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in collaboration with

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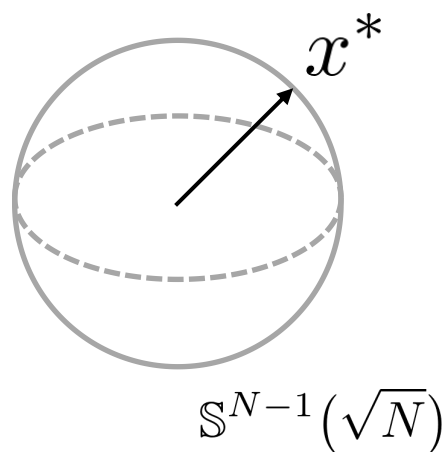
Lenka Zdeborová

ICML 2019

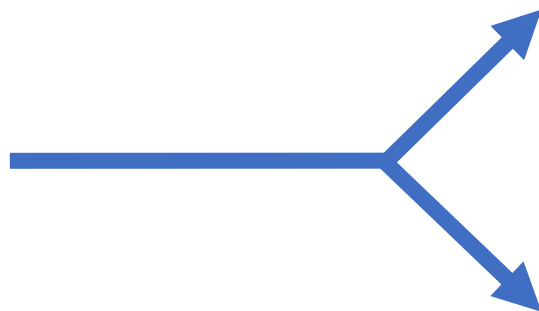
Descent Algorithms and Local Minima in Spiked Matrix- Tensor Models



Spiked Matrix-Tensor Model



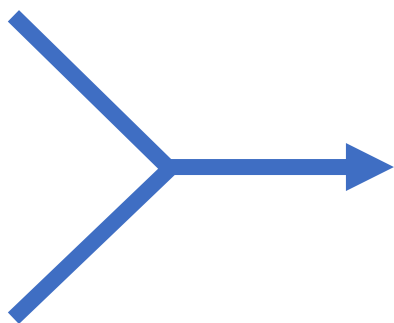
$$Y_{ij} = \frac{1}{\sqrt{N}} x_i^* x_j^* + \xi_{ij} \sim \mathcal{N}(0, \Delta_2)$$



$$T_{ijk} = \sqrt{\frac{(p-1)!}{N^{p-1}}} x_i^* x_j^* x_k^* + \xi_{ijk} \sim \mathcal{N}(0, \Delta_p)$$

