
A Conditional-Gradient-Based Augmented Lagrangian Framework

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joint work with

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Conditional Gradient Method (CGM)

(Frank & Wolfe, 1956)
(Hazan, 2008)
(Jaggi, 2013)

$$\min_{x \in \mathcal{X}} f(x)$$

- ▷ $\mathcal{X} \subset \mathbb{R}^n$ is a convex compact set
- ▷ $f : \mathcal{X} \rightarrow \mathbb{R}$ is a smooth convex function

Input: $x_1 \in \mathcal{X}$

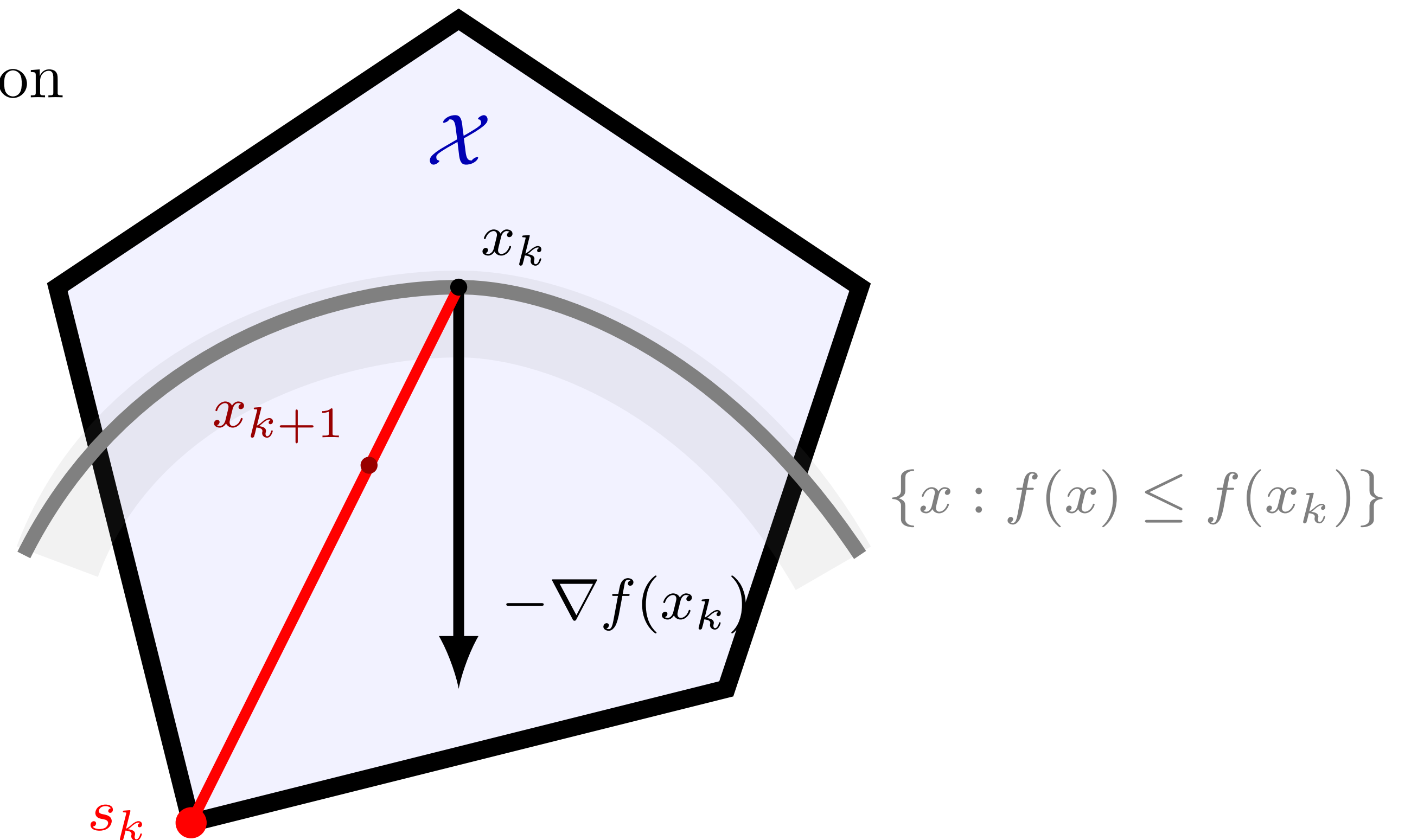
for $k = 1, 2, \dots$, **do**

$$\eta_k = 2/(k + 1)$$

$$s_k = \arg \min_{x \in \mathcal{X}} \langle \nabla f(x_k), x \rangle$$

$$x_{k+1} = x_k + \eta_k (s_k - x_k)$$

end for



Motivation: Solving Large-Scale SDP

(Hazan, 2008)
(Yurtsever et al., 2017)

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When \mathcal{X} is PSD-cone with bounded trace

- *lmo* is cheap (Arithmetic Scalability)
- updates are rank-1 (Storage Scalability)

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$$\min_{x \in \mathcal{X}} f(x) \quad \text{s.t.} \quad Ax \in \mathcal{K}$$

- ▷ $A : \mathcal{X} \rightarrow \mathbb{R}^d$ is a given linear map
- ▷ \mathcal{K} is a simple convex set

This paper:
A new **CGM-type** method
based on **augmented Lagrangian**

CGM via Quadratic Penalty: HCGM

(Yurtsever et al., 2018)

$$\min_{x \in \mathcal{X}} f(x) + \frac{\lambda}{2} \text{dist}^2(Ax, \mathcal{K}) \quad (\text{QP formulation})$$

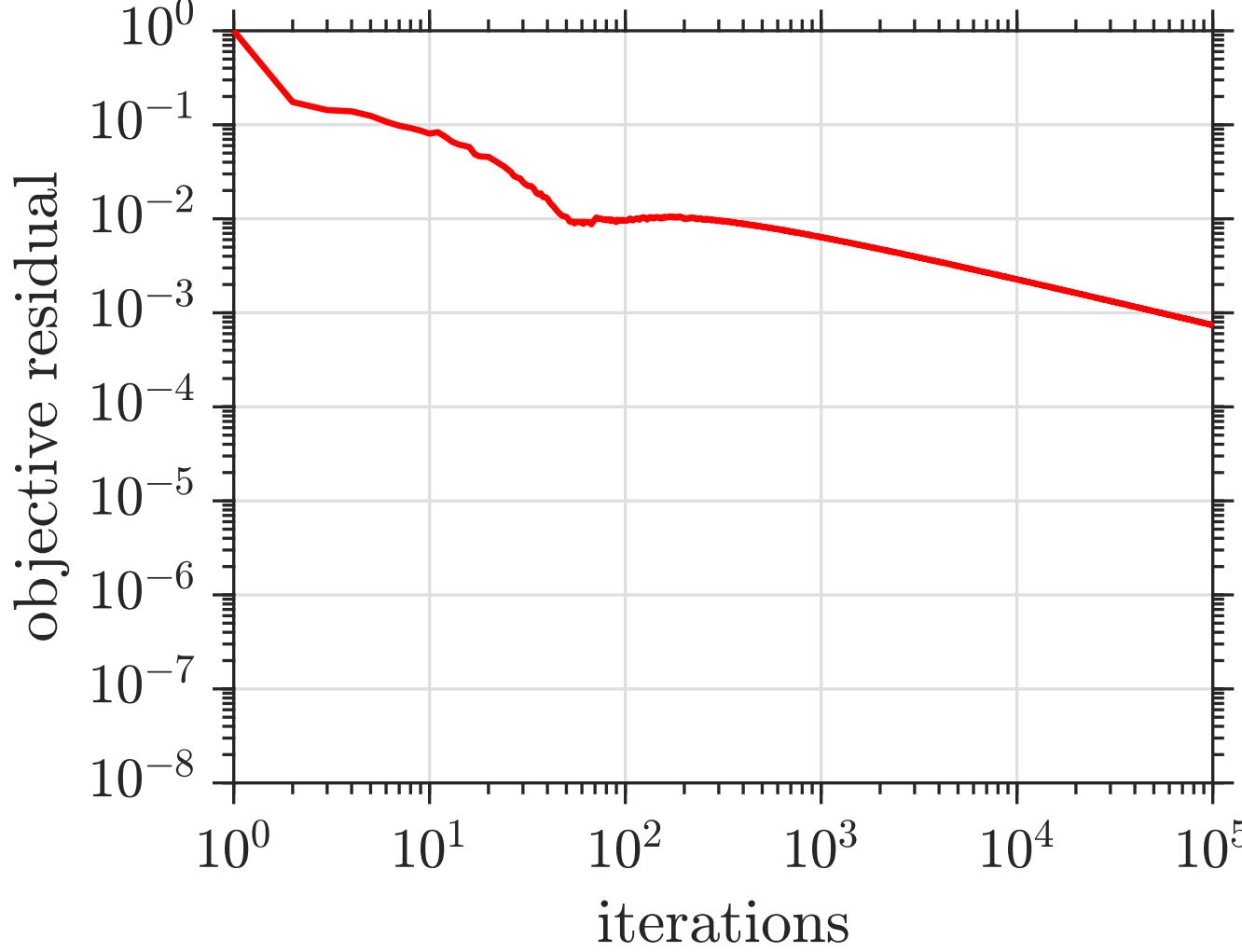
$$(\text{QP formulation}) \xrightarrow{\lambda \rightarrow +\infty} (\text{Original problem})$$

