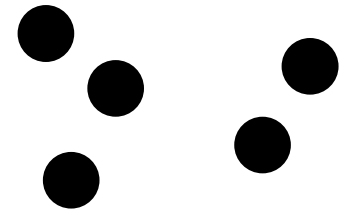
Group Fairness



Individual Fairness

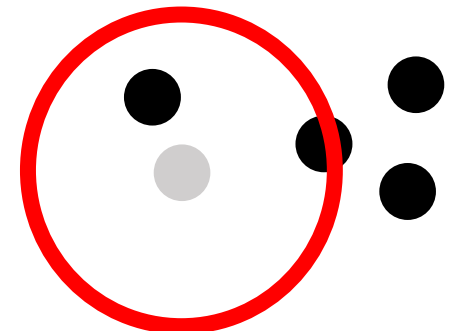
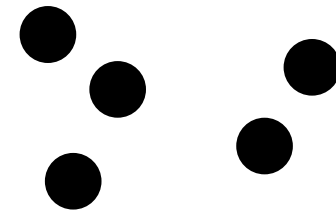
Fairness for Clustering

- **Clustering:** one of the most important *unsupervised learning* tasks



Fairness for Clustering

- **Clustering:** one of the most important *unsupervised learning* tasks
- **Individual Fairness** for Clustering
[Jung-Kannan-Lutz'20]

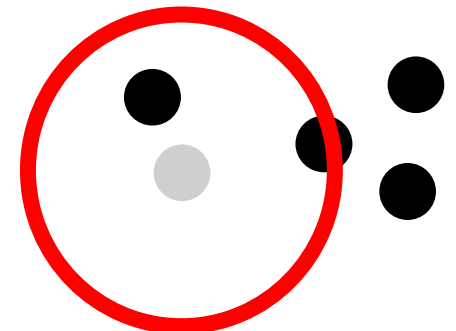
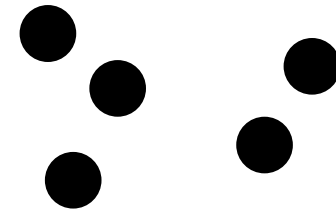


Fairness for Clustering

- **Clustering:** one of the most important *unsupervised learning* tasks
- **Individual Fairness** for Clustering
[Jung-Kannan-Lutz'20]

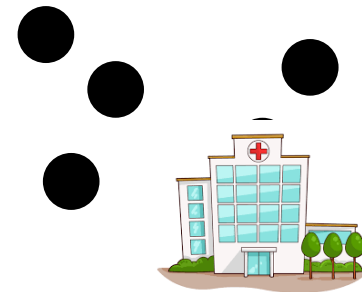
Picking k centers,

Each expects to see a center among its $\frac{n}{k}$ closest neighbors



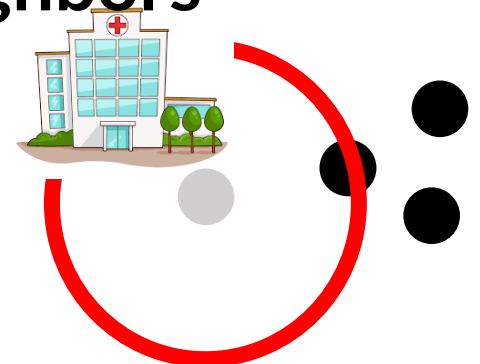
Fairness for Clustering

- **Clustering:** one of the most important *unsupervised learning* tasks
- **Individual Fairness** for Clustering
[Jung-Kannan-Lutz'20]

