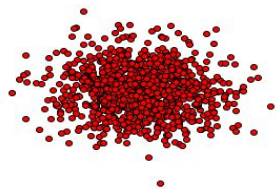


Stochastic Deep Networks

Gwendoline De Bie, Gabriel Peyré, Marco Cuturi

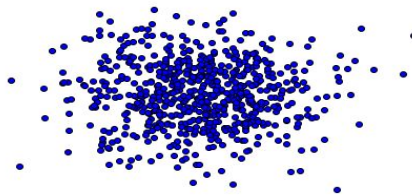


Deep Architectures on Density Inputs

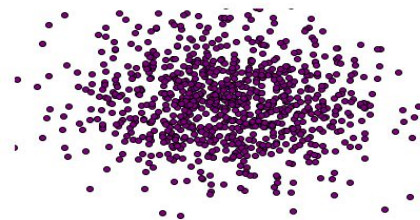


$t=1$, 1000 cells

of varying physical attributes

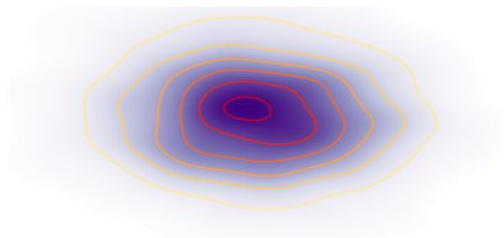
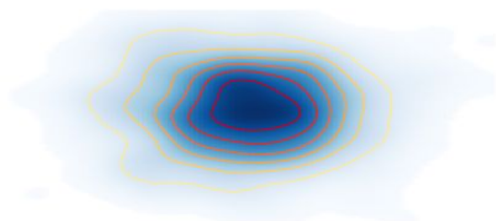
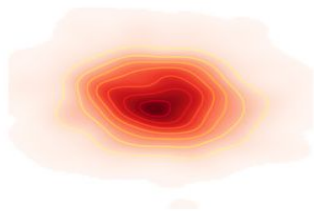


$t=2$, 650 cells



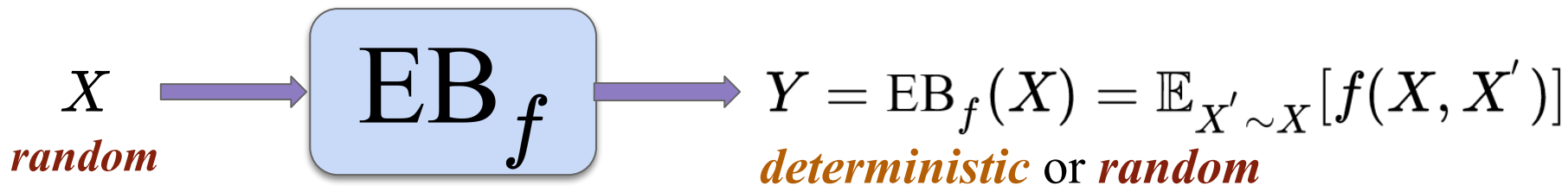
$t=3$, 890 cells

- Representing inputs as **densities** (discretized in practice)



- How to define a **‘layer’** of a Deep Net taking such inputs ?

Proposed Layer: Elementary Block (EB)



Discrete case: $X \sim \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$

$\rightarrow Y \sim \frac{1}{n} \sum_{i=1}^n \delta_{y_i}$, where: $y_i = \sum_{j=1}^n f(x_i, x_j)$