Start with some λ
apply CGM step w.r.t. QP form.
increase λ at each iteration

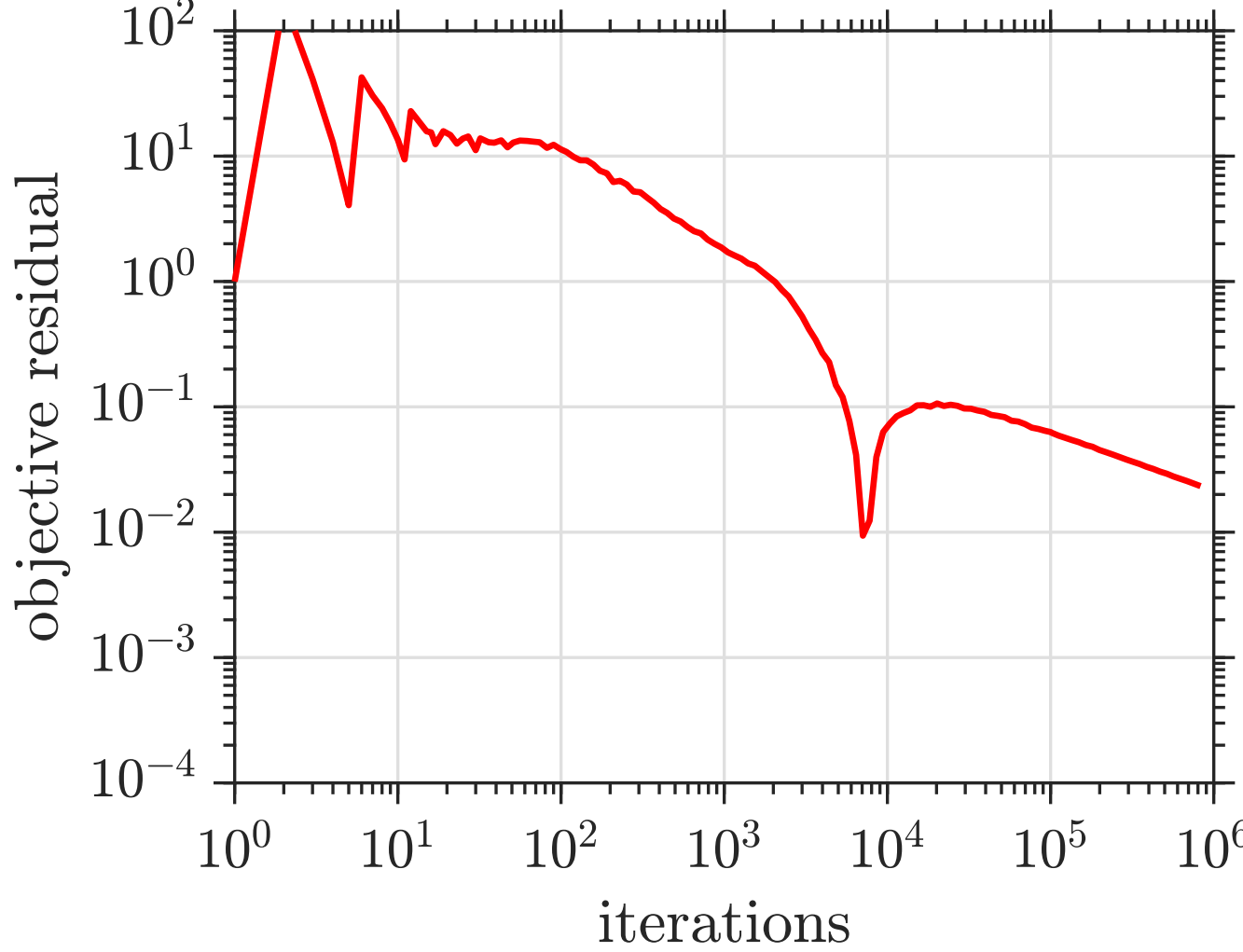
$$|f(x) - f^*| = \mathcal{O}(1/\sqrt{k}) \quad \& \quad \text{dist}(Ax, \mathcal{K}) = \mathcal{O}(1/\sqrt{k})$$