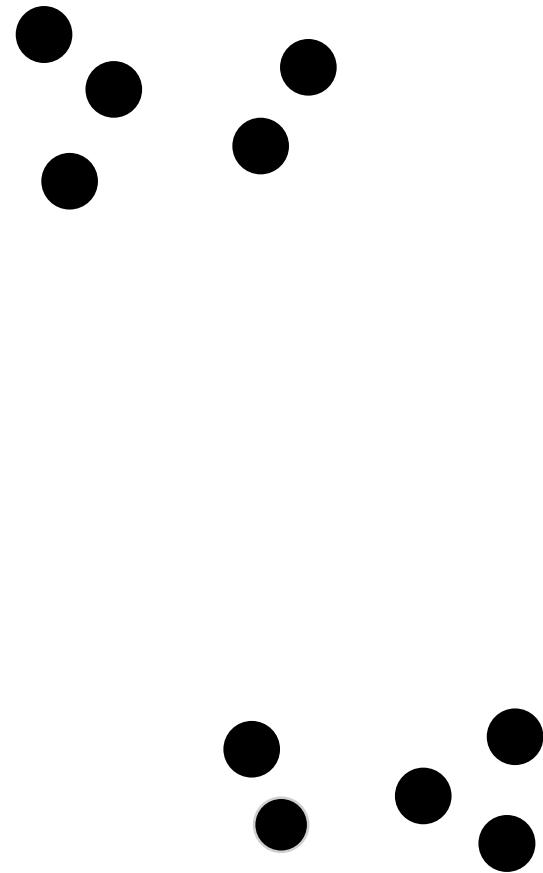


Picking k centers,

Each expects to see a center among its $\frac{n}{k}$ closest neighbors

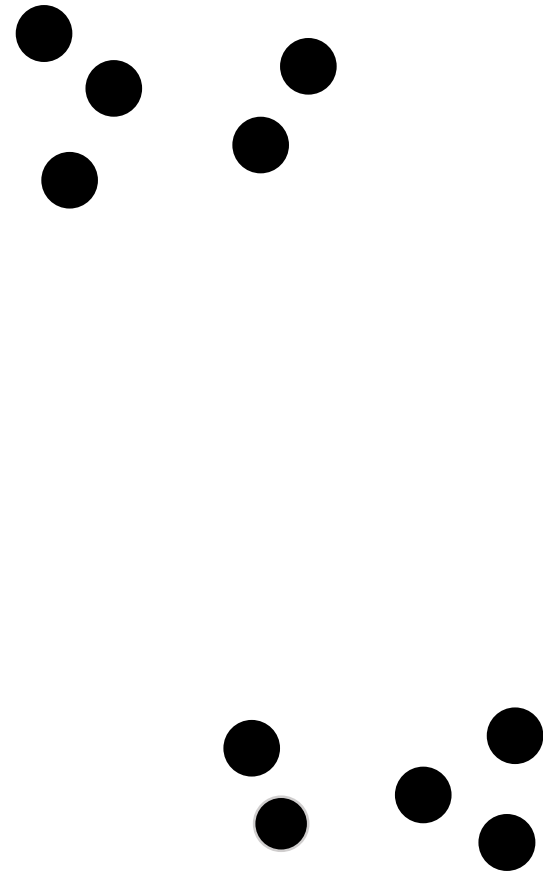


Clustering with Individual Fairness



Clustering with Individual Fairness

- Collection of n points in a metric space

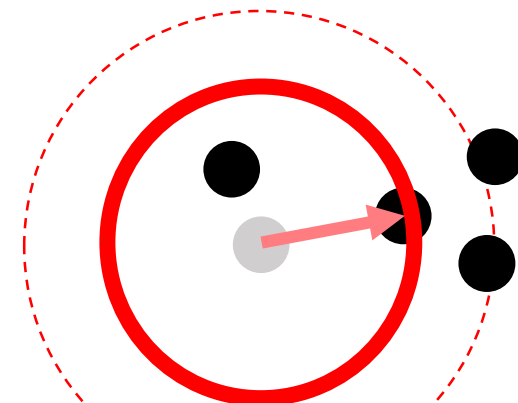
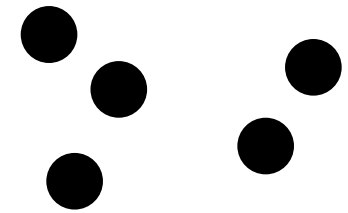