Spiked Matrix-Tensor Model

$$Y_{ij} = \frac{1}{\sqrt{N}} x_i^* x_j^* + \xi_{ij}$$



$$x^* = ?$$

$$\hat{x} = \arg \min_x \mathcal{L}(x)$$

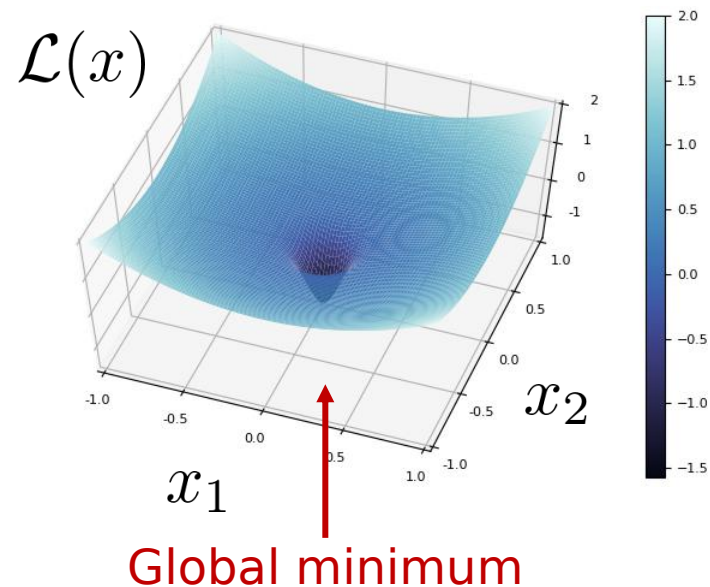
minus log-likelihood

$$T_{ijk} = \sqrt{\frac{(p-1)!}{N^{p-1}}} x_i^* x_j^* x_k^* + \xi_{ijk}$$

Spiked Matrix-Tensor Model

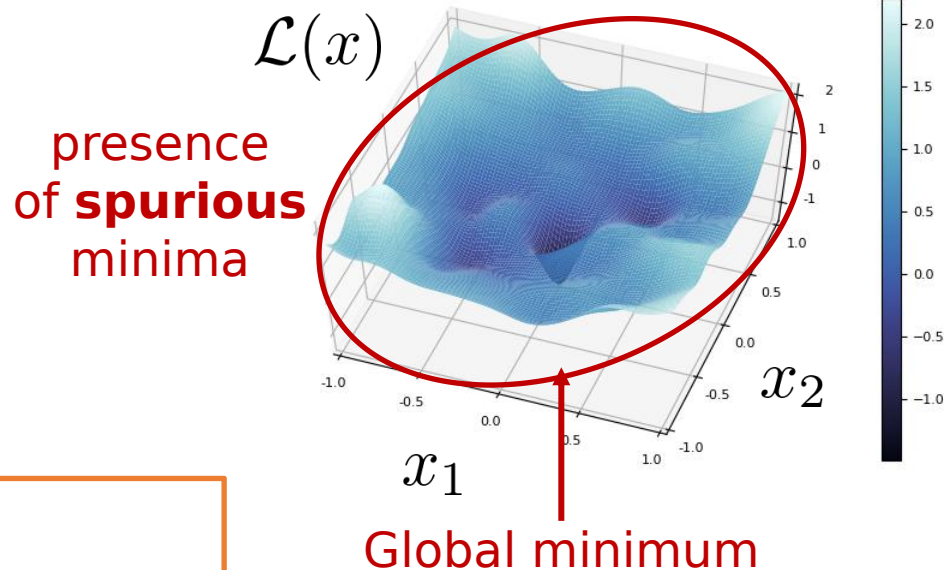
$$Y_{ij} = \frac{1}{\sqrt{N}} x_i^* x_j^* + \xi_{ij}$$

$$T_{ijk} = \sqrt{\frac{(p-1)!}{N^{p-1}}} x_i^* x_j^* x_k^* + \xi_{ijk}$$



Spiked Matrix-Tensor Model

$$Y_{ij} = \frac{1}{\sqrt{N}} x_i^* x_j^* + \xi_{ij}$$



$$T_{ijk} = \sqrt{\frac{(p-1)!}{N^{p-1}}} x_i^* x_j^* x_k^* + \xi_{ijk}$$

Gradient Flow Analysis

Analytical analysis of **gradient flow dynamics**.

$$\frac{\partial}{\partial t} C(t, t') = 2R(t', t) - \mu(t)C(t, t') + Q'(m(t))m(t') + \int_0^t dt'' R(t, t'')Q''(C(t, t''))C(t', t'') + \int_0^{t'} dt'' R(t', t'')Q'(C(t, t'')),$$