Performance of HCGM

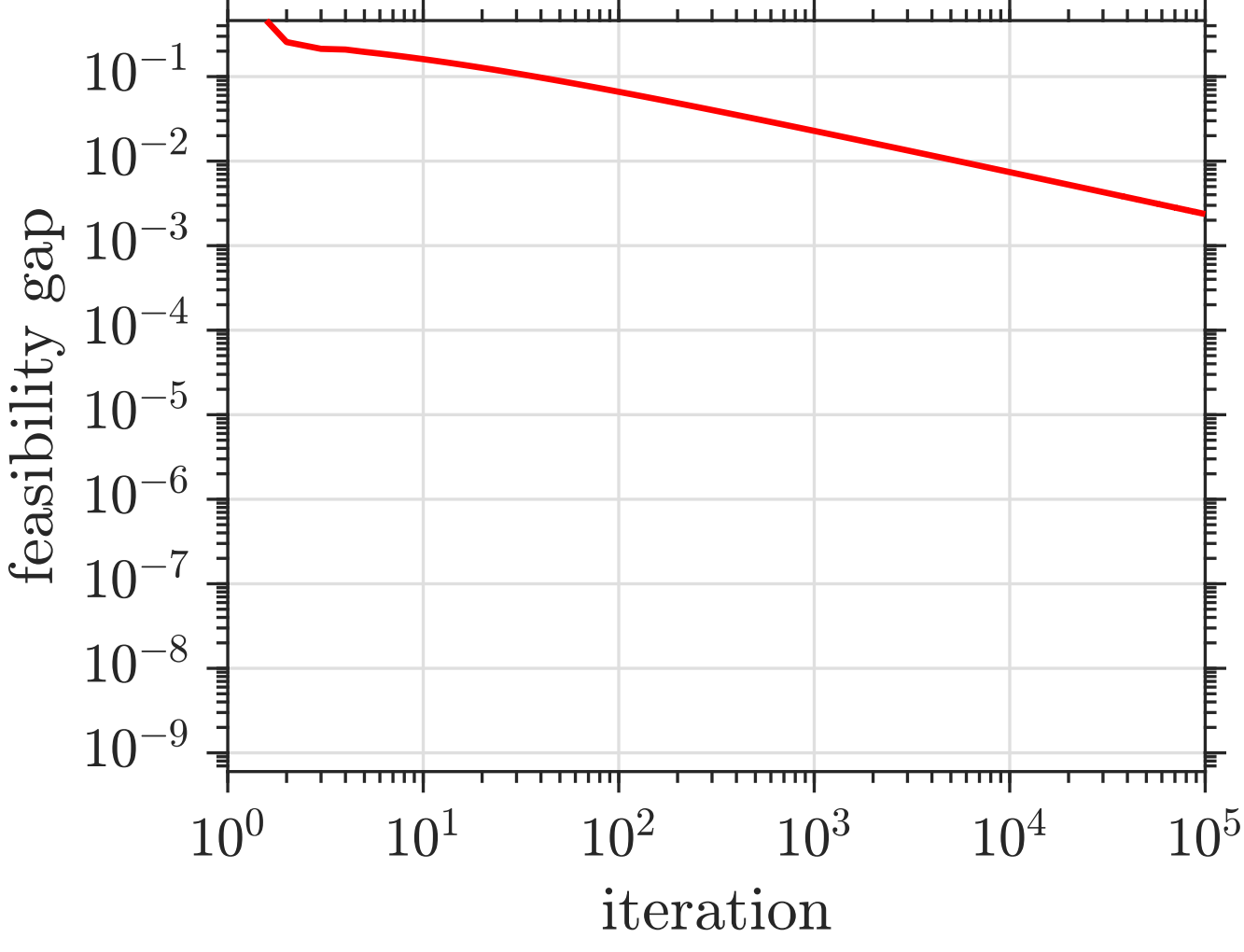
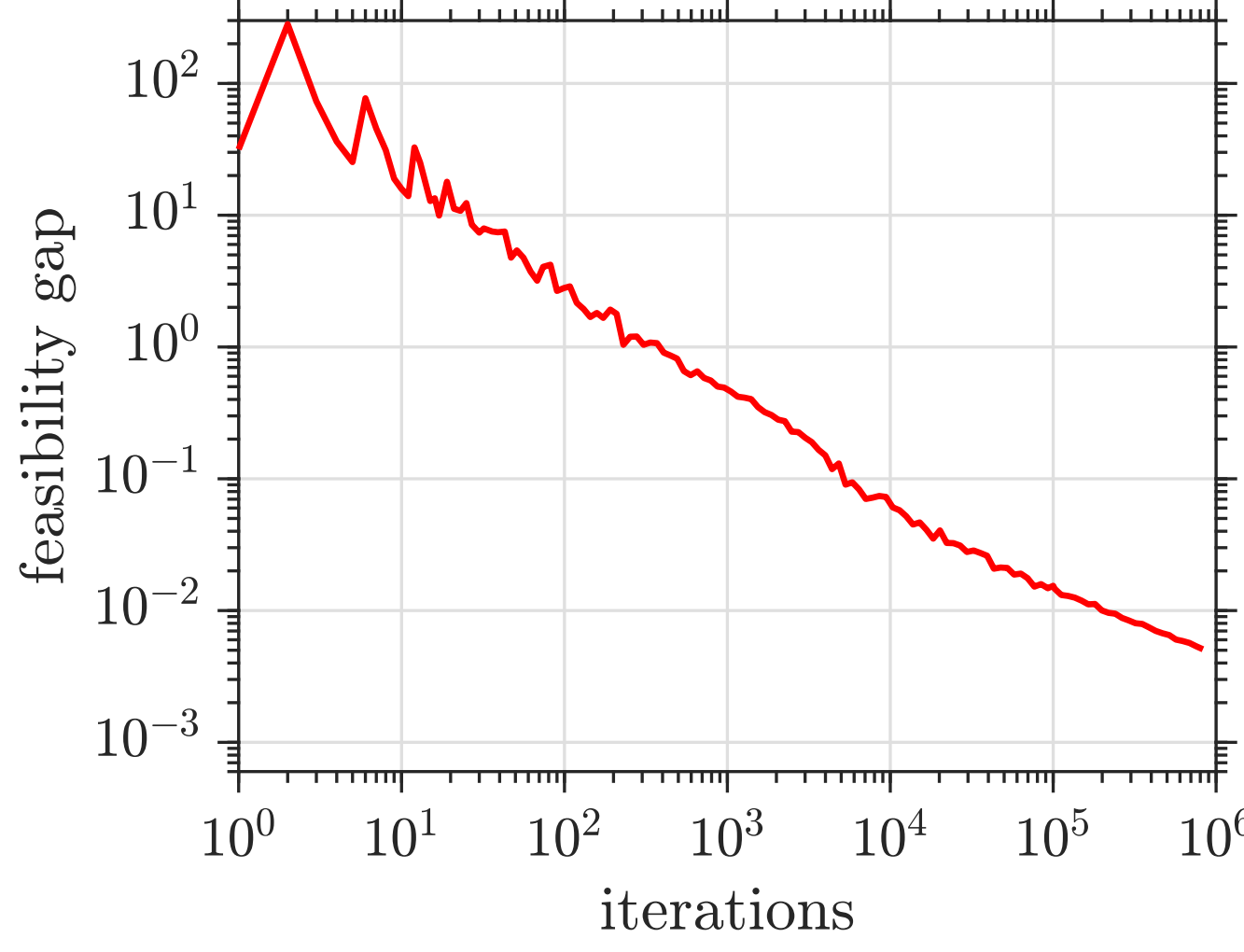
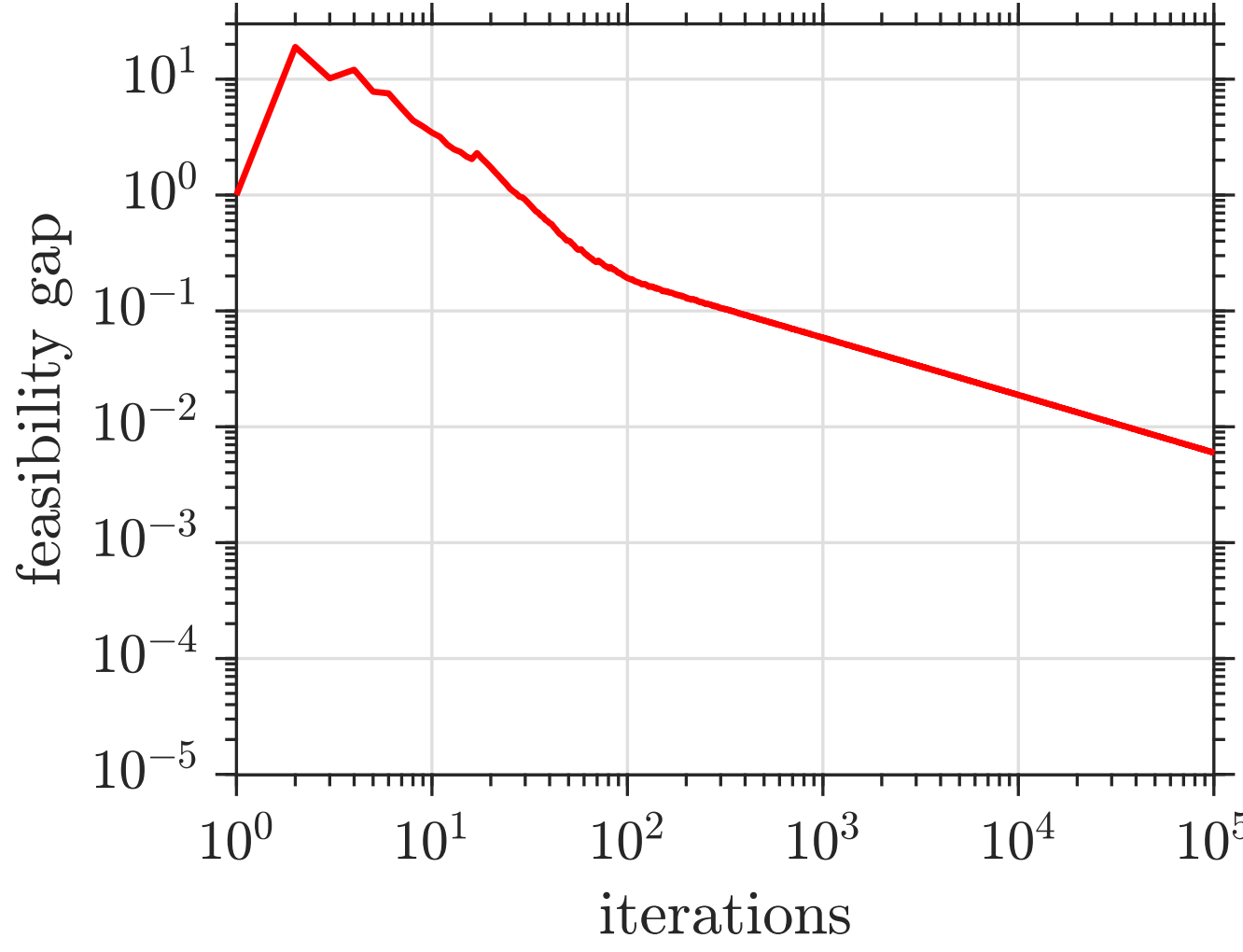
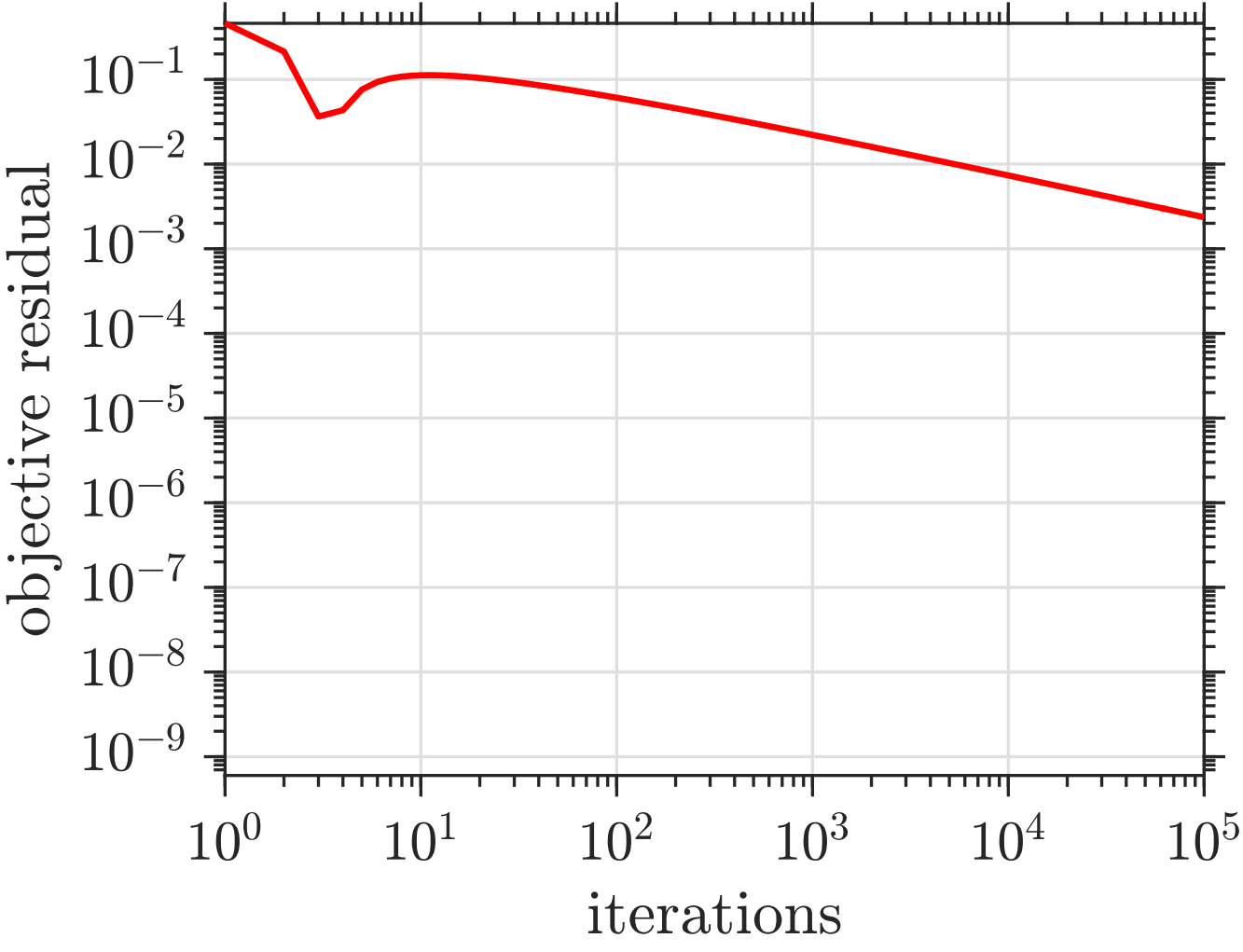
MaxCut