Clustering with Individual Fairness

□ Collection of n points in a metric space

□ Fair Radius ($r_{\text{fair}}(v)$):

distance of v to its (n/k) -th closest neighbor



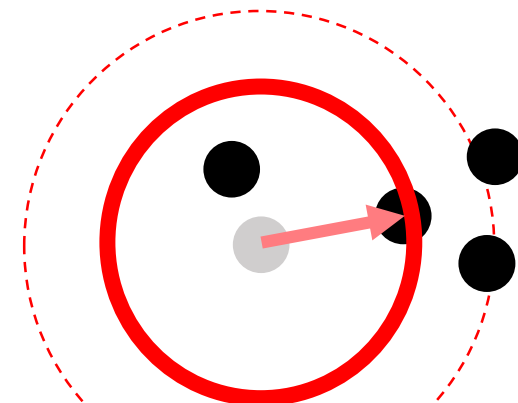
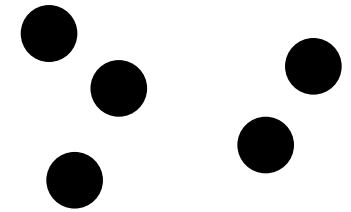
Clustering with Individual Fairness

□ Collection of n points in a metric space

□ Fair Radius ($r_{\text{fair}}(v)$):

distance of v to its (n/k) -th closest neighbor

[JKL20] NP-hard to decide whether there exists a fair solution

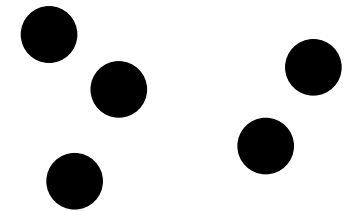


Clustering with Individual Fairness

□ Collection of n points in a metric space

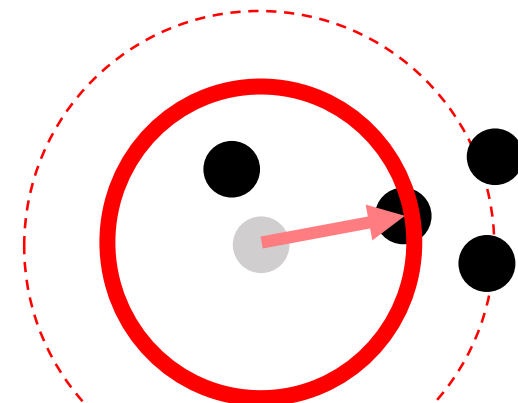
□ Fair Radius ($r_{\text{fair}}(v)$):

distance of v to its (n/k) -th closest neighbor



[JKL20] NP-hard to decide whether there exists a fair solution

□ **α -Fair k -Clustering**: Find k centers s.t. each v has a center in distance at most $\alpha \times$ its fair radius (i.e., $r_{\text{fair}}(v)$)



Prior Work

[Jung, Kannan, Lutz'20] introduces this notion of fairness

Prior Work

[[Jung, Kannan, Lutz'20](#)] introduces this notion of fairness

- Finds a **2-fair** solution

Prior Work

[Jung, Kannan, Lutz'20] introduces this notion of fairness

- Finds a **2-fair** solution

- Each v has a center in distance at most $2 \cdot r_{\text{fair}}(v)$

Prior Work

[Jung, Kannan, Lutz'20] introduces this notion of fairness

- Finds a **2-fair** solution

- Each v has a center in distance at most $2 \cdot r_{\text{fair}}(v)$

- In [Chan-Dinitz-Gupta'06] & [Charikar-Makarychev-Makarychev'10]

Prior Work

[Jung, Kannan, Lutz'20] introduces this notion of fairness

- Finds a **2-fair** solution

- Each v has a center in distance at most $2 \cdot r_{\text{fair}}(v)$

- In [Chan-Dinitz-Gupta'06] & [Charikar-Makarychev-Makarychev'10]

Only a fair solution, without optimizing the clustering cost

Prior Work

[Jung, Kannan, Lutz'20] introduces this notion of fairness

- Finds a **2-fair** solution
 - Each v has a center in distance at most $2 \cdot r_{\text{fair}}(v)$
 - In [Chan-Dinitz-Gupta'06] & [Charikar-Makarychev-Makarychev'10]

Only a fair solution, without optimizing the clustering cost

- ***k-median***: total distance of points to their centers
- ***k-means***: total squared distance of points to their centers
- ***k-center***: maximum distance of any point to its center

Our Results

[This work] Local search returns $(O(1), O(1))$ approximation for α -fair k -median clustering.