Fully connected case: $f(x, u) = (\phi(y_i))_i$

where $y = A \cdot [x, u]^T + b$, ϕ non-linearity

Deterministic output: $f(x, u) = g(u)$

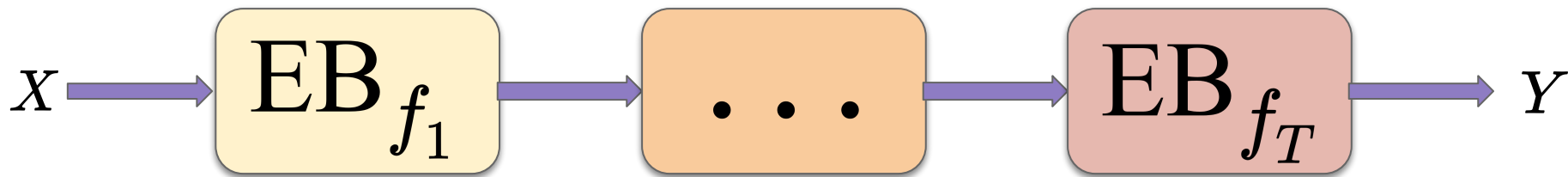
$\rightarrow Y = \mathbb{E}_{X'}[g(X')]$ **deterministic**

Classical warping: $f(x, u) = h(x)$

$\rightarrow Y = h(X)$ **random**

Proposed Architectures

$$Y = \text{EB}_{f_T} \circ \dots \circ \text{EB}_{f_1} (X)$$



Tasks		
Discriminative	Generative	Predictive
Y deterministic	Y random	Y random
X random	X noise + code	X random

Approximation Property

➤ *Theoretically, three blocks are enough*

Theorem (Universal Approximation). Let F a continuous map for the convergence in law, mapping measures supported on compact sets. Then *three EBs are necessary to approximate F arbitrarily close*: $\forall \epsilon > 0$, there exists three continuous maps f, g, h , such that, for all random vectors X ,

$$\text{Wasserstein}_1(F(X), EB_h \circ \Lambda \circ EB_g \circ EB_f(X)) \leq \epsilon$$

where $\Lambda : X \mapsto (X, U)$ concatenates a uniform random vector.

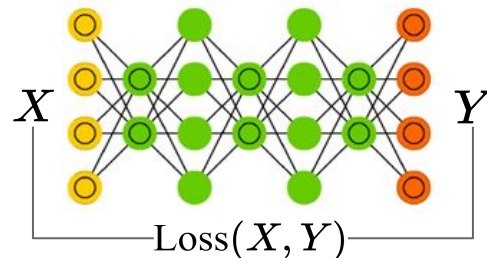
Applications

In practice: f fully connected

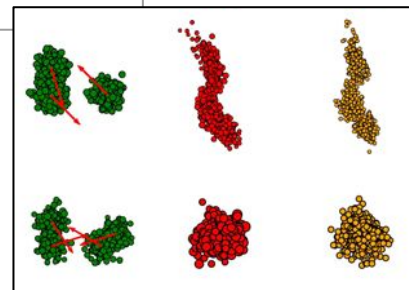
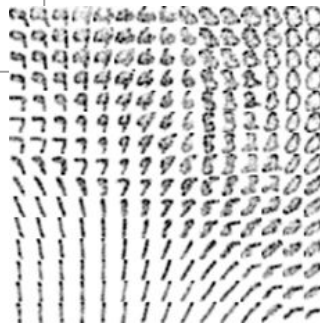
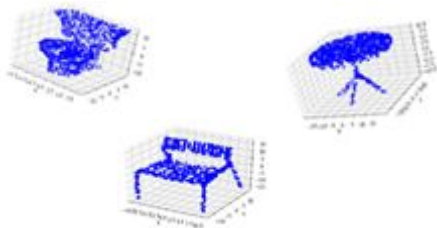
$$f(x, u) = (\phi(y_i))_i$$

Loss functions:

- *Cross-entropy* (classification)
- *Regularized Wasserstein* (Cuturi, 2013)
- *Sinkhorn divergence* (Genevay et al, 2018)



Classification		Generation	Dynamics
MNIST as <i>point clouds</i>	Modelnet40 as <i>point clouds</i>	MNIST as <i>point clouds</i>	Flocking model
99,2% accuracy, 2 EBs	83,5% accuracy, 2 EBs	2 EBs	5 EBs



Conclusion / Open Problems

- **New formalism for stochastic deep architectures**
 - Probability distributions
 - Deterministic feature vectors
- **Robustness & approximation power**
- **Perspectives**
 - Understanding block roles
 - Investigate translation & rotation equivariance

Poster: #30 Pacific Ballroom today - see you there !