Clustering



Generalized Eig. Vec.



CGM via augmented Lagrangian: CGAL

$$\max_{y \in \mathbb{R}^d} \min_{x \in \mathcal{X}} \mathcal{L}_\lambda(x, y) \quad (\text{AL formulation})$$

$$\text{where } \mathcal{L}_\lambda(x, y) := f(x) + \min_{r \in \mathcal{K}} \left\{ \langle y, Ax - r \rangle + \frac{\lambda}{2} \|Ax - r\|^2 \right\}$$

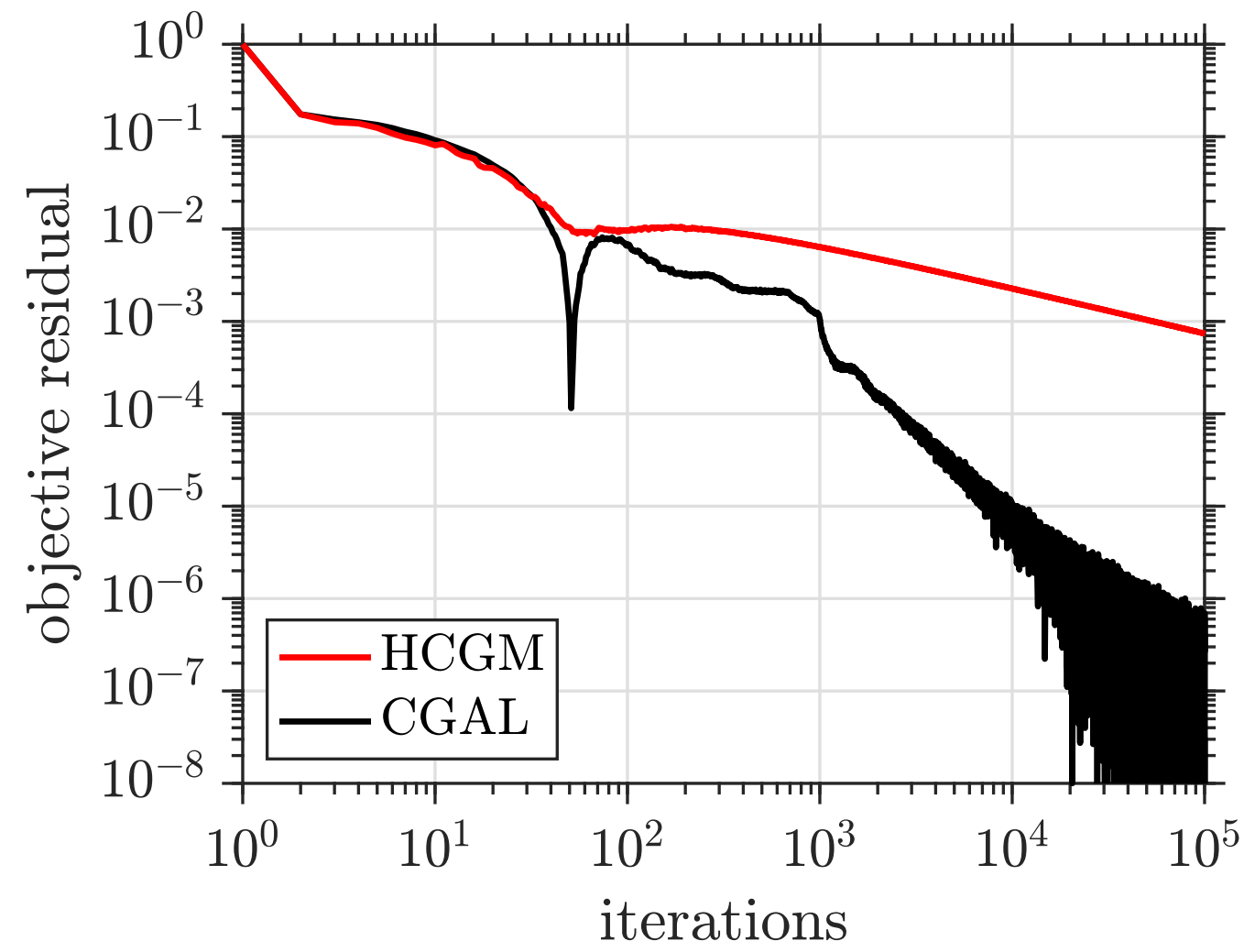
Start with some λ
apply CGM step on x
apply dual ascent step on y
increase λ at each iteration

$$|f(x) - f^*| = \mathcal{O}(1/\sqrt{k}) \quad \& \quad \text{dist}(Ax, \mathcal{K}) = \mathcal{O}(1/\sqrt{k})$$