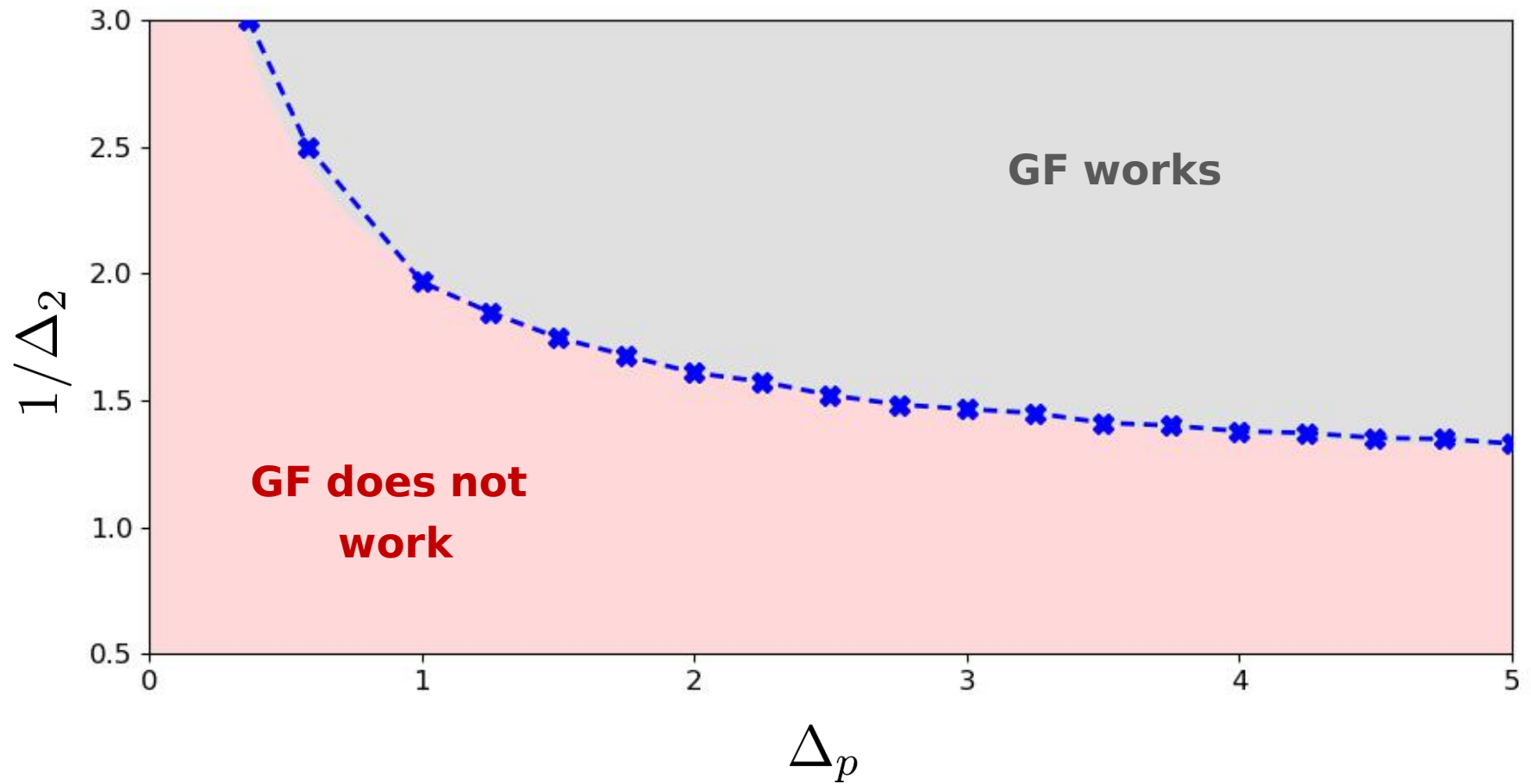
$$\frac{\partial}{\partial t} R(t, t') = \delta(t - t') - \mu(t)R(t, t') + \int_{t'}^t dt'' R(t, t'')Q''(C(t, t''))R(t'', t'),$$

$$\frac{\partial}{\partial t} m(t) = -\mu(t)m(t) + Q'(m(t)) + \int_0^t dt'' R(t, t'')m(t'')Q(C(t, t'')),$$