Our Results

[This work] Local search returns $(O(1), O(1))$ approximation for α -fair k -median clustering. *I.e., finds a set of k centers \mathbf{C} s.t.*

- \mathbf{C} is $O(\alpha)$ -fair and
- cost of \mathbf{C} is at most *constant* times the cost of an *optimal α -fair solution*

Our Results

[This work] Local search returns $(O(1), O(1))$ approximation for α -fair k -median clustering. *I.e., finds a set of k centers \mathbf{C} s.t.*

- \mathbf{C} is $O(\alpha)$ -fair and
- cost of \mathbf{C} is at most *constant* times the cost of an *optimal α -fair solution*

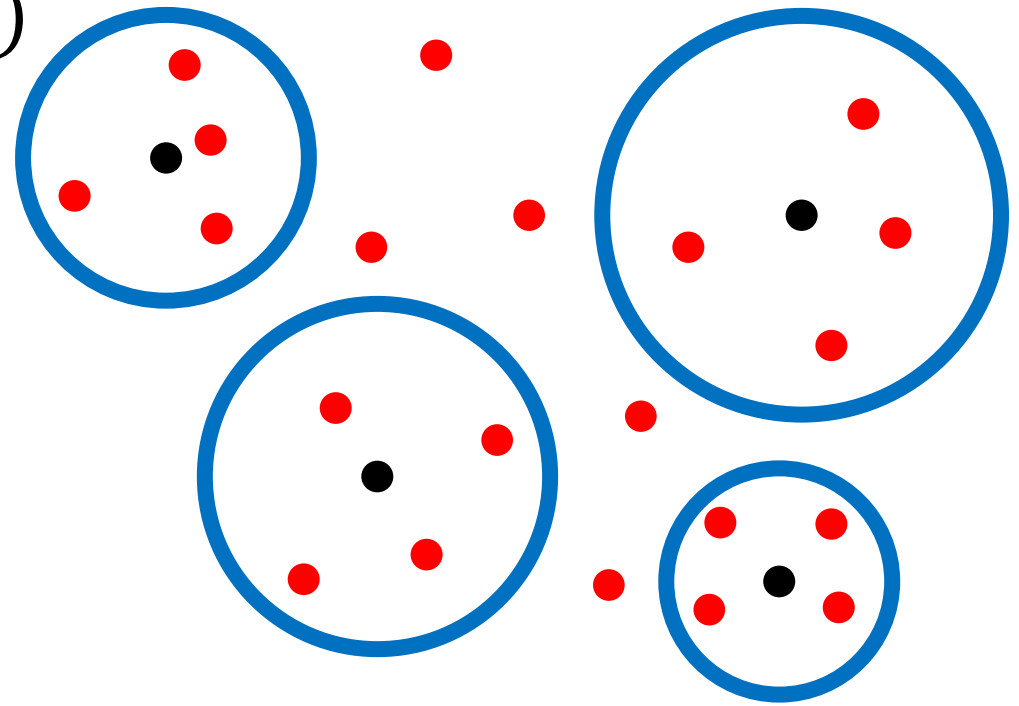
Our algorithm works for any ℓ_p -norm objective (e.g., k -means & k -center)

- k -means: $O(\alpha)$ -fair and cost is *constant* times the optimal α -fair k -means
- k -center: $O(\alpha)$ -fair and cost is $O(\log n)$ times the optimal α -fair k -center

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

$B(c_1, \alpha r_{\text{fair}}(c_1)), \dots, B(c_k, \alpha r_{\text{fair}}(c_\ell))$