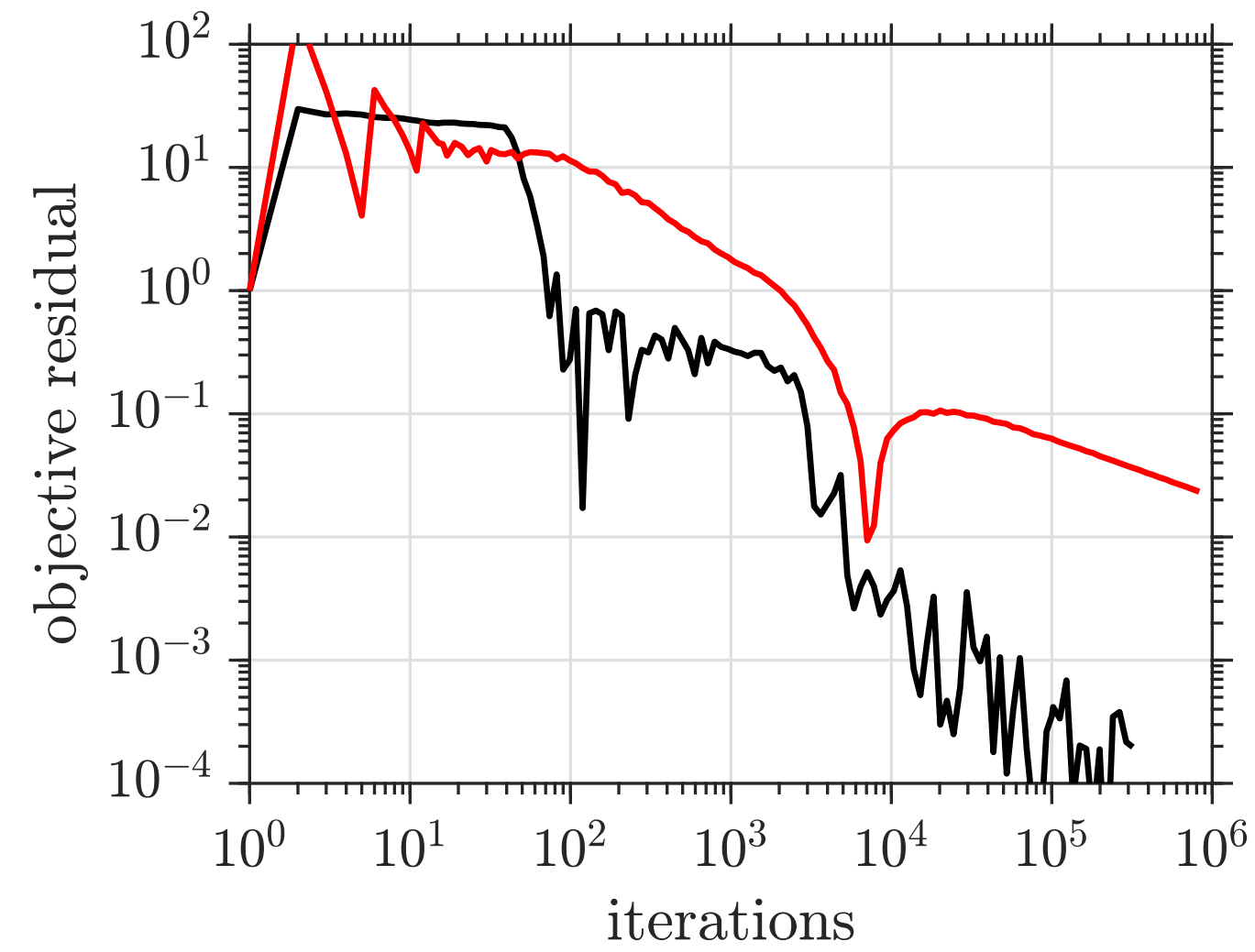
CGAL vs HCGM

Poster today: **Pacific Ballroom #194**

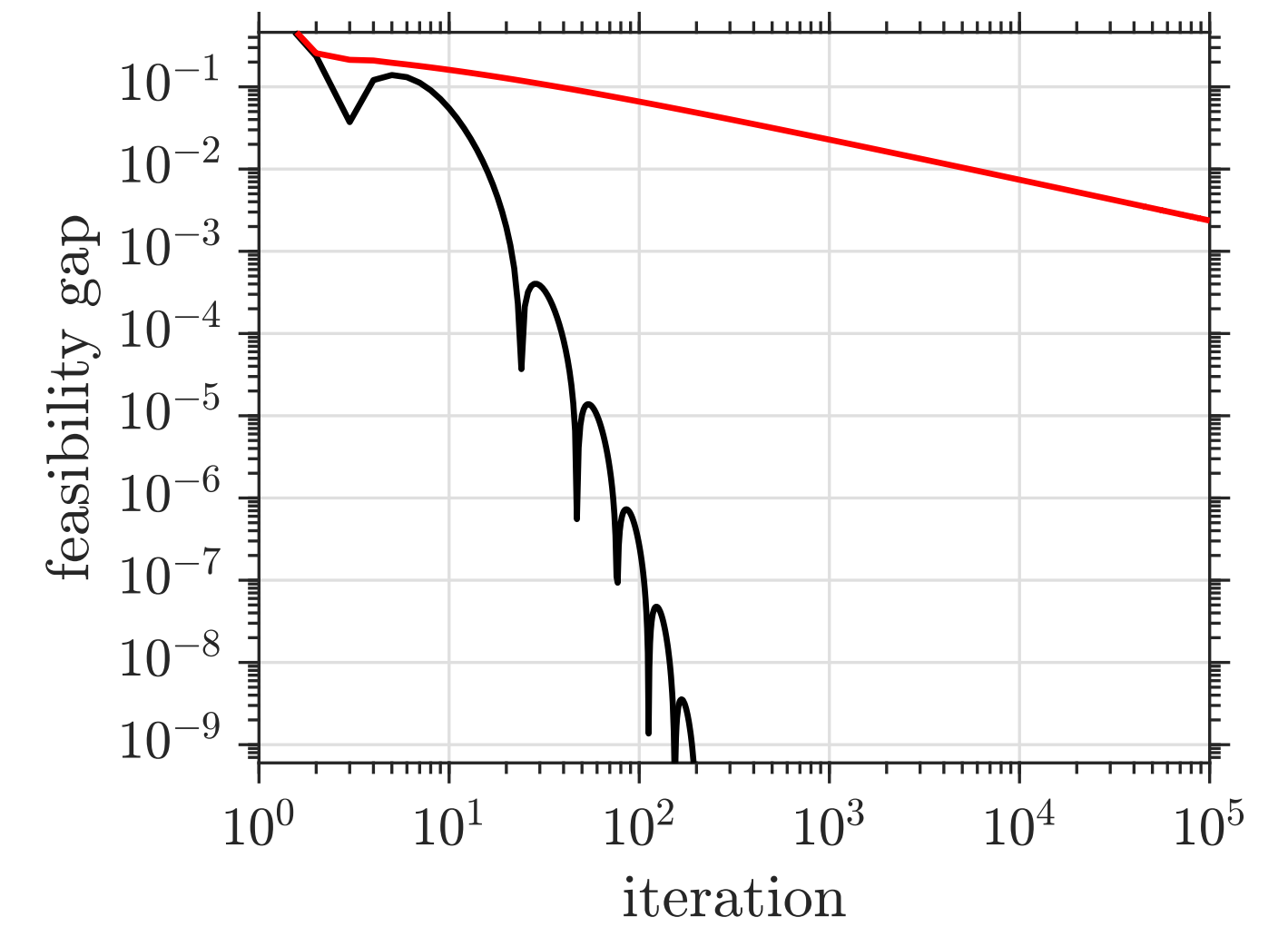
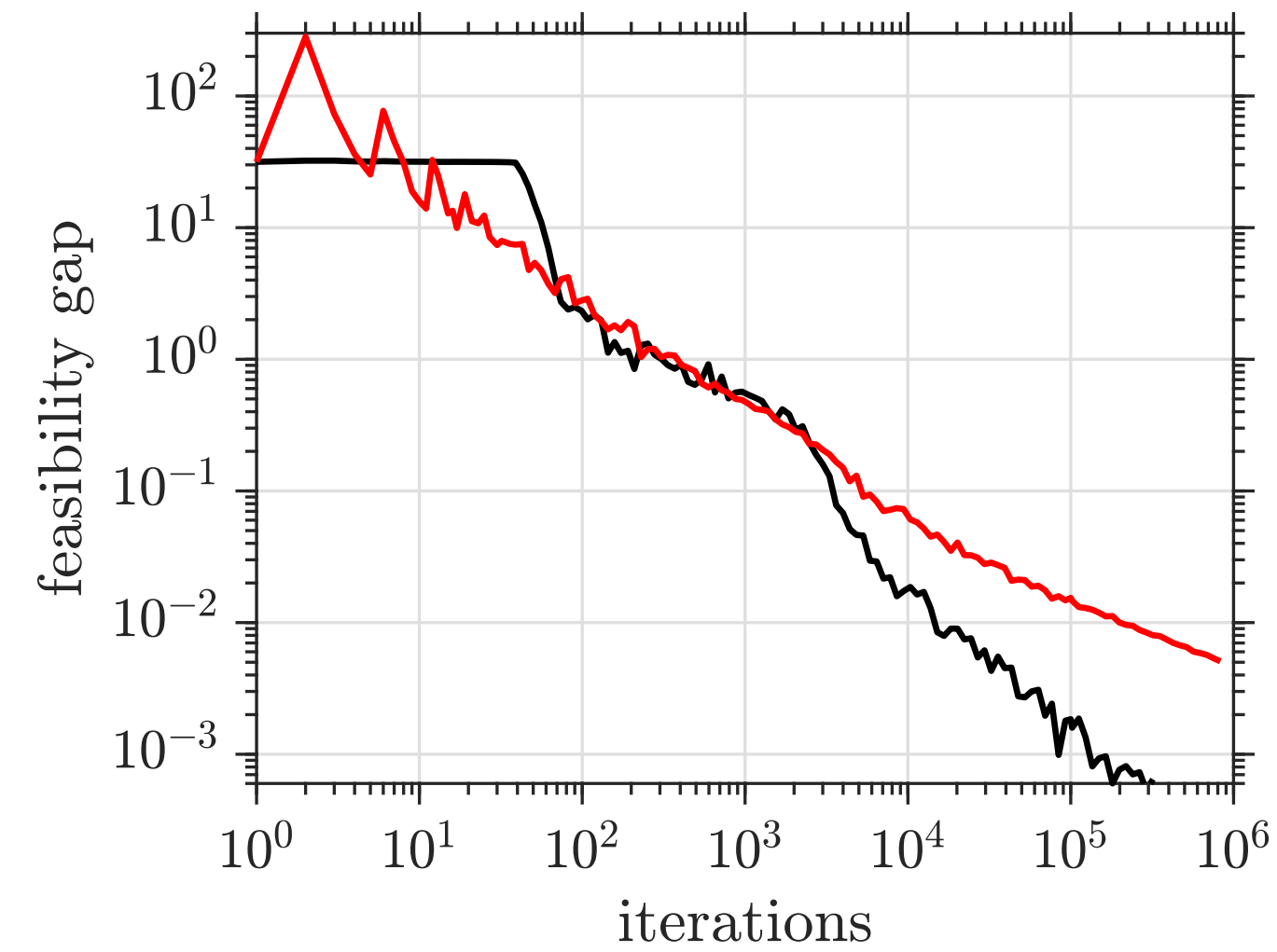
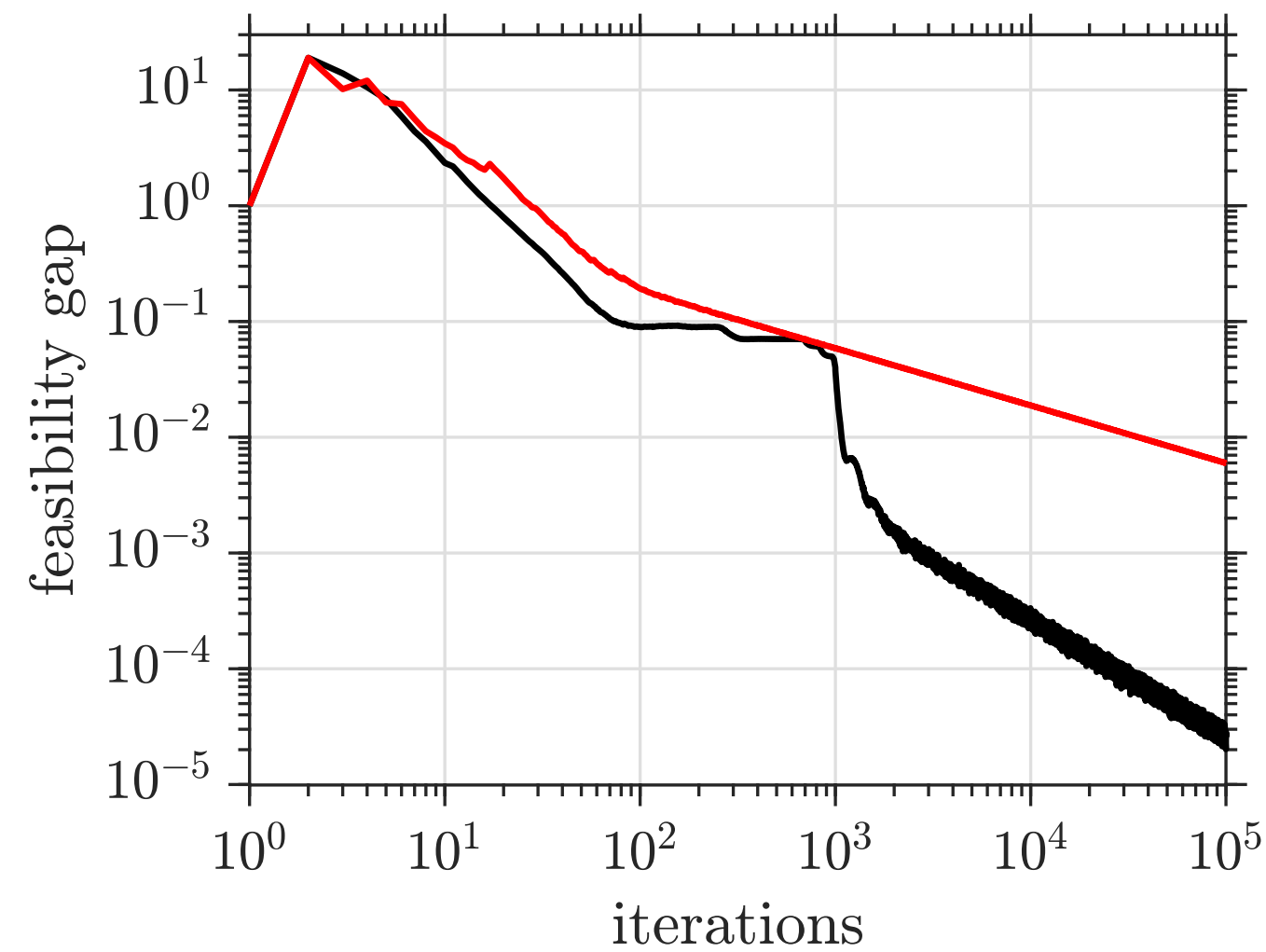