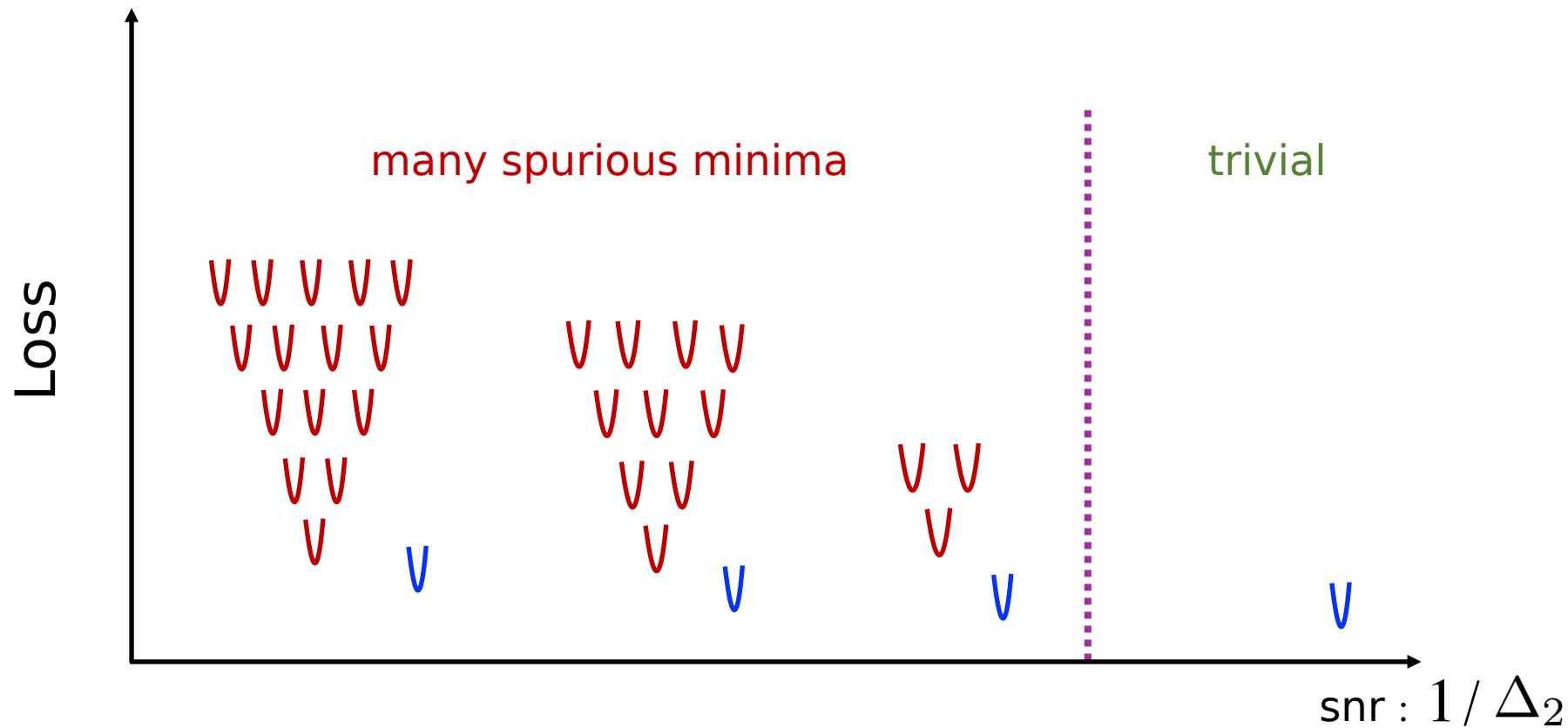
with $Q(x) = x^2/(2\Delta_2) + x^p/(p\Delta_p)$.

$$C(t, t') = \frac{1}{N} \sum_{i=1}^N \langle x_i(t)x_i(t') \rangle, \quad R(t, t') = \frac{1}{N} \sum_{i=1}^N \left\langle \frac{\delta x_i(t)}{\delta \eta_i(t')} \right\rangle, \quad m(t) = \frac{1}{N} \sum_{i=1}^N \langle x_i(t)x_i^* \rangle.$$