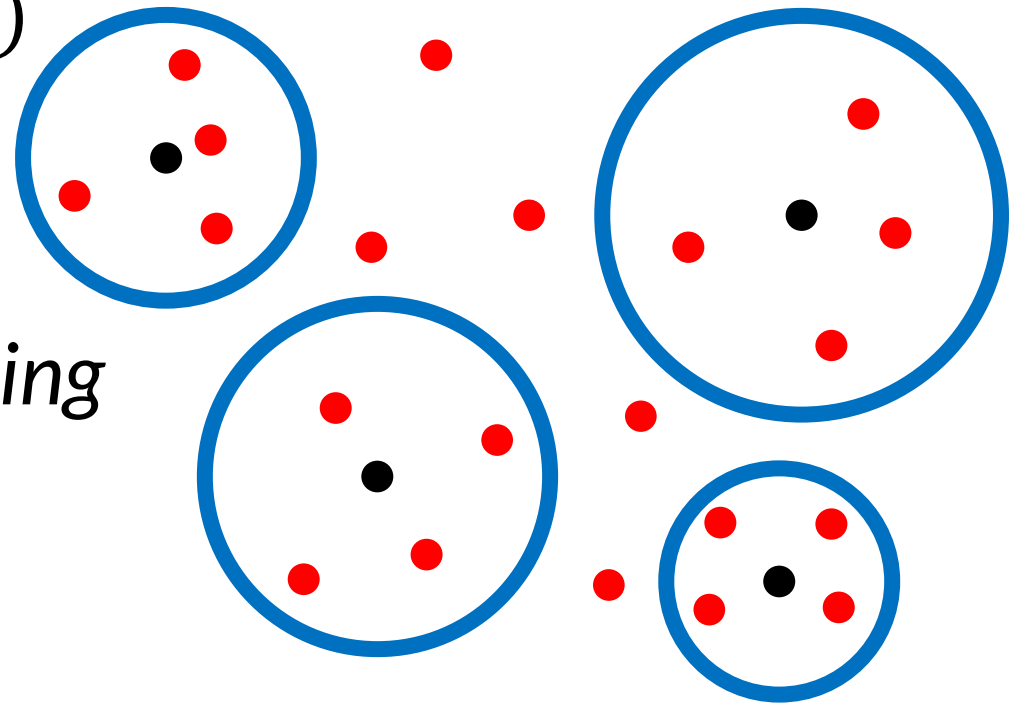


Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

$B(c_1, \alpha r_{\text{fair}}(c_1)), \dots, B(c_k, \alpha r_{\text{fair}}(c_\ell))$

Lemma. *Any set of k centers intersecting with critical balls is $O(\alpha)$ -fair.*



Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an **initial (fair) solution**

- I. Pick the centers of critical balls
- II. In $k - \ell$ remaining iterations
 - I. Pick the furthest point from the current set of centers

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

- I. Pick the centers of critical balls
- II. In $k - \ell$ remaining iterations
 - I. Pick the furthest point from the current set of centers

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

*Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?*

Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

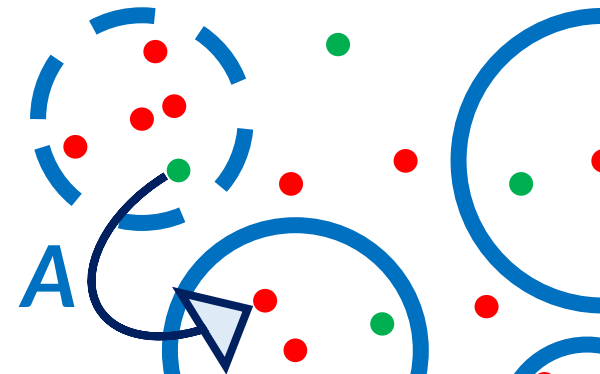
Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?



Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

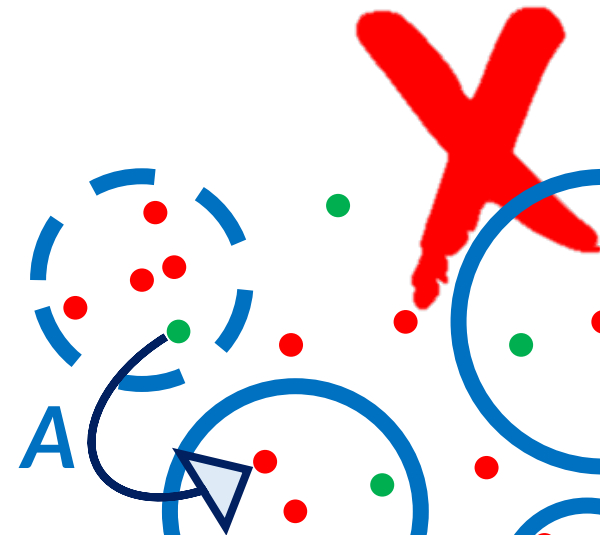
Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

*Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?*

- Not all swaps are feasible



Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

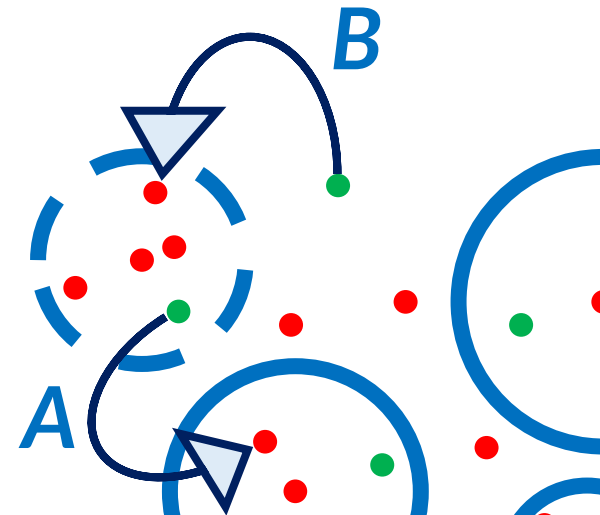
Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?

- Not all swaps are feasible



Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

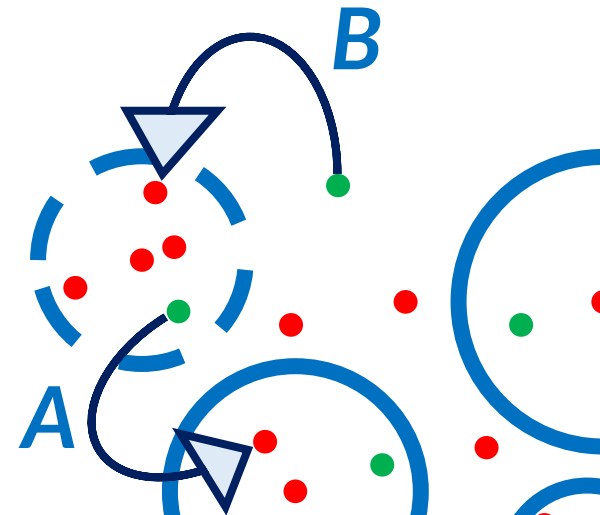
$O(n)$ -approximation

Step 2-b. Local Update

Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?

- Not all swaps are feasible

requires more complex analysis



Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

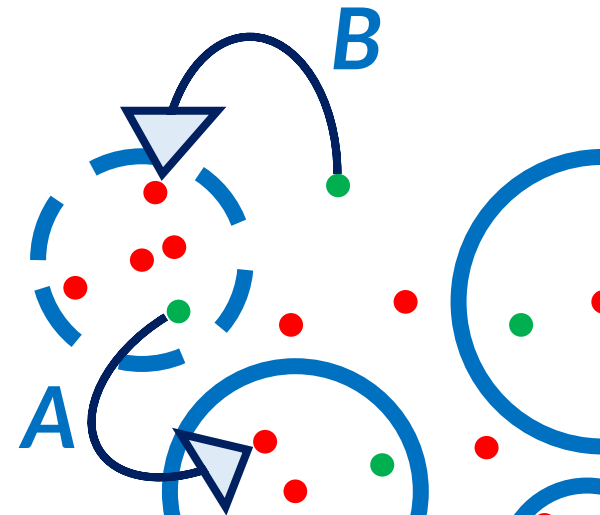
Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?

- Not all swaps are feasible
requires more complex analysis
- “valid” swaps of size at most four suffices



Outline of Our Algorithm

Step 1. Find a set of **critical balls** of size $\ell \leq k$

Step 2. Run **local search** algorithm

Step 2-a. Find an initial (fair) solution

$O(n)$ -approximation

Step 2-b. Local Update

Is there a **swap** of size at most t reducing cost by $(1+\epsilon)$?

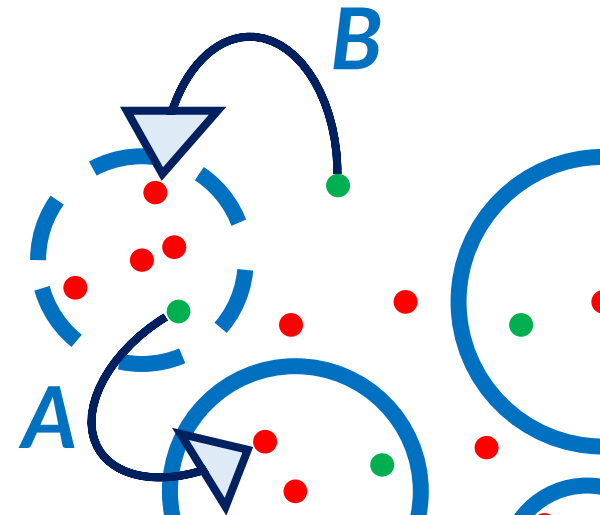
- Not all swaps are feasible

requires more complex analysis

- “valid” swaps of size at most four suffices

□ The algorithm terminates after $O(\log n/\epsilon)$ iterations

□ Each iteration runs in $O(k^4 n^4)$



Empirical Evaluation

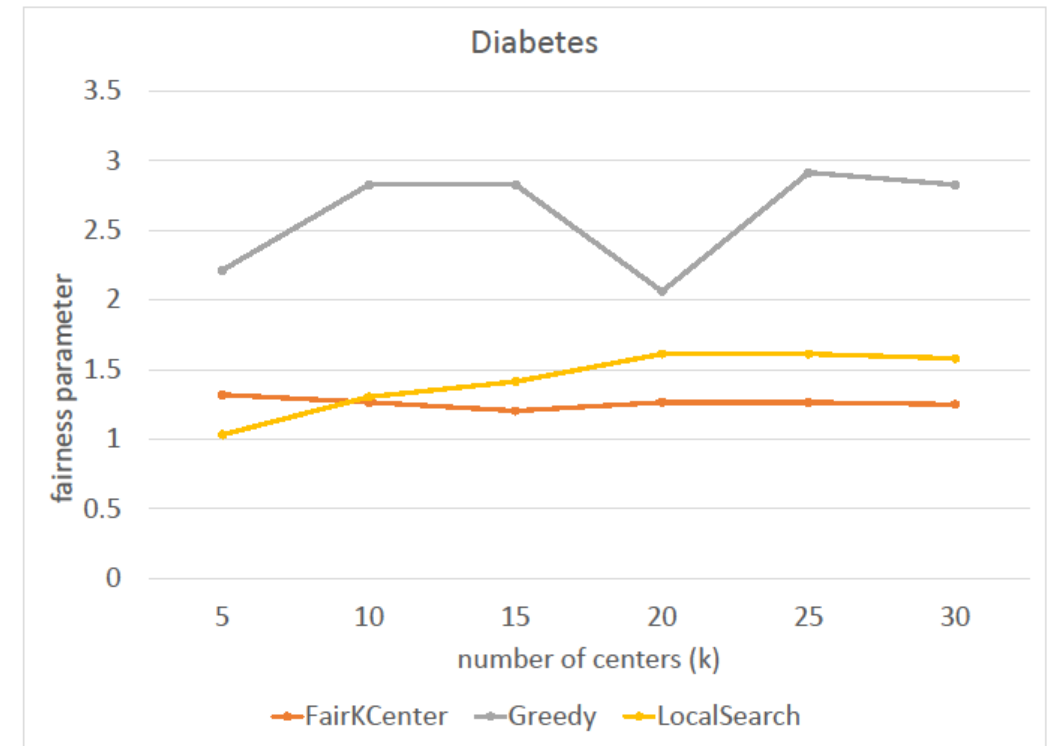
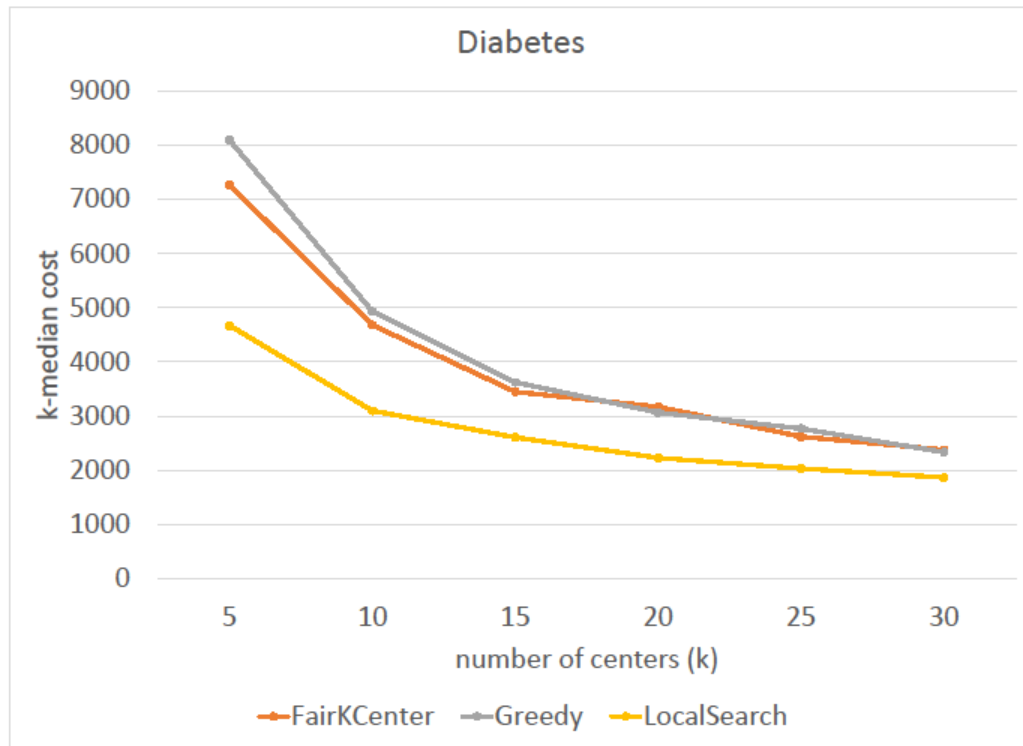
- UCI datasets: Diabetes, Bank, Census

Dataset	Dimension	#Points
Diabetes	2	101,765
Bank	3	4,520
Census	5	32,560

- **Local Search** reports a solution with
 - Better cost than [\[JKL20\]](#) by a factor of 1.4, 2.25, and 1.93
 - Worse fairness than [\[JKL20\]](#) by a factor of 1.13, 1.5, and 1.16

Empirical Evaluation

- UCI datasets: Diabetes, Bank, Census



Future Directions

- Scalable algorithms w.r.t this notion of fairness?
- Better analysis of Local Search algorithm (with smaller swap sizes)?
- Constant-factor approximation for fair k -center problem?
Our result implies a $(O(1), O(\log n))$ -approximation algorithm

Future Directions

- Scalable algorithms w.r.t this notion of fairness?
- Better analysis of Local Search algorithm (with smaller swap sizes)?
- Constant-factor approximation for fair k -center problem?
Our result implies a $(O(1), O(\log n))$ -approximation algorithm

Thank You