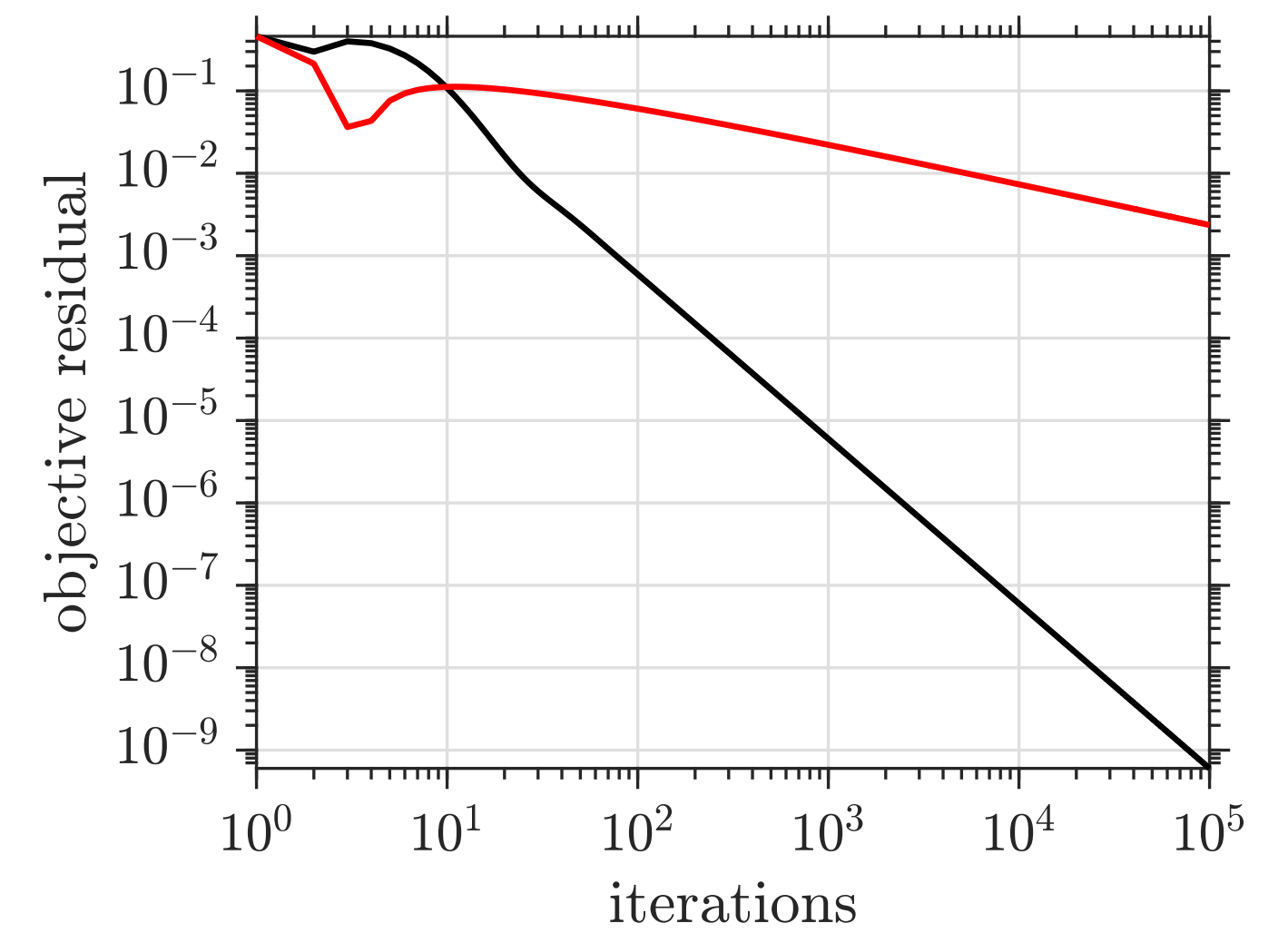
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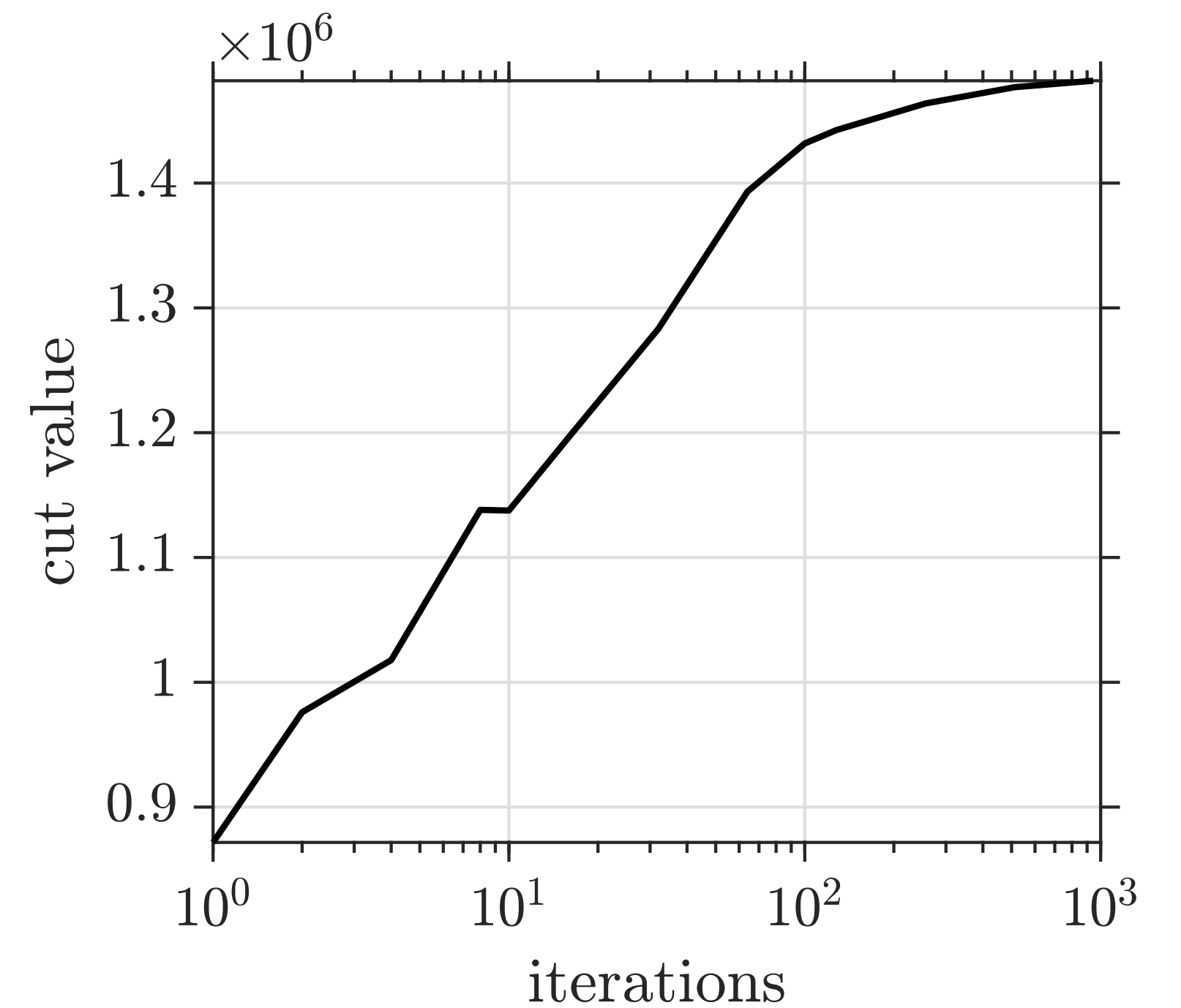
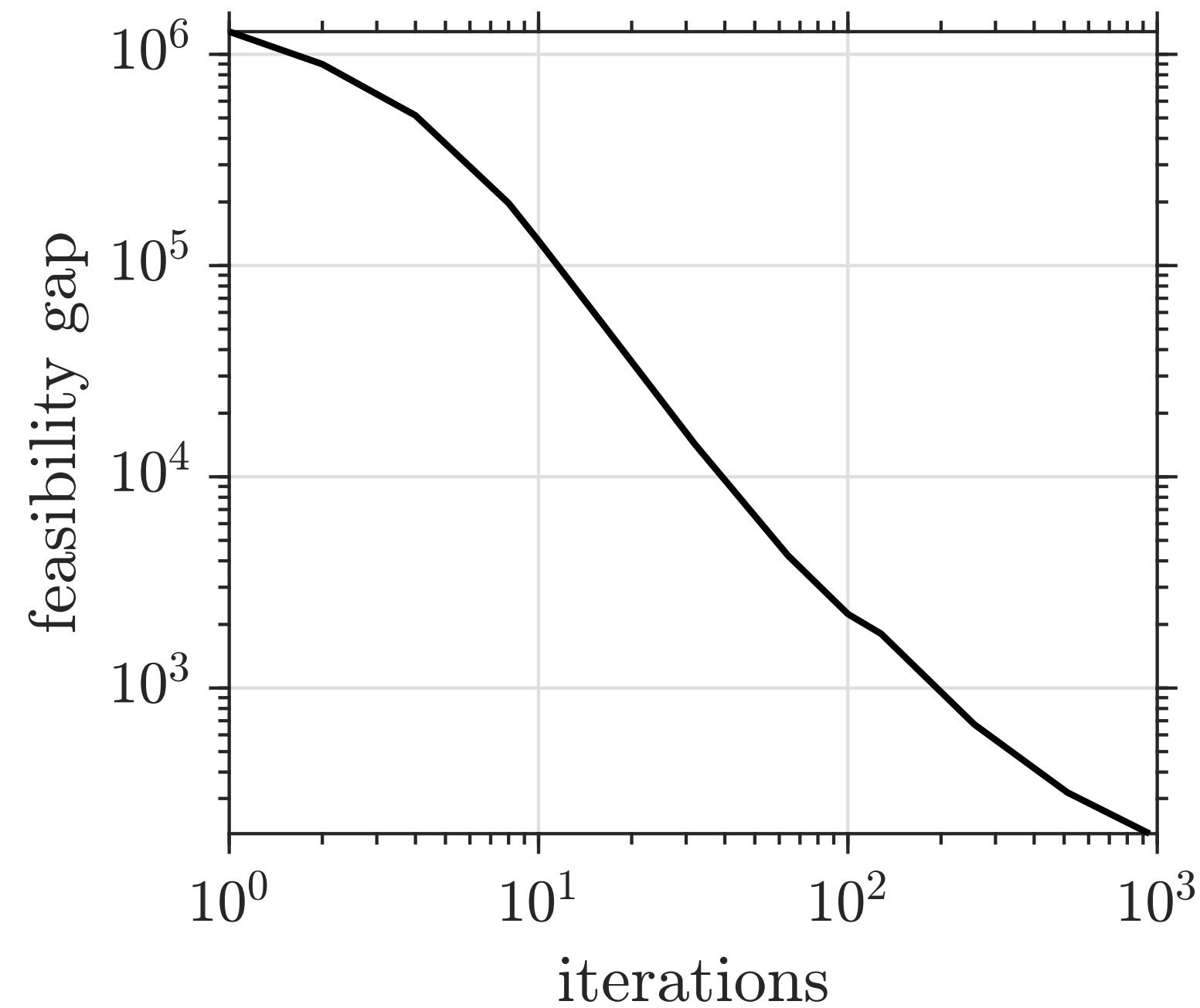
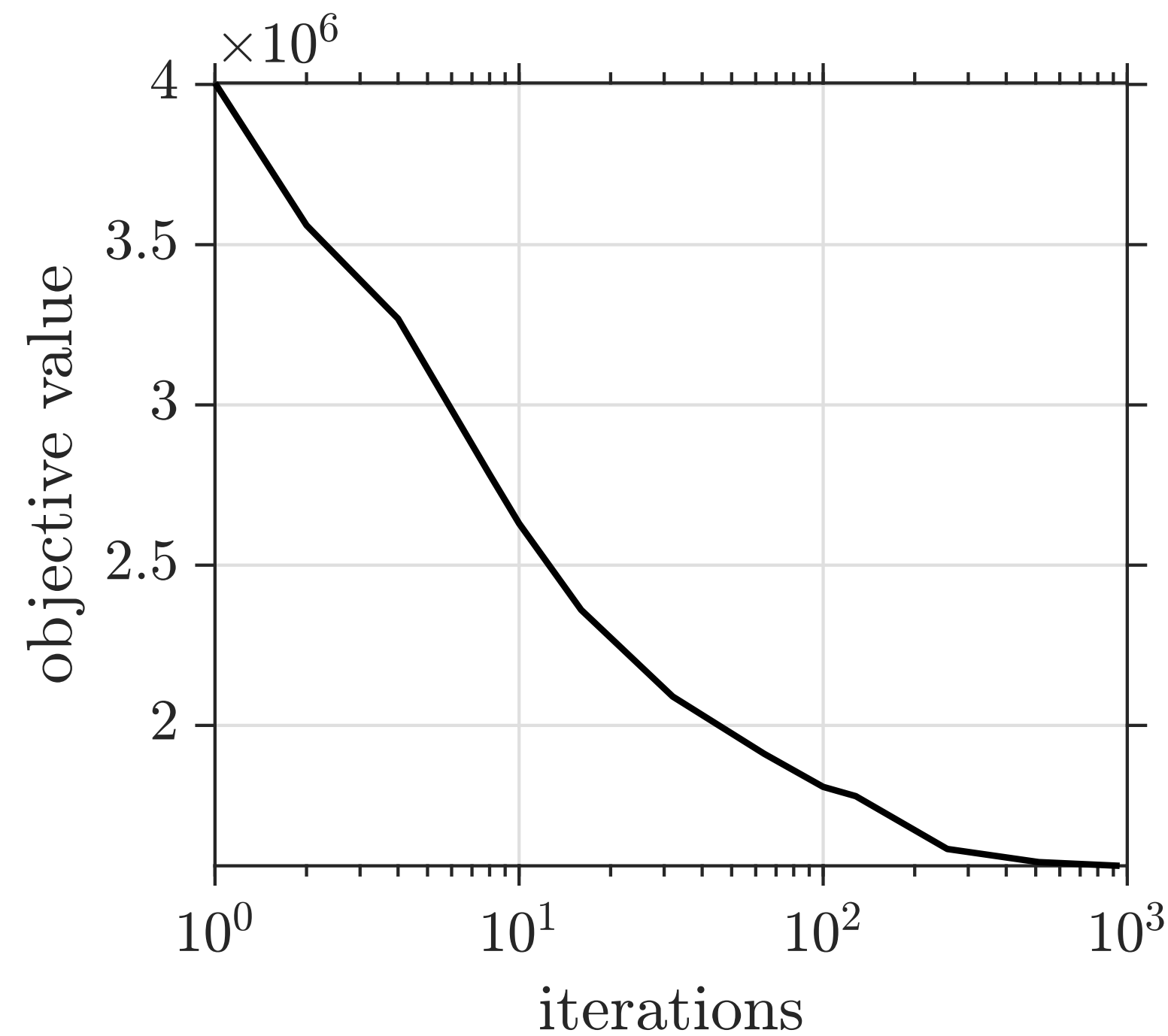
Generalized Eig. Vec.



Coming soon: Sketchy-CGAL

(Cevher-Tropp-Yurtsever, 2019)

$$\underset{x}{\text{minimize}} \quad -\frac{1}{4}\langle L, X \rangle \quad \text{subject to} \quad \text{diag}(X) = 1, \quad \text{trace}(X) = n, \quad X \text{ is PSD}$$



MaxCut with **(1`441`295 x 1`441`295)** dimensional **belgium-osm** Street Network
from DIMACS10 Implementation Challenge Library