

Phaseless PCA: Low-Rank Matrix Recovery from Column-wise Phaseless Measurements

Syedehsara Nayer, Praneeth Narayanamurthy, Namrata Vaswani

Iowa State University

Phase Retrieval (PR)

- Recover a length n signal \mathbf{x}^* from its phaseless linear projections

$$\mathbf{y}_i := |\langle \mathbf{a}_i, \mathbf{x}^* \rangle|, \quad i = 1, 2, \dots, m$$

- Without any structural assumptions, PR necessarily needs $m \geq n$.

To reduce sample complexity, can try to exploit structure

- Most existing work studies sparse PR – assumes \mathbf{x}^* is sparse.

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- Most existing work studies sparse PR – assumes \mathbf{x}^* is sparse.
- Another simple structure is low-rank. Two ways to use this:
 - 1 assume \mathbf{x}^* can be rearranged as a low-rank matrix (not studied); or
 - 2 assume a set of signals (or vectorized images) \mathbf{x}_k^* , $k = 1, 2, \dots, q$, together form a low-rank matrix

The second is a more practical and commonly used model and we use this:

- ▶ first studied in our earlier work [Vaswani, Nayer, Eldar, Low-Rank Phase Retrieval, T-SP'17]

Recover an $n \times q$ matrix of rank r

$$\mathbf{X}^* = [\mathbf{x}_1^*, \mathbf{x}_2^*, \dots, \mathbf{x}_k^*, \dots, \mathbf{x}_q^*]$$

from a set of m phaseless linear projections of *each* of its q columns

$$\mathbf{y}_{ik} := |\langle \mathbf{a}_{ik}, \mathbf{x}_k^* \rangle|, \quad i = 1, \dots, m, \quad k = 1, \dots, q.$$

Application: fast phaseless dynamic imaging, e.g., Fourier ptychographic imaging of live biological specimens

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- Even the linear version of this problem is different from both
 - ▶ LR matrix sensing: recover \mathbf{X}^* from $\mathbf{y}_i = \langle \mathbf{A}_i, \mathbf{X}^* \rangle$ with \mathbf{A}_i 's dense
 - ★ global measurements (y_i depends on entire \mathbf{X}^*)
 - ▶ LR matrix completion: recover \mathbf{X}^* from a subset of its entries
 - ★ completely local measurements
 - ★ need rows & cols to be “dense” to allow for correct “interpolation”
- Our problem - non-global measurements of \mathbf{X}^* , but global for each column
 - ▶ only need denseness of rows (incoherence of right singular vectors)

Recover an $n \times q$ rank- r matrix \mathbf{X}^* from $\mathbf{y}_{ik} = |\langle \mathbf{a}_{ik}, \mathbf{x}_k^* \rangle|$, $i \in [1, m]$, $k \in [1, q]$.

AltMinLowRaP algo: careful spectral init followed by alternating minimization.

Theorem (Guarantee for AltMinLowRaP)

Assume μ -incoherence of right singular vectors of \mathbf{X}^ . Set $T := C \log(1/\epsilon)$. Assume that, for each new update step, we use a new (independent) set of mq measurements with m satisfying*

$$mq \geq C \kappa^6 \mu^2 nr^4$$

and $m \geq C \max(r, \log q, \log n)$. Then, w.p. at least $1 - 10n^{-10}$,

$$\text{dist}(\hat{\mathbf{x}}_k^T, \mathbf{x}_k^*) \leq \epsilon \|\mathbf{x}_k^*\|, \quad k = 1, 2, \dots, q$$

Also, the error decays geometrically with t .

Sample complexity: $C \cdot nr^4 \log(1/\epsilon)$ (treating κ, μ as constants).

Time complexity: $C \cdot mqn r \log^2(1/\epsilon)$.

Recover a rank- r $n \times q$ matrix \mathbf{X}^* from $\mathbf{y}_{ik} = |\langle \mathbf{a}_{ik}, \mathbf{x}_k^* \rangle|$, $i \in [1, m]$, $k \in [1, q]$.

- Treating κ, μ as constants, our sample complexity is

$$m_{\text{tot}}q \geq C nr^4 \log(1/\epsilon)$$

Number of unknowns in \mathbf{X}^* is $(q + n)r \approx 2nr$

- ▶ sample complexity is r^3 times the optimal value (nr)
- No existing guarantees for our problem or even its linear version:
 - ▶ closest LR recovery problem with non-global measurements is LR Matrix Completion (LRMC)

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- No existing guarantees for our problem or even its linear version:
 - ▶ closest LR recovery problem with non-global measurements is LR Matrix Completion (LRMC)
- Sample complexity of non-convex LRMC solutions is also sub-optimal
 - ▶ AltMinComplete needs $C nr^{4.5} \log(1/\epsilon)$ samples
 - ▶ Best LRMC solution (proj-GD) needs $C nr^2 \log^2 n$ samples
- Comparison with standard (unstructured) PR
 - ▶ Standard PR sample complexity is nq : much larger when $r^4 \ll q$

Key idea of the algorithm: Alt-Min for Phaseless Low Rank Recovery [Nayer,

Narayanamurthy, Vaswani, Phaseless PCA, ICML 2019 (this work)]

- Alternating minimization relies on the following key idea:
 - 1 Let $\mathbf{X}^* = \mathbf{U}^* \mathbf{B}^*$.
Thus $\mathbf{x}_k^* = \mathbf{U}^* \mathbf{b}_k^*$ and so $y_{ik} := |\langle \mathbf{a}_{ik}, \mathbf{x}_k^* \rangle| = |\langle \mathbf{U}^{*T} \mathbf{a}_{ik}, \mathbf{b}_k^* \rangle|$
 - 2 If \mathbf{U}^* is known, recovering \mathbf{b}_k^* is an (easy) r -dimensional standard PR problem
 - ★ needs only $m \geq r$ measurements.
 - 3 Given an estimate of \mathbf{U}^* and of \mathbf{b}_k^* , we can get an estimate of phase of $\langle \mathbf{a}_{ik}, \mathbf{x}_k^* \rangle$. Updating \mathbf{U}^* is then a Least Squares problem
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 - ★ can show that for this step m of order nr^4 suffices.
- Spectral init: compute $\hat{\mathbf{U}}^{init}$ as top r eigenvectors of

$$\mathbf{Y}_U = \frac{1}{mq} \sum_{k=1}^q \sum_{i=1}^m \mathbf{y}_{ik}^2 \mathbf{a}_{ik} \mathbf{a}_{ik}' \mathbf{1} \left\{ \mathbf{y}_{ik}^2 \leq \frac{9}{mq} \sum_{ik} \mathbf{y}_{ik}^2 \right\}$$

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- 1: $\hat{r} \leftarrow$ largest index j for which $\lambda_j(\mathbf{Y}_U) - \lambda_n(\mathbf{Y}_U) \geq \omega$
 - 2: $\mathbf{U} \leftarrow$ top \hat{r} singular vectors of $\mathbf{Y}_U := \frac{1}{mq} \sum_{i,k: \mathbf{y}_{ik}^2 \leq \frac{\omega}{mq}} \sum_{ik} \mathbf{y}_{ik}^2 \mathbf{a}_{ik} \mathbf{a}_{ik}'$
 - 3: **for** $t = 0 : T$ **do**
 - 4: $\hat{\mathbf{b}}_k \leftarrow$ RWF($\{\mathbf{y}_k, \mathbf{U}' \mathbf{a}_{ik}\}, i = 1, 2, \dots, m$) for each $k = 1, 2, \dots, q$
 - 5: $\hat{\mathbf{X}}^t \leftarrow \mathbf{U} \hat{\mathbf{B}}$ where $\hat{\mathbf{B}} = [\hat{\mathbf{b}}_1, \hat{\mathbf{b}}_2, \dots, \hat{\mathbf{b}}_q]$
 - 6: QR decomposition: $\hat{\mathbf{B}} \stackrel{\text{QR}}{=} \mathbf{R}_B \mathbf{B}$
 - 7: $\hat{\mathbf{c}}_{ik} \leftarrow \text{phase}(\langle \mathbf{a}_{ik}, \hat{\mathbf{x}}_{ik} \rangle), i = 1, 2, \dots, m, k = 1, 2, \dots, q$
 - 8: $\hat{\mathbf{U}} \leftarrow \arg \min_{\tilde{\mathbf{U}}} \sum_{k=1}^q \sum_{i=1}^m (\hat{\mathbf{c}}_{ik} \mathbf{y}_{ik} - \mathbf{a}_{ik}' \tilde{\mathbf{U}} \mathbf{b}_k)^2$
 - 9: QR decomp: $\hat{\mathbf{U}} \stackrel{\text{QR}}{=} \mathbf{U} \mathbf{R}_U$
 - 10: **end for**
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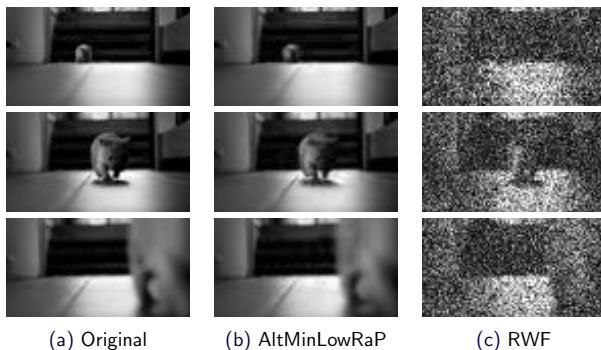


Figure 1: Recovering a real video of a moving mouse (approx low-rank) from simulated $m = 5n$ coded diffraction pattern (CDP) measurements. Showing frames 20, 60, 78.