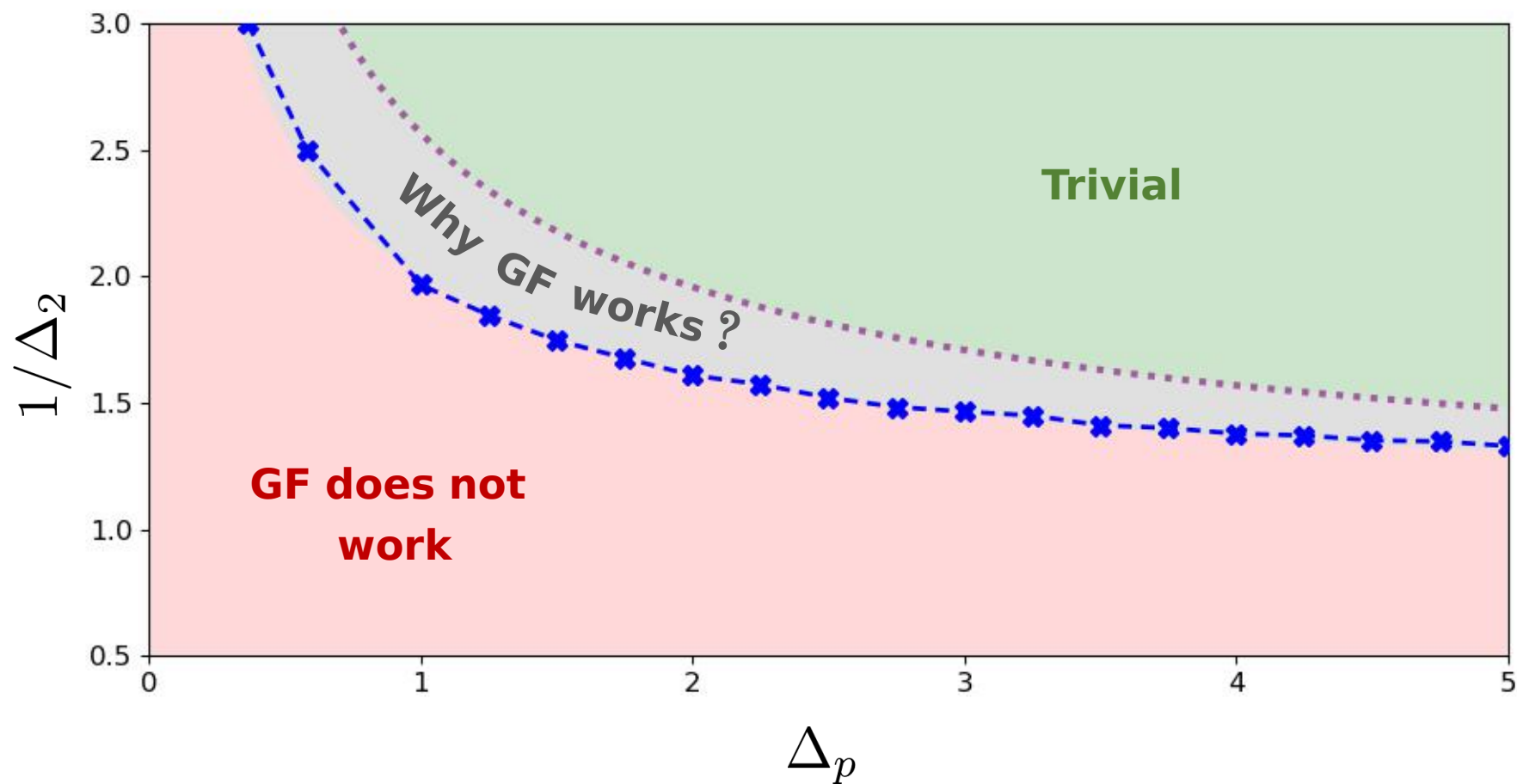
Phase Diagram



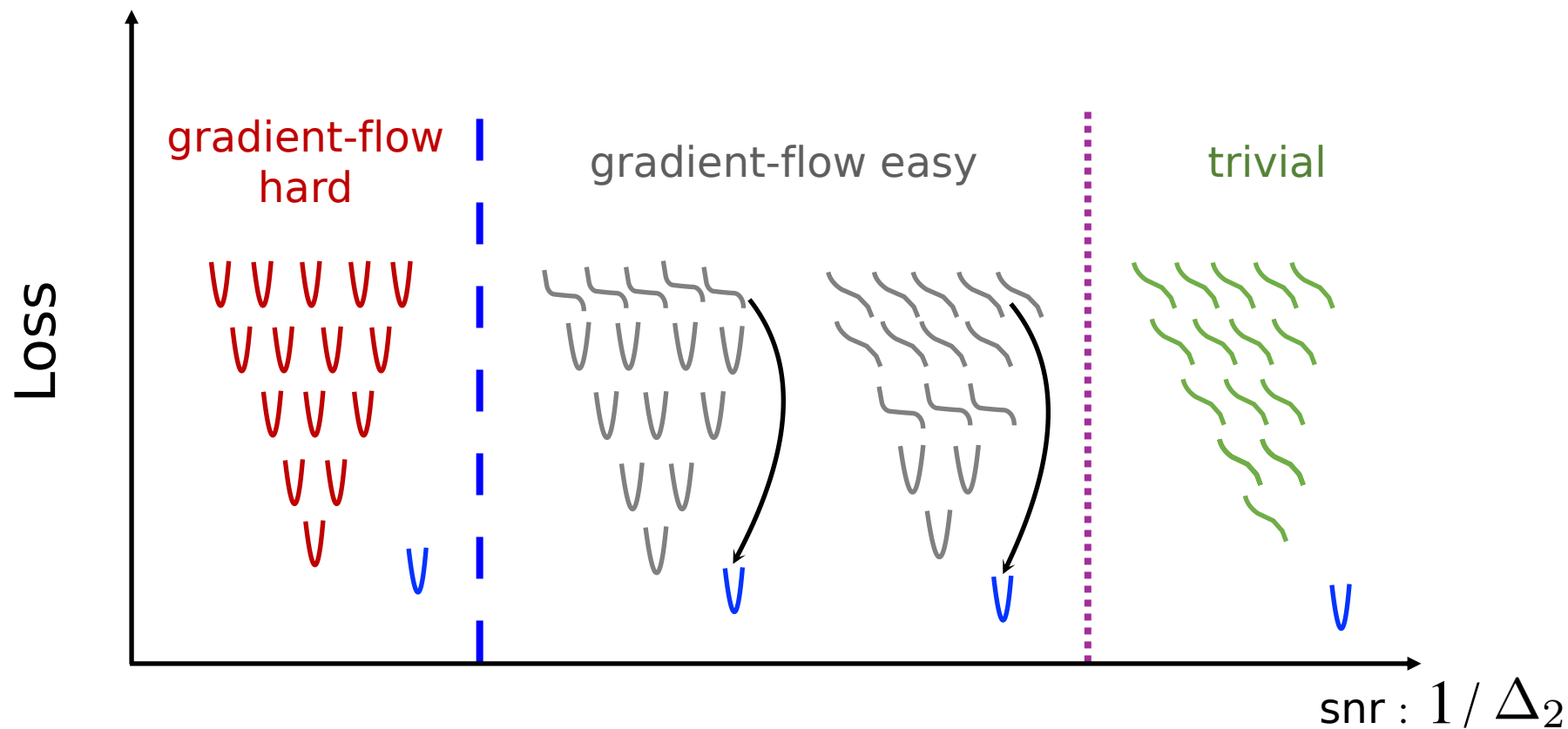
Phase Diagram



Phase Diagram



Phase Diagram



*joint work with Giulio Biroli and Chiara Cammarota

PASSED & SPURIOUS



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Thank you